Translation of the original operating instructions /
Project planning manual | EN

Inverter

i550 cabinet frequency inverter

0.25 kW ... 132 kW
0.33 hp ... 175 hp

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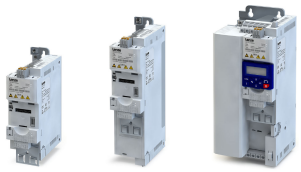


About this document

Document description

This document is intended for all persons who want to configure inverters with the products described.

This document assists you with the configuration and selection of your product. It contains information on mechanical and electrical installation, on product expansions, and on accessories.

Further documents

For certain tasks, information is available in further documents.

Document	Contents/topics
Mounting sheet	General safety instructions and important UL/CSA instructions, connection diagram and technical data. • The mounting sheet is included in the delivery of the product.
Operating instructions	Basic information on installing and commissioning the product.
Commissioning manual	Detailed information on setting and parameterizing the product.

More information

For certain tasks, information is available in other media.

Medium	Contents/topics
Engineering Tools	For commissioning
AKB articles	Additional technical information for users in the Application Knowledge Base
CAD data	Download in different formats from the EASY Product Finder
EPLAN macros	Project planning, documentation and management of projects for EPLAN P8.
Device descriptions	Standardized files for network configuration

Information and tools with regard to the Lenze products can be found on the Internet:
www.Lenze.com → Downloads

Notations and conventions

Conventions are used in this document to distinguish between different types of information.

Numeric notation		
Decimal separator	Point	Generally shown as a decimal point. Example: 1 234.56
Warnings		
UL Warnings	UL	Are used in English and French.
UR warnings	UR	
Text		
Engineering Tools	" "	Software Example: "Engineer", "EASY Starter"
Icons		
Page reference	🕮	Reference to another page with additional information. Example: 🕮 16 = see page 16
Documentation reference	ⓚ	Reference to other documentation with additional information. Example: ⓚ EDKxxx = see documentation EDKxxx

Layout of the safety instructions

⚠DANGER!

Indicates an extremely hazardous situation. Failure to comply with this instruction will result in severe irreparable injury and even death.

⚠WARNING!

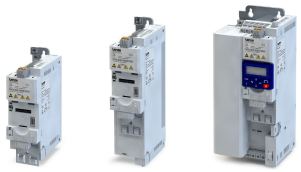
Indicates an extremely hazardous situation. Failure to comply with this instruction may result in severe irreparable injury and even death.

⚠CAUTION!

Indicates a hazardous situation. Failure to comply with this instruction may result in slight to medium injury.

NOTICE

Indicates a material hazard. Failure to comply with this instruction may result in material damage.



Product information

Product description

The i550 cabinet frequency inverter is a compact control cabinet device with scalable functionality. It is versatile, reliable and easy to use.

The requirements of the Ecodesign Directive, standard EN 50598-2, are met.

Application areas: Conveyor drives, traveling drives, winding drives, hoist drives, extruders, packaging machines, pumps, fans, ...

Overview					
Power range	0.25 ... 132 kW				
Mains connection	1 x 120 V	1 x 230 V	3 x 230 V	3 x 400 V	3 x 480 V
Degree of protection	IP20				
Communication	CANopen, EtherCAT, EtherNet/IP, Modbus RTU, Modbus TCP, Powerlink, PROFIBUS, PROFINET				

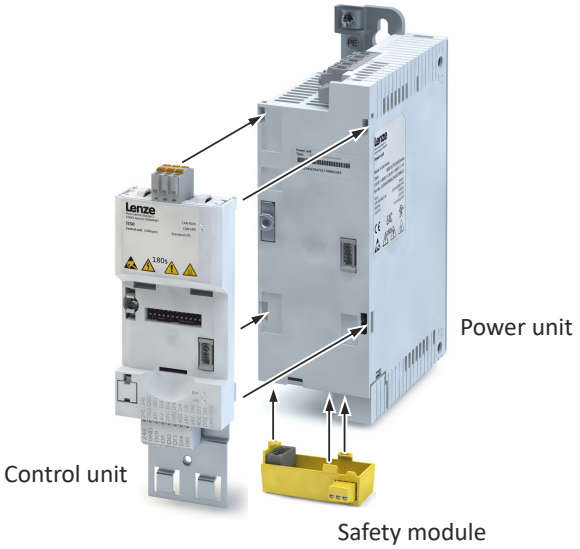
Highlights

- Space saving design: 60 mm wide (up to 4 kW), 130 mm deep (up to 11 kW), with zero-clearance mounting
- Innovative interaction (e.g. over WLAN) makes new record-breaking commissioning times and convenient diagnostics a reality
- The modular design allows different product configurations – just as the machine requires
- Optionally available with "Safe Torque Off (STO)" with SIL 3 (EN IEC 62061/EN IEC 61508) and Performance Level e (EN ISO 13849-1)
- For the greatest possible flexibility available as a complete device or in individual parts (Power Unit, Control Unit and Safety Unit)
- Can be directly connected without external cooling
- All typical motor control types of modern inverters
- Cyclic and continuous operation of the motor according to common operating modes
- Industry-standard networking opportunities
- High internal functional range

The concept

Thanks to its flexible concept and modular structure consisting of power unit, control unit and safety module, the inverter can be optimally adapted to the application.

This provides the user with a flexible logistics concept - ordered as a complete inverter or single components.

Complete inverter	Inverter consisting of components
	

Power unit

The Power Unit is the power section of the inverter.

It is available in the power range from 0.25 kW to 110 kW.

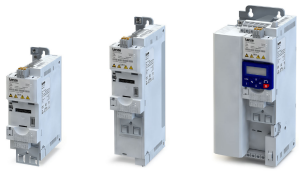
Control unit

The control unit is the open and closed-loop control unit.

It contains I/O connections, an optional network, the interface for diagnostic modules, LED status displays and the memory module.

Safety module

The optional safety module is available with the functional safety STO (Safe Torque Off).



Load characteristics

The inverters have two different load characteristics: "Light Duty" and "Heavy Duty".

The "Light Duty" load characteristic allows for a higher output current with restrictions regarding overload capacity, ambient temperature and switching frequency. This allows the motor required for the application to be driven by a less powerful inverter. Select the load characteristic according to the application.

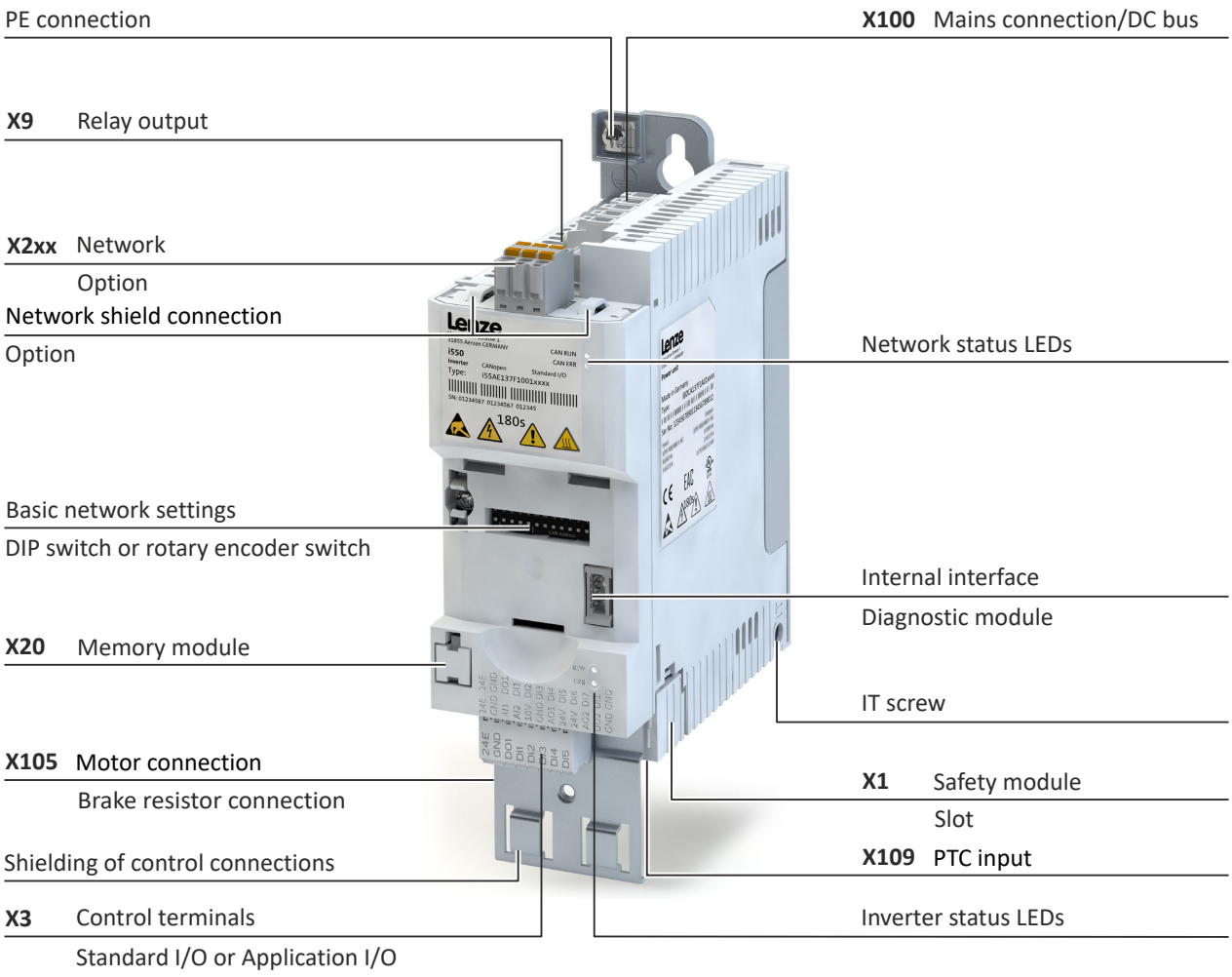
	Heavy Duty	**Light Duty**
Characteristic	High dynamic requirements	Low dynamic requirements
Typical applications	Main tool drives, travelling drives, hoist drives, winders, forming drives and conveyors	Pumps, fans, general horizontal materials handling technology and line drives
Overload capacity	3 s/200 %, 60 s/150 % See technical data	Restricted See technical data

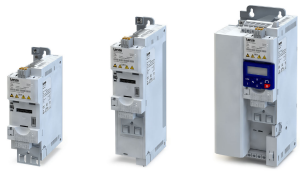
Features

The following figures give an overview of the elements and connections on the devices. Position, size and appearance of elements and connections may vary depending on the capacity and size of the equipment.

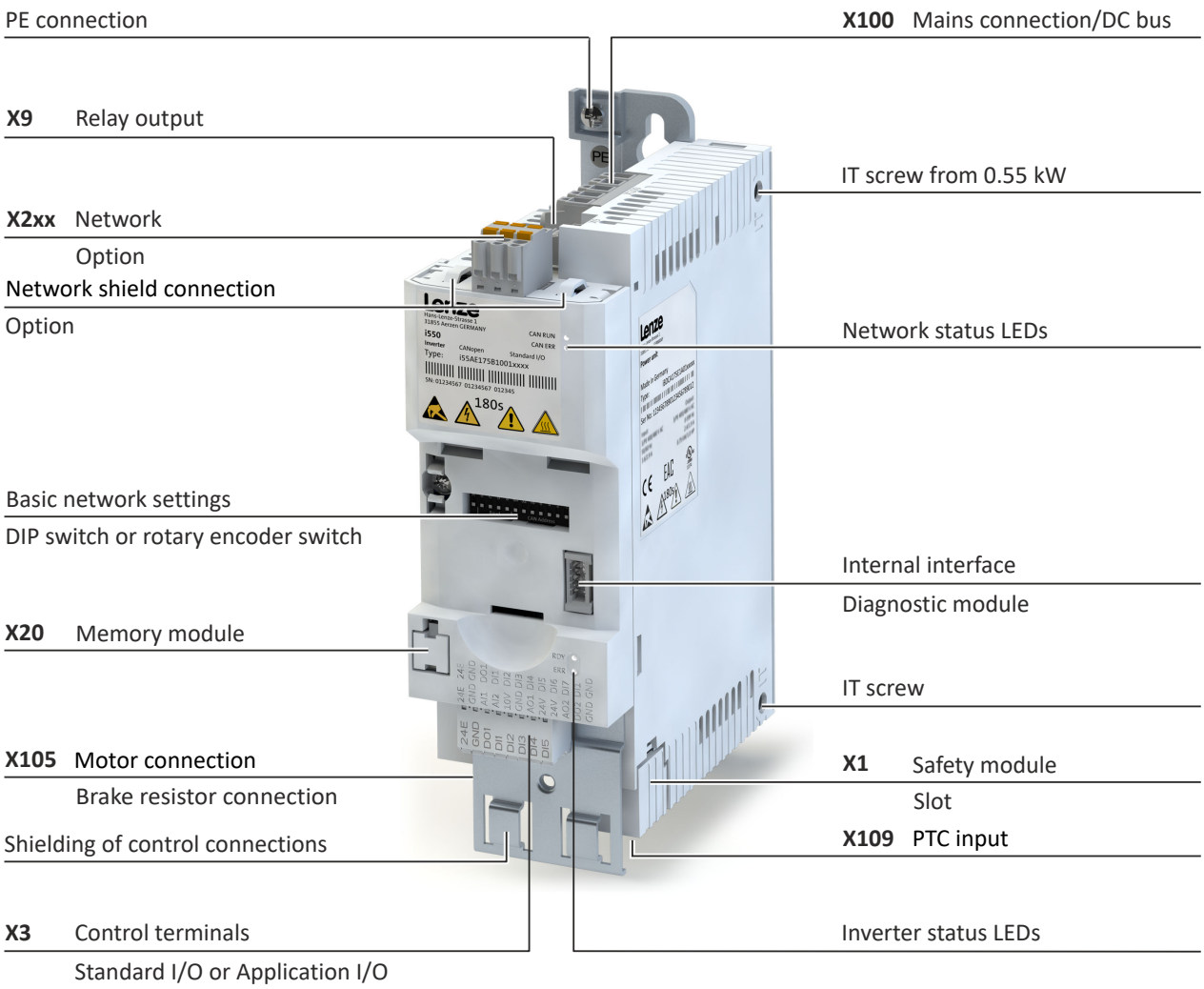
Some equipment may be optional.

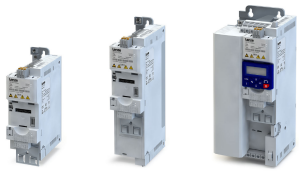
Example of 0.25 kW ... 0.37 kW



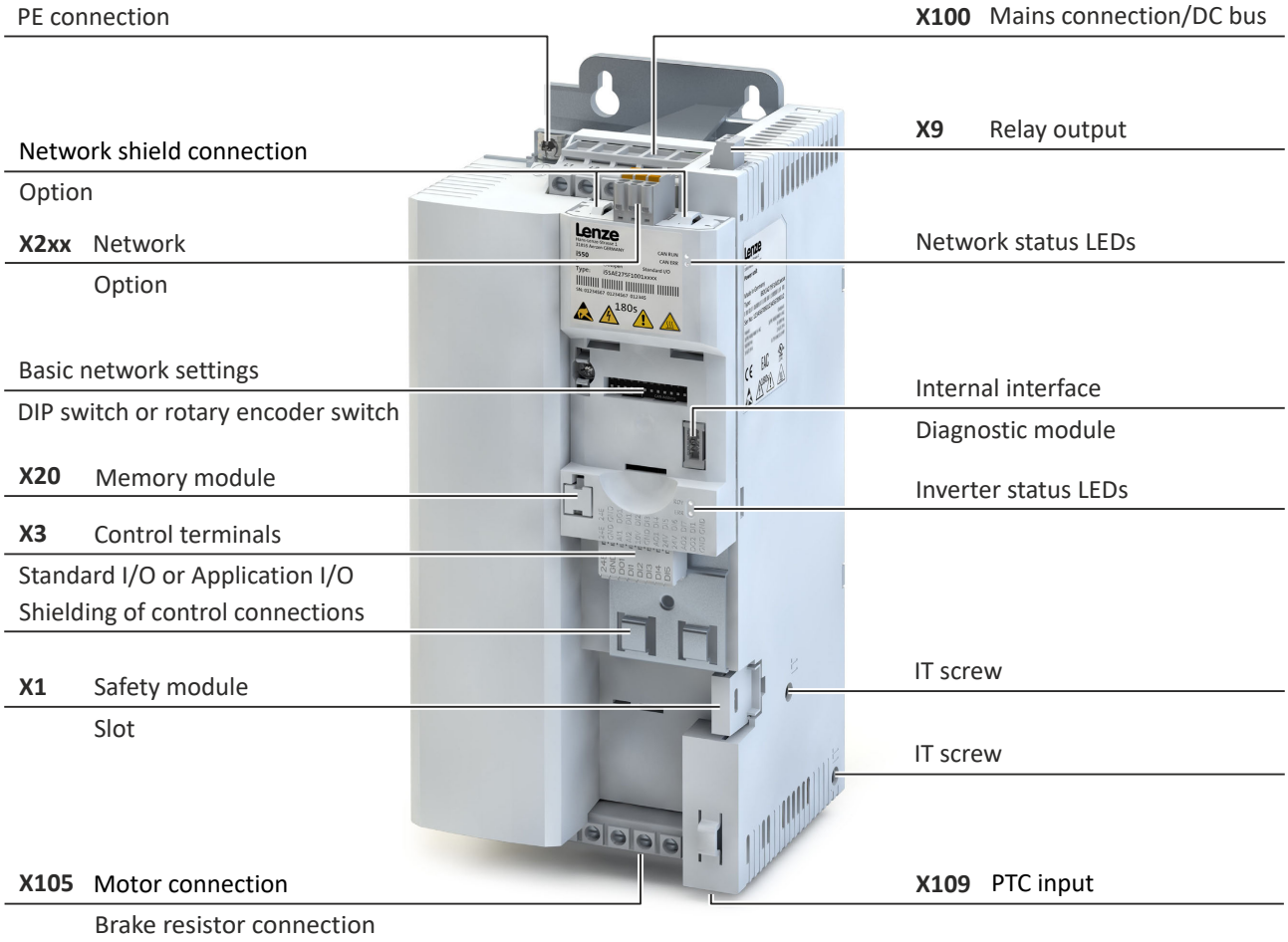


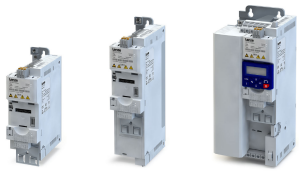
Example of 0.55 kW ... 4 kW



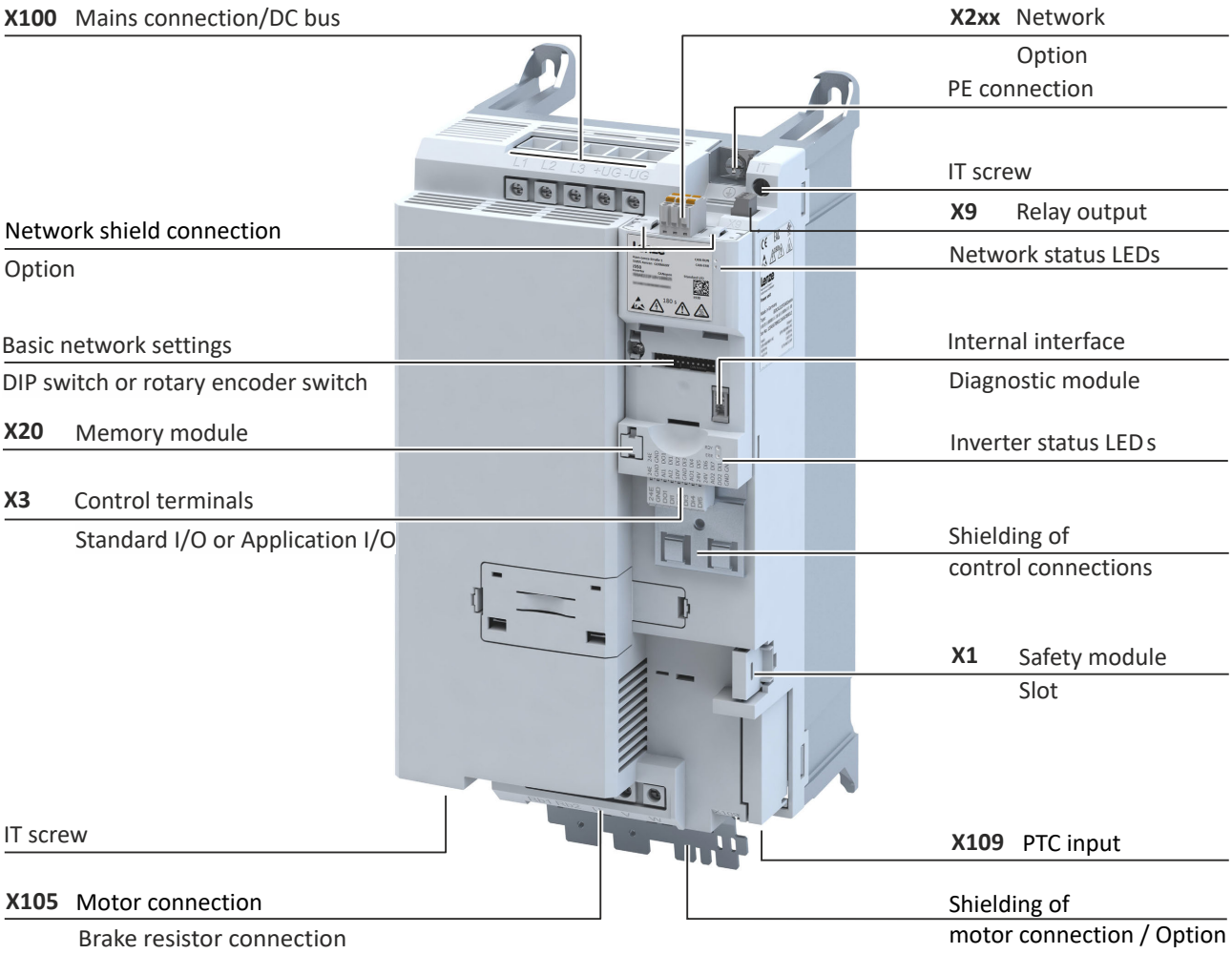


Example of 5.5 kW ... 11 kW

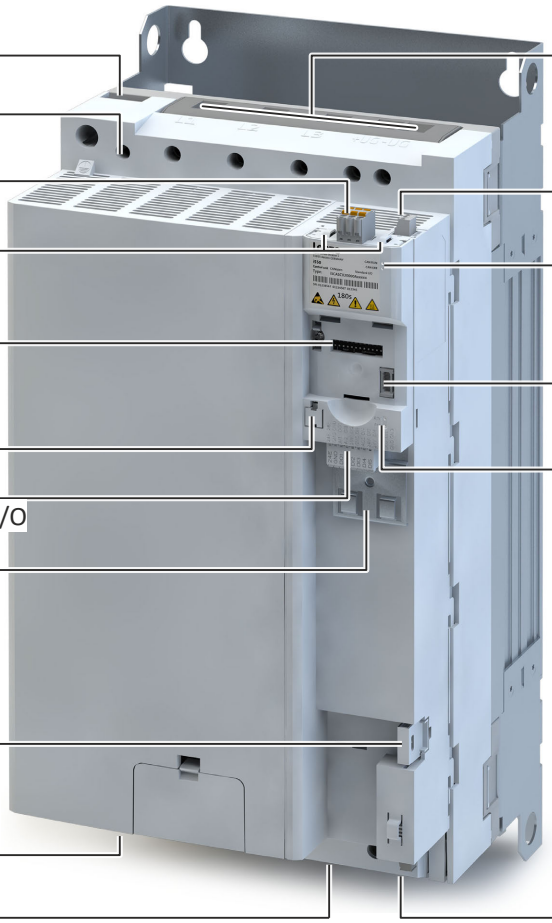


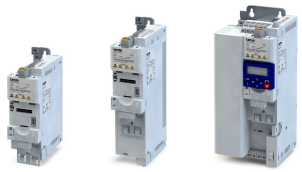


Example of 15 kW ... 30 kW

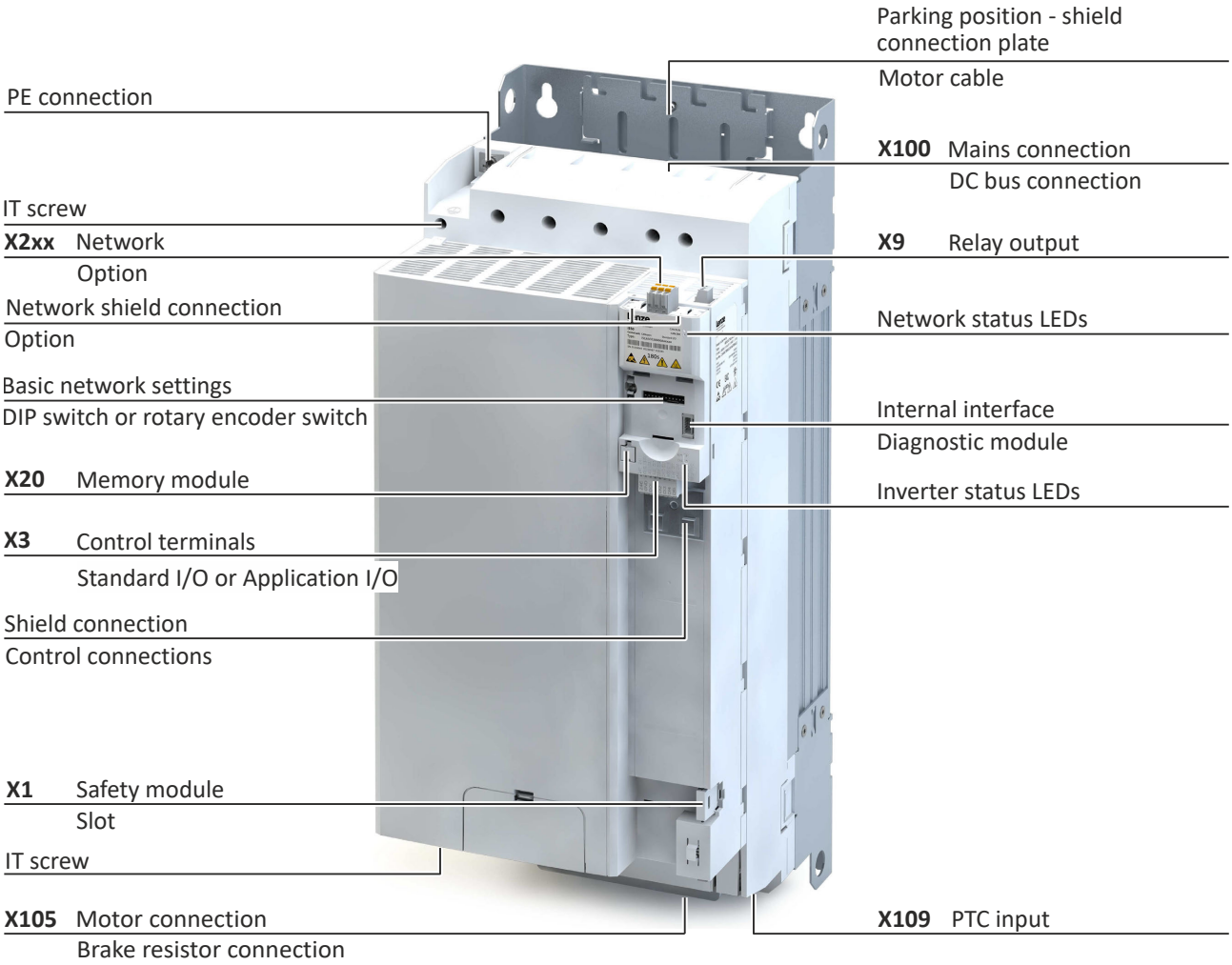


Example of 37 kW ... 45 kW

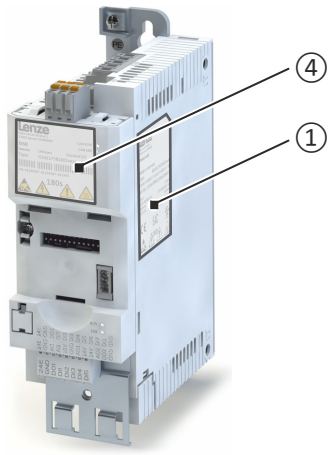
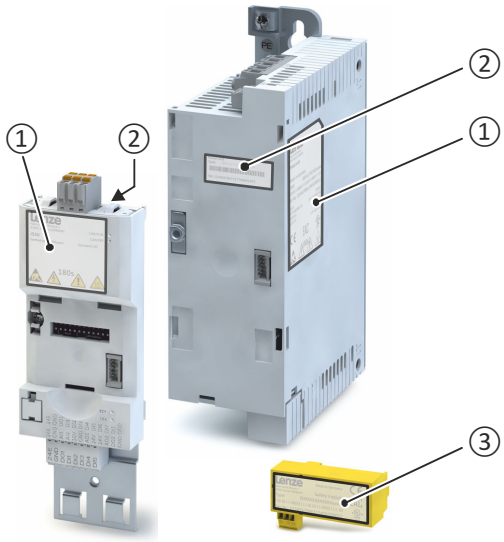




Example of 55 kW ... 110 kW



Position and meaning of the nameplates

Complete inverter	Inverter consisting of components
	

①	Technical data of the inverter	①	Technical data of the component
□	Technical data of the control unit Type and serial number of the inverter	②	Type and serial number of the component
		③	Technical data, type, and serial number of the safety module

Topologies / network

The inverters can be equipped with different fieldbus networks.

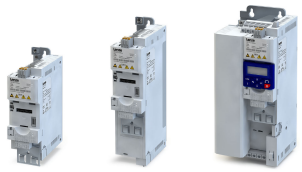
The topologies and protocols typical for the prevailing networks are supported.

Currently available networks:

CANopen	CANopen® is a communication protocol based on CAN. CANopen® is a registered community trademark of the CAN user organisation CiA® (CAN in Automation e. V.). Device descriptions for the download: EDS files for Lenze devices
Modbus	The Modbus protocol is an open communication protocol based on a client/server architecture and developed for the communication with programmable logic controllers. Further development is carried out by the international user organisation Modbus Organization, USA.
IO-Link	IO-Link is the standardized IO technology (IEC 61131-9) for communication with sensors and actuators. Point-to-point communication is based on the 3-wire sensor and actuator connection without additional requirements concerning the cable material. IO-Link is a registered trademark. It may only be used by members of the IO-Link community and non-members that have purchased the corresponding license. Detailed information on the usage can be found in the IO-Link Community Rules at www.io-link.com.
PROFIBUS	PROFIBUS® (Process Field Bus) is a widely-used fieldbus system for the automation of machines and production plants. PROFIBUS® is a registered trademark and patented technology licensed by the PROFIBUS & PROFINET International (PI) user organisation. Device descriptions for the download: GSD files for Lenze devices
EtherCAT	EtherCAT® (Ethernet for Controller and Automation Technology) is an Ethernet-based fieldbus system meeting the application profile for industrial real-time systems. EtherCAT® is a registered trademark and patented technology, licensed by Beckhoff Automation GmbH, Germany. Device descriptions for the download: XML/ESI files for Lenze devices
EtherNet/IP ODVA CONFORMANT	EtherNet/IP™ (EtherNet Industrial Protocol) is an Ethernet-based fieldbus system that uses Common Industrial Protocol™ (CIP™) to exchange data. EtherNet/IP™ and Common Industrial Protocol™ (CIP™) are trademarks and patented technologies, licensed by the user organization ODVA (Open DeviceNet Vendor Association), Inc., USA. Device descriptions for the download: EDS files for Lenze devices
ETHERNET POWERLINK	Ethernet POWERLINK is and Ethernet-based fieldbus system which fulfils the application profile for industrial real-time systems. POWERLINK is an open technology. Detailed information on POWERLINK can be found on the web page of the Ethernet POWERLINK Standardization Group (EPSG): http://www.ethernet-powerlink.org
PROFINET	PROFINET® (Process Field Network) is a real-time capable fieldbus system based on Ethernet. PROFINET® is a registered trademark and patented technology licensed by the PROFIBUS & PROFINET International (PI) user organisation. Device descriptions for the download: GSDML files for Lenze devices

More information on the supported networks can be found at:

www.Lenze.com



Functions

Overview

With regard to their functionality, the inverters i550 are adapted to extensive applications.
This is also reflected in the overall scope of the products.

Functions		
Motor control		Monitoring
V/f characteristic control linear/square-law (VFC plus)		Short circuit
V/f characteristic control (VFC closed loop)		Earth fault
Energy saving function (VFC-Eco)		Device overload (i*t)
Sensorless vector control (SLVC)		Motor overload (i^2*t)
Sensorless control for synchronous motors (SL-PSM/SLSM-PSM)		Mains phase failure
Servo control for asynchronous motors (SC-ASM)		Stall protection
Motor functions		Motor current limit
Flying restart circuit		Maximum torque
Slip compensation		Ultimate motor current
DC braking		Motor speed
Oscillation damping		Load loss detection
Skip frequencies		Motor temperature
Automatic identification of the motor data		Diagnostics
Braking energy management		Error history buffer
Holding brake control		Logbook
Voltage add – function		LED status displays
Rational Energy Ride Through (RERT)		Keypad language selection German, English
Speed feedback (HTL encoder)		Network
Brake resistor control (brake chopper integrated)		CANopen
Frequency setpoint		Modbus RTU
DC-bus connection (400V devices)		Modbus TCP
Application functions		PROFIBUS
Process controller		EtherCAT
Access protection		EtherNet/IP
Process controller sleep mode and rinse function		PROFINET
Freely assignable favorite menu		POWERLINK
Parameter change-over		IO-Link
S-shaped ramps for smooth acceleration		Safety functions
Motor potentiometer		STO (Safe Torque Off)
Flexible I/O configuration		
Automatic restart		
OEM parameter set		
Complete control with 8-key keypad		
UPS operation		
Frequency output via digital output DO1		
"Light Duty" load characteristic can be adjusted for selected inverters		

Motor control types

The following table contains the possible control types with Lenze motors.

Motors	V/f characteristic control VFCplus	Sensorless vector control SLVC	ASM servo control SC ASM
Three-phase AC motors			
MD	•	•	•
MF	•	•	•
mH	•	•	•
m500	•	•	•

Lenze synchronous servo motors are not suitable for use with inverters, e.g. the types MCS, MCM or m850.

Motor functions

Motor setting range

Rated point 120 Hz

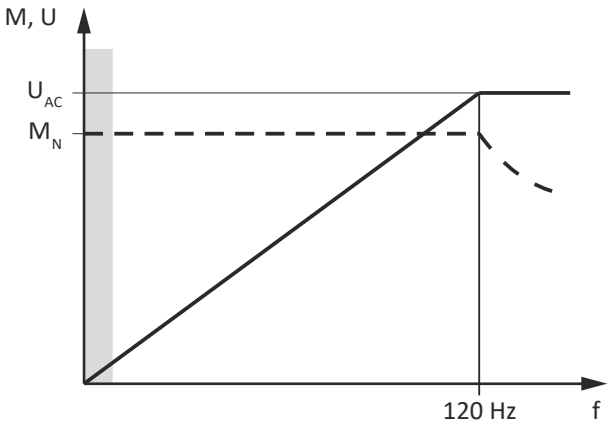
Only possible with Lenze MF motors.

The rated motor torque is available up to 120 Hz.

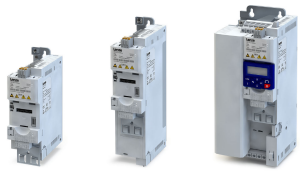
Compared to the 50-Hz operation, the setting range increases by 2.5 times.

Thus, a smaller motor can be selected at the same rated power.

V/f at 120 Hz



V	Voltage	V_{AC}	Mains voltage
M	Torque	M_N	Rated torque
f	Frequency		



Rated point 87 Hz

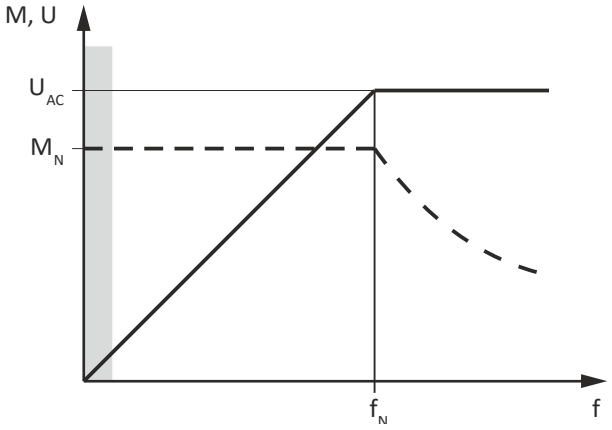
The rated motor torque is available up to 87 Hz.

Compared to the 50-Hz operation, the setting range increases by 1.74 times.

For this purpose, a motor with 230/400 V in a triangle is driven by a 400 V inverter.

The inverter must be dimensioned for a rated motor current of 230 V.

V/f at 87 Hz

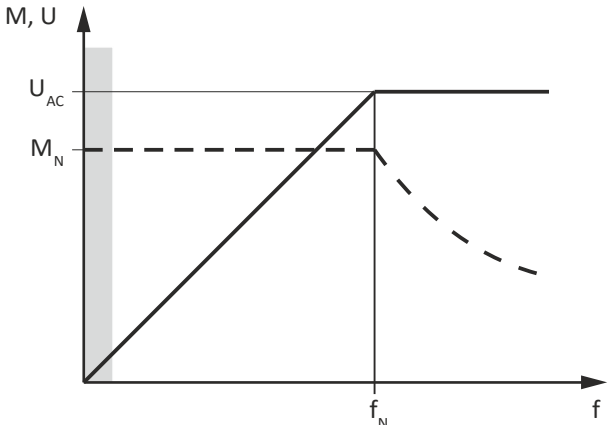


V	Voltage	U_{AC}	Mains voltage
M	Torque	M_{rated}	Rated torque
f	Frequency	f_{rated}	Rated frequency

Rated point 50 Hz

The rated motor torque is available up to 50 Hz.

V/f at 50 Hz



V	Voltage	U_{AC}	Mains voltage
M	Torque	M_{rated}	Rated torque
f	Frequency	f_{rated}	Rated frequency

Identification of the products

When the technical data of the different versions was listed, the product name was entered because it is easier to read than the individual product code of the product. The product name is also used for categorising the accessories. The assignment of product name and order code can be found in the "Order" chapter. 231

The product name contains the power in kW, the mains voltage class 120 V, 230 V or 400 V and the number of phases.

In the product name, the power information always refers to the "Heavy Duty" load characteristic.

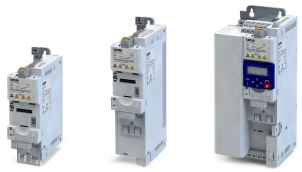
The 1/3-phase inverters are marked at the end with "-2".

"C" marks the "Cabinet" version = inverter for the installation into the control cabinet.

Device series	Design	Rated power		Rated mains voltage	No. of phases	Inverter
		Light Duty	Heavy Duty			
		kW	kW	V		
i550	C	-	0.25	120	1	i550-C0.25/120-1
			0.37			i550-C0.37/120-1
			0.75			i550-C0.75/120-1
			1.1			i550-C1.1/120-1

Device series	Design	Rated power		Rated mains voltage	No. of phases	Inverter
		Light Duty	Heavy Duty			
		kW	kW	V		
i550	C	-	0.25	230	1	i550-C0.25/230-1
					1/3	i550-C0.25/230-2
			0.37		1	i550-C0.37/230-1
					1/3	i550-C0.37/230-2
			0.55		1	i550-C0.55/230-1
					1/3	i550-C0.55/230-2
			0.75		1	i550-C0.75/230-1
					1/3	i550-C0.75/230-2
			1.1		1	i550-C1.1/230-1
					1/3	i550-C1.1/230-2
			1.5		1	i550-C1.5/230-1
					1/3	i550-C1.5/230-2
			2.2		1	i550-C2.2/230-1
					1/3	i550-C2.2/230-2

Device series	Design	Rated power		Rated mains voltage	No. of phases	Inverter
		Light Duty	Heavy Duty			
		kW	kW	V		
i550	C	-	0.25	240	1/3	i550-C0.25/230-2
			0.37			i550-C0.37/230-2
			0.55			i550-C0.55/230-2
			0.75			i550-C0.75/230-2
			1.1			i550-C1.1/230-2
			1.5			i550-C1.5/230-2
			2.2			i550-C2.2/230-2
		5.5	4		3	i550-C4.0/230-3
		7.5	5.5			i550-C5.5/230-3



Device series	Design	Rated power		Rated mains voltage	No. of phases	Inverter
		Light Duty	Heavy Duty			
		kW	kW	V		
i550	C	-	0.37	400	3	i550-C0.37/400-3
			0.55			i550-C0.55/400-3
			0.75			i550-C0.75/400-3
			1.1			i550-C1.1/400-3
			1.5			i550-C1.5/400-3
			2.2			i550-C2.2/400-3
		4	3			i550-C3.0/400-3
		5.5	4			i550-C4.0/400-3
		7.5	5.5			i550-C5.5/400-3
		11	7.5			i550-C7.5/400-3
		15	11			i550-C11/400-3
		18.5	15			i550-C15/400-3
		22	18.5			i550-C18/400-3
		30	22			i550-C22/400-3
		37	30			i550-C30/400-3
		45	37			i550-C37/400-3
		55	45			i550-C45/400-3
		75	55			i550-C55/400-3
		90	75			i550-C75/400-3
		110	90			i550-C90/400-3
		132	110			i550-C110/400-3

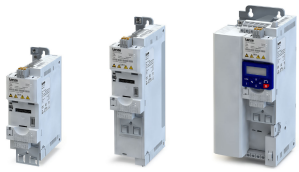
Device series	Design	Rated power		Rated mains voltage	No. of phases	Inverter
		Light Duty	Heavy Duty			
		kW	kW	V		
i550	C	-	0.37	480	3	i550-C0.37/400-3
			0.55			i550-C0.55/400-3
			0.75			i550-C0.75/400-3
			1.1			i550-C1.1/400-3
			1.5			i550-C1.5/400-3
			2.2			i550-C2.2/400-3
		4	3			i550-C3.0/400-3
		5.5	4			i550-C4.0/400-3
		7.5	5.5			i550-C5.5/400-3
		11	7.5			i550-C7.5/400-3
		15	11			i550-C11/400-3
		18.5	15			i550-C15/400-3
		22	18.5			i550-C18/400-3
		30	22			i550-C22/400-3
		37	30			i550-C30/400-3
		45	37			i550-C37/400-3
		55	45			i550-C45/400-3
		75	55			i550-C55/400-3
		90	75			i550-C75/400-3
		110	90			i550-C90/400-3
		132	110			i550-C110/400-3

Product code

		I	5	5	A	E	□□□	□	1	□	□	□	□	□□□□
Product type	Inverter	I												
Product family	i500		5											
Product	i550			5										
Product generation	Generation 1				A									
	Generation 2				B									
Mounting type	Control cabinet mounting					E								
Rated power (Examples)	0.25 kW						125							
	0.55 kW						155							
	2.2 kW						222							
	3.0 kW						230							
	15 kW						315							
	30 kW						330							
Mains voltage and connection type	1/N/PE AC 120 V							A						
	1/N/PE AC 230/240 V							B						
	3/PE AC 230/240 V							C						
	1/N/PE AC 230/240 V 3/PE AC 230/240 V							D						
	3/PE AC 400 V 3/PE AC 480 V							F						
Motor connections	Single axis								1					
Integrated functional safety	Without safety function									0				
	Basic Safety STO									A				
Degree of protection	IP20, coated										V			
Interference suppression	Without											0		
	Integrated RFI filter											1		
Application	Default parameter setting: Region EU (50-Hz networks)												0	
	Default parameter setting: Region US (60-Hz networks)												1	
Design types	Standard I/O without network													000S
	Application I/O without network													001S
	Standard I/O with CANopen													002S
	Standard I/O with Modbus RTU													003S
	Standard I/O with PROFIBUS													004S
	Standard I/O with POWERLINK													012S
	Standard I/O with EtherCAT													00KS
	Standard I/O with PROFINET													0xLS
	Standard I/O with EtherNet/IP													0xMS
	Standard I/O with Modbus TCP													0xWS
	Standard I/O with IO-Link													016S

Example:

Product code	Meaning
I55AE311F1AV1000KS	Inverter i550 cabinet, 11 kW, 3-phase, 400 V/480 V STO safety function, IP20, varnished, integrated RFI filter; 50 Hz variant Standard I/O with EtherCAT network



Ways of commissioning

There are three ways to commission the inverter quickly and easily.

Thanks to Lenze's engineering philosophy, the high functionality is still easy to grasp. Parameterization and commissioning are a breeze thanks to clear structure and simple dialogs, leading to the desired outcome quickly and reliably.

Keypad

If it's only a matter of setting a few key parameters such as acceleration and deceleration time, this can be done quickly on the keypad.

»EASY Starter«

If functions such as the holding brake control or sequencer need to be set, it's best to use the »EASY Starter« engineering tool.

SMART Keypad App

The Lenze SMART Keypad App for Android or iOS allows you to diagnose and parameterize an inverter. A WLAN module on the inverter is required for communication.

- Ideal for the parameterization of simple applications such as a conveyor belt.
- Ideal for the diagnostics of the inverter.

The app can be found in the Google Play Store or in the Apple App Store.

Android

iOS

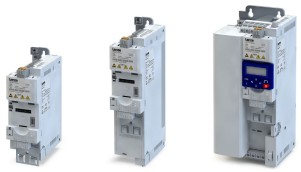
Safety instructions

Basic safety instructions

Disregarding the following basic safety instructions and safety information may lead to severe personal injury and damage to property!

- Only use the product as directed.
- Never commission the product in the event of visible damage.
- Never modify the product technically.
- Never commission the product before assembly has been completed.
- Never operate the product without the required covers.
- Connect/disconnect all pluggable connections only in deenergized condition!
- Only remove the product from the installation in the deenergized state.
- The product can – depending on their degree of protection – have live, movable or rotating parts during or after operation. Surfaces can be hot.
- Observe the specifications of the corresponding documentation. This is the condition for safe and trouble-free operation and the achievement of the specified product features.
- The procedural notes and circuit details given in the associated documentation are suggestions and their transferability to the respective application has to be checked. The manufacturer of the product does not take responsibility for the suitability of the process and circuit proposals.
- All work with and on the product may only be carried out by qualified personnel. IEC 60364 and CENELEC HD 384 define the qualifications of these persons:
  - They are familiar with installing, mounting, commissioning, and operating the product.
  - They have the corresponding qualifications for their work.
  - They know and can apply all regulations for the prevention of accidents, directives, and laws applicable at the place of use.

Please observe the specific safety information in the other sections!



Application as directed

- The product is a professional equipment intended for use by trades, specific professions or industry and not for sale to the general public. IEC 60050 [IEV 161-05-05]
- To prevent personal injury and damage to property, higher-level safety and protection systems must be used!
- All transport locks must be removed.
- The product may only be operated under the specified operating conditions and in the specified mounting positions.
- The product is exclusively suitable for installation in control cabinets and, depending on the protection class and design, for wall and motor mounting.
- The product must only be actuated with motors that are suitable for the operation with inverters.
- The product must not be operated in private areas, in potentially explosive atmospheres and in areas with harmful gases, oils, acids and radiation.

Additional information for the intended use in North America:

The cables must be installed in accordance with US National Electrical Code NFPA 70 or Canadian Electrical Code C22.1.

Use of explosion-protected motors

Explosion-protected motors that are not designed for use with an inverter lose their approval if they are used for variable speed applications. Due to the many areas of liability that may arise when handling these applications, the following policy statement applies:

Lenze inverters are sold without warranty of suitability for use with explosion-protected motors. Lenze assumes no responsibility for direct, incidental or consequential damages, costs or losses that may result from the use of AC inverters with explosion-protected motors. Buyer expressly agrees to assume any risk of loss, expense or damage that may result from such application.

Foreseeable misuse

Inverters are not to be operated with DC motors.

Handling

Transport, storage

Observe the notes regarding transport, storage and correct handling. Ensure proper handling and avoid mechanical stress. Do not bend any components and do not change any insulation distances during transport or handling. Do not touch any electronic components and contacts. Inverters contain electrostatically sensitive components which can easily be damaged by inappropriate handling. Do not damage or destroy any electrical components since thereby your health could be endangered!

Installation

The technical data and supply conditions can be obtained from the nameplate and the documentation. They must be strictly observed.

The inverters must be installed and cooled according to the instructions given in the corresponding documentation. Observe the climatic conditions according to the technical data. The ambient air must not exceed the degree of pollution 2 according to EN 61800-5-1.

Electrical connection

When working on energized inverters, comply with the applicable national accident prevention regulations.

The electrical installation must be carried out according to the appropriate regulations (e. g. cable cross-sections, fuses, PE connection). Additional information can be obtained from the documentation.

The documentation contains information about installation according to EMC regulations (shielding, grounding, filters and cable routing). Please also observe this information for CE-marked inverters. The manufacturer of the system or machine is responsible for adherence to the limit values required in connection with EMC legislation.

The inverters must be installed in housings (e. g. control cabinets) to meet the limit values for radio interferences valid at the site of installation. The housings must enable an EMC-compliant installation. Observe in particular that e. the control cabinet doors should have a circumferential metal connection to the housing. Reduce housing openings and cutouts to a minimum.

Protection in the event of short circuit or earth fault

To ensure protection according to EN 61800-5-1 in the event of an electrical short circuit or earth fault (protection against electric shock, thermal hazards and fire), the following must be taken into account in the installation:

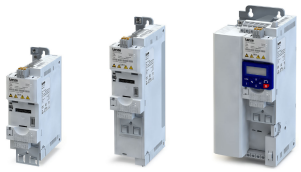
- Use fuses according to the technical data.
- The installation must meet the requirements of the IEC 60364.
- The continuity of all associated protective conductors and equipotential bonding conductors including all connection points must be ensured.
- If the maximum permissible switch-off time according to IEC 60364 is exceeded with a high system impedance (especially with TT mains) or a high loop impedance with the prescribed fuses, a residual current device (RCD) can be used. Alternatively, other protective measures can be used, e. g. isolation from the environment by means of double or reinforced insulation, or isolation from the supply system by using a transformer.
- If a residual current device (RCD) is connected upstream of the inverter for protection in the event of an earth fault, only type B/B+ is permitted for three-phase devices.

Operation

If necessary, systems including inverters must be equipped with additional monitoring and protection devices. Also comply with the safety regulations and provisions valid at the installation site.

After the inverter has been disconnected from the supply voltage, all live components and power terminals must not be touched immediately because capacitors can still be charged. Please observe the corresponding stickers on the inverter.

All protection covers and doors must be shut during operation.



You may adapt the inverters to your application by parameter setting within the limits available. For this, observe the notes in the documentation.

Safety functions

Certain inverter versions support safety functions (e. g. ”safe torque off”, formerly ”safe standstill”) according to the requirements of the EC Machinery Directive 2006/42/EC [UKCA: S.I. 2008/1597] . The notes on the integrated safety provided in this documentation must be observed.

The user is not allowed to change inverters that come with integrated safety technology.

- The safety module must not be removed.
- The user must not carry out any repairs on the safety module.
- The safety module is not a spare part.
- If the safety module is defective, the inverter has to be replaced.

Maintenance and servicing

The inverters do not require any maintenance if the prescribed operating conditions are observed.

Disposal

In accordance with the current provisions, Lenze products and accessories have to be disposed of by means of professional recycling. Lenze products contain contain recyclable raw material such as metal, plastics and electronic components.

Residual hazards

Even if notes given are taken into consideration and protective measures are implemented, the occurrence of residual risks cannot be fully prevented.

The user must take the residual hazards mentioned into consideration in the risk assessment for his/her machine/system.

If the above is disregarded, this can lead to severe injuries to persons and damage to property!

Product

Observe the warning labels on the product!

Dangerous electrical voltage:
Before working on the product, make sure there is no voltage applied to the power terminals! After mains disconnection, the power terminals will still carry the hazardous electrical voltage for the time given next to the symbol!

Electrostatic sensitive devices:
Before working on the product, the staff must ensure to be free of electrostatic charge!

High leakage current:
Carry out fixed installation and PE connection in compliance with:
EN 61800-5-1 / EN 60204-1

Hot surface:
Use personal protective equipment or wait until the device has cooled down!

Degree of protection - protection of persons and device protection

- Information applies to the mounted and ready-for-use state.
- Information does not apply to the wire range of the terminals.
  - Terminals that are not wired have low protection against physical contact.
  - Terminals for large cable cross-sections have lower classes of protection, e. g. from 15 kW IP10 only.

Protection of persons

Before working on the inverter, check if no voltage is applied to the power terminals.

- Depending on the device, the power terminals X105 remain live for up to 20 minutes.
- The power terminals X100 and X105 remain live even when the motor is stopped.

Device protection

- The maximum test voltage for insulation tests between a control potential of 24 V and PE must not exceed 110 V DC (EN 61800-5-1).

Motor protection

With some settings of the inverter, the connected motor can be overheated.

- E. g. by longer operation of self-ventilated motors at low speed.
- E. g. by longer operation of DC-injection braking.

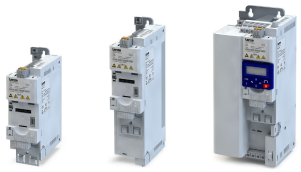
Protection of the machine/system

Drives can reach dangerous overspeeds.

- E. g. by setting high output frequencies in connection with motors and machines not suitable for this purpose.
- The inverters do not provide protection against such operating conditions. For this purpose, use additional components.

Switch contactors in the motor cable only if the controller is inhibited.

- Switching while the inverter is enabled is only permissible if no monitoring functions are activated.



Motor

If there is a short circuit of two power transistors, a residual movement of up to 180°/number of pole pairs can occur at the motor! (e. g. 4-pole motor: residual movement max. 180°/2 = 90°).

Information on project planning

Project planning process

Dimensioning

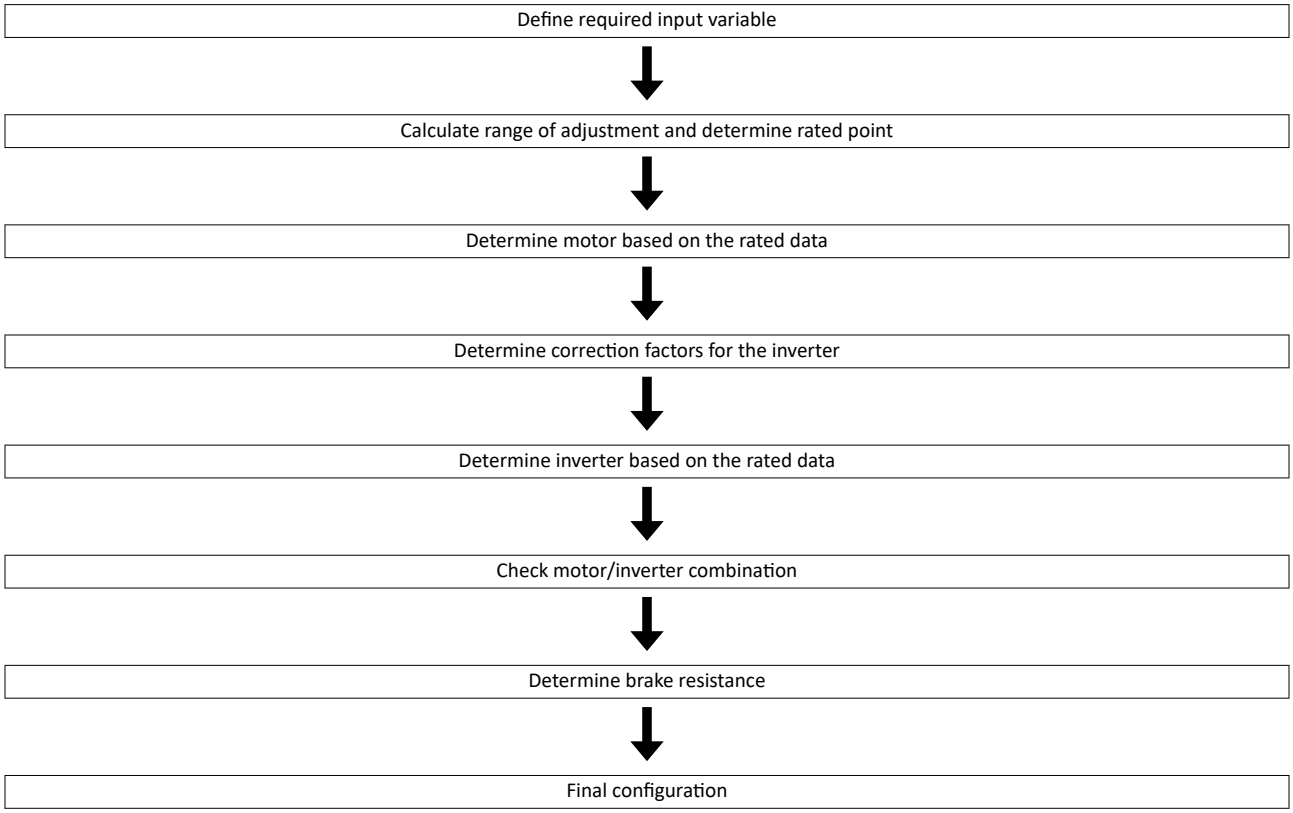
3 methods for dimensioning

Fast: Selection of the inverter based on the motor data of a 4-pole asynchronous motor.

Detailed: In order to optimize the selection of the inverter and all drive components, it is worthwhile to execute the detailed system dimensioning based on the physical requirements of the application. For this purpose, Lenze provides the Drive Solution Designer (DSD) design program.

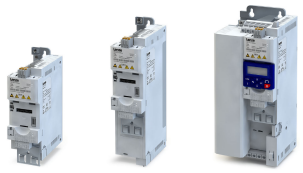
Manual: The following chapter guides you step by step through the selection of a drive system.

Workflow of a configuration process



Define required input variables

Operating mode			S1 or S6
Max. load torque	$M_{L,max}$	Nm	
Max. load speed	$n_{L,max}$	rpm	
Min. load speed	$n_{L,min}$	rpm	
Site altitude	H	m	
Ambient temperature (inverter)	T_U	°C	



Calculate range of adjustment and determine rated point

	Calculation
Setting range	$V = \frac{n_{L,max}}{n_{L,min}}$

	Setting range	Rated point
Motor with integral fan	≤ 2.50 (20 - 50 Hz) ≤ 4.35 (20 - 87Hz) ≤ 6 (20 - 120Hz)	50 Hz 87 Hz 120 Hz
Motor with blower	≤ 10.0 (5 - 50 Hz) ≤ 17.4 (5 - 87Hz) ≤ 24 (5 - 120Hz)	50 Hz 87 Hz 120 Hz
Motor with integral fan (reduced torque)		

Determine motor based on the rated data

			Check
Rated torque			
Operating mode S1	M_{rated}	Nm	$M_N \geq \frac{M_{L,max}}{T_{H,Mot} \times T_{U,Mot}}$
Operating mode S6	M_{rated}	Nm	$M_N \geq \frac{M_{L,max}}{2 \times T_{H,Mot} \times T_{U,Mot}}$
Rated speed	n_{rated}	rpm	$n_{rated} \geq n_{L,max}$ $\frac{n_n}{V} \leq n_{L,min}$

			Note
Rated torque	M_{rated}	Nm	→ Rated motor data
Rated speed	n_{rated}	rpm	
Rated point at		Hz	→ setting range
Power factor	cos φ		→ Rated motor data
Rated current	$I_{N,MOT}$	A	
Rated power	P_{rated}	kW	
Correction factor - site altitude	$T_{H,MOT}$		→ Technical motor data
Correction factor - ambient temperature	$T_{U,MOT}$		
Select motor			

Correction factors for the inverter

Site altitude Amsl		H			
	[m]	≤ 1000	≤ 2000	≤ 3000	≤ 4000
$k_{H,INV}$		1.00	0.95	0.90	0.85

Temperature in the control cabinet		T_U			
	[°C]	≤ 40	≤ 45	≤ 50	≤ 55
Switching frequency					
2 or 4 kHz	$k_{TU,INV}$	1.00	1.00	0.875	0.750
8 or 16 kHz		1.00	0.875	0.750	0.625
Switching frequency with the "Light Duty" load characteristic					
2 or 4 kHz	$k_{TU,INV}$	1.00	0.875	0.750	-
8 or 16 kHz		-	-	-	-

Determine the inverter based on the rated data

			Check
Output current			
Continuous operation	I_{out}	A	$I_{out} \geq I_{N,Mot} / (k_{H,INV} \times k_{TU,INV})$
Overcurrent operation cycle 15 s	I_{out}	A	$I_{out} \geq I_{N,Mot} \times 2 / (k_{H,INV} \times k_{TU,INV})$
Overcurrent operation cycle 180 s	I_{out}	A	$I_{out} \geq I_{N,Mot} \times 1.5 / (k_{H,INV} \times k_{TU,INV})$

Determine the inverter based on the rated data for the "Light Duty" load characteristic

			Check
Output current			
Continuous operation	I_{out}	A	$I_{out} \geq I_{N,Mot} / (k_{H,INV} \times k_{TU,INV})$
Overcurrent operation cycle 15 s	I_{out}	A	$I_{out} \geq I_{N,Mot} \times 1.65 / (k_{H,INV} \times k_{TU,INV})$
Overcurrent operation cycle 180 s	I_{out}	A	$I_{out} \geq I_{N,Mot} \times 1.25 / (k_{H,INV} \times k_{TU,INV})$

Check motor/inverter combination

			Calculation
Motor torque	M	Nm	$M = \sqrt{\left(\frac{I_{out,INV}}{I_{N,MOT}}\right)^2 - \left(1 - \cos\varphi^2\right)} \times \frac{M_N}{\cos\varphi}$

		Check
Inverter overload capacity		$\frac{M_{L,max}}{M} \leq 1.5$

Braking operation without additional measures

To decelerate small masses, the "DC injection brake DCB" function can be parameterised. DC-injection braking enables a quick deceleration of the drive to standstill without the need for an external brake resistor.

- A code can be used to select the braking current.
- The maximum braking torque to be realised by the DC braking current amounts to approx. 20 ... 30 % of the rated motor torque. It is lower compared to braking action in generator mode with external brake resistor.
- Automatic DC-injection braking (Auto-DCB) improves the starting performance of the motor when the operation mode without speed feedback is used.

Braking operation with external brake resistor

To decelerate greater moments of inertia or with a longer operation in generator mode an external brake resistor is required. It converts braking energy into heat.

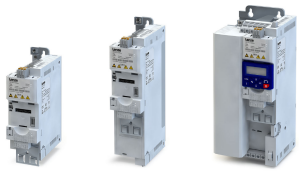
The brake resistor is connected if the DC-bus voltage exceeds the switching threshold. This prevents the controller from setting pulse inhibit through the "Overvoltage" fault and the drive from coasting down. The external brake resistor serves to control the braking process at any time.

The brake chopper integrated in the controller connects the external brake resistor.

Determine brake resistance

			Application	
			With active load	With passive load
Rated power	P_{rated}	kW	$P_N \geq P_{max} \times \eta_e \times \eta_m \times \frac{t_1}{t_z}$	$P_N \geq \frac{P_{max} \times \eta_e \times \eta_m}{2} \times \frac{t_1}{t_z}$
Thermal capacity	C_{th}	kWs	$C_{th} \geq P_{max} \times \eta_e \times \eta_m \times t_1$	$C_{th} \geq \frac{P_{max} \times \eta_e \times \eta_m}{2} \times t_1$
Rated resistance	R_{rated}	Ω	$R_N \geq \frac{U_{DC}^2}{P_{max} \times \eta_e \times \eta_m}$	

Active load	Can start to move independent of the drive (e.g. unwinder)
Passive load	Can stop independent of the drive (e.g. horizontal travelling drives, centrifuges, fans)
U_{DC} [V]	Switching threshold - brake chopper
P_{max} [W]	Maximum occurring braking power
η_e	Electrical efficiency
η_m	Mechanical efficiency
t_1 [s]	Braking time
t_z [s]	Cycle time = time between two successive braking processes (t_1 + dead time)



Final configuration

Product extensions and accessories can be found here:

▸ Product extensions 📖 190

▸ Accessories 📖 216

Operation in motor and generator mode

The energy analysis differs between operation in motor mode and generator mode.

During operation in motor mode, the energy flows from the supplying mains via the inverter to the motor which converts electrical energy into mechanical energy (e. g. for lifting a load).

During operation in generator mode, the energy flows back from the motor to the inverter. The motor converts the mechanical energy into electrical energy - it acts as a generator (e. g. when lowering a load).

The drive brakes the load in a controlled manner.

The energy recovery causes a rise in the DC-bus voltage. If this voltage exceeds an upper limit, the output stage of the inverter will be blocked to prevent the device from being destroyed.

The drive coasts until the DC-bus voltage reaches the permissible value range again.

In order that the excessive energy can be dissipated, a brake resistor or a regenerative module is required.

Overcurrent operation

The inverters can be driven at higher amperages beyond the rated current if the duration of this overcurrent operation is time limited.

Two utilisation cycles of 15 s and 180 s are defined. Within these utilisation cycles, an overcurrent is possible for a certain time if afterwards an accordingly long recovery phase takes place.

Cycle 15 s

During this operation, the inverter may be loaded for 3 s with up to 200 % of the rated current if afterwards a recovery time of 12 s with max. 75 % of the rated current is observed. A cycle corresponds to 15 s.

Cycle 180 s

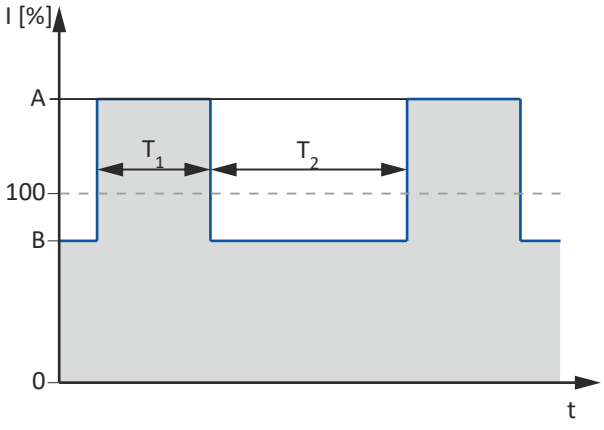
During this operation, the inverter may be loaded for 60 s with up to 150 % of the rated current if afterwards a recovery time of 120 s with max. 75 % of the rated current is observed. A cycle corresponds to 180 s.

The monitoring of the device utilization (Ixt) triggers an error if the utilization value exceeds a threshold of 100 %.

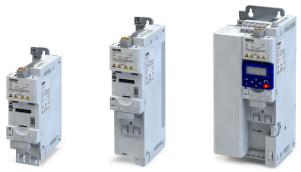
The maximum output currents correspond to the switching frequencies and the overload behaviour of the inverters are given in the rated data.

In case of rotating frequencies < 10 Hz, the time-related overload behaviour may be reduced.

The graphics shows a cycle. The basic conditions given in the table (graphics field highlighted in grey) have to be complied with in order that the inverter will not be overloaded. Both cycles can be combined with each other.



Cycle	Max. output current	Max. overload time	Max. output current during the Recovery time	Min. recovery time
	A	T_1	B	T_2
s	%	s	%	s
15	200	3	75	12
180	150	60	75	120



Control cabinet structure

Control cabinet requirements

- Protection against electromagnetic interferences
- Compliance with the ambient conditions of the installed components

Mounting plate requirements

- The mounting plate must be electrically conductive.
  - Use zinc-coated mounting plates or mounting plates made of V2A.
  - Varnished mounting plates are unsuitable, even if the varnish is removed from the contact surfaces.
- When using several mounting plates, make a conductive connection over a large surface (e. g. using grounding strips).

Arrangement of components

- Division into power and control areas

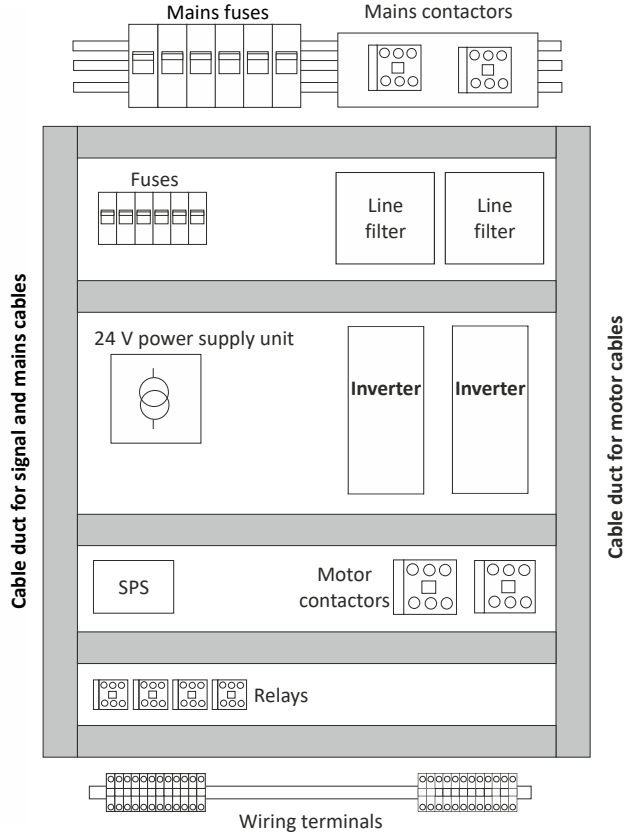


Fig. 1: Example for the ideal arrangement of components in the control cabinet

Cables

Requirements

- The cables used must correspond to the requirements at the location (e. g. EN 60204-1, UL).
- The cable cross-section must be dimensioned for the assigned fusing. Observe national and regional regulations.
- You must observe the regulations for minimum cross-sections of PE conductors. The cross-section of the PE conductor must be at least as large as the cross-section of the power connections.

Installation inside the control cabinet

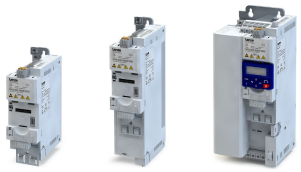
- Always install cables close to the mounting plate (reference potential), as freely suspended cables act like antennas.
- Use separated cable ducts for motor cables and control cables. Do not mix up different cable types in one cable duct.
- Route cables so that they are straight-lined to the terminals (do not form cable bundles).
- Minimize coupling capacities and coupling inductances by avoiding unnecessary cable lengths and reserve loops.
- Short-circuit unused cores to the reference potential.
- Install the cables of a 24 V DC supply (positive and negative cable) close to each other or twisted over the entire length to avoid loops.
- Before leaving the control cabinet, connect the shield of the fieldbus cable to the mounting plate in accordance with EMC requirements.

Installation outside the control cabinet

- In the case of greater cable lengths, a greater cable distance between the cables is required.
- In the case of parallel routing (cable trays) of cables with different types of signals, the degree of interference can be minimized by using a metallic cable separator or isolated cable ducts.

Earthing concept

- Set up the earthing system with a star topology.
- Connect all components (inverters, filters, chokes) to a central earthing point (PE rail).
- Comply with the corresponding minimum cross-sections of the cables.
- When using several mounting plates, make a conductive connection over a large surface (e. g. using grounding strips).



Mechanical installation

Important notes

Measures for cooling during operation

- Ensure unimpeded ventilation of cooling air and outlet of exhaust air.
- If the cooling air is polluted (fluff, (conductive) dust, soot, grease, aggressive gases), take adequate countermeasures.
  - Install filters.
  - Arrange for regular cleaning of the filters.
  - Use air conditioners with hermetic separation of the inside and outside air of the control cabinet.
- If required, implement a separate air guide.

Preparation

Further data and information for mechanical mounting:

▸ Control cabinet structure 🕮 38

▸ Dimensions 🕮 171

Mounting position

- Vertical alignment - all mains connections are at the top and the motor connections at the bottom.

Installation clearances

- Maintain the specified installation clearances above and below to the other installations.
- Several devices of the same series can be lined up directly, regardless of the device size. No installation clearance is required between the devices.

Mechanical installation

- The mounting location and material must ensure a durable mechanical connection.
- Do not mount onto DIN rails!
- In case of continuous vibrations or shocks use vibration dampers. If non-conductive vibration dampers are used, an EMC-compliant design must be ensured.

How to mount the inverters onto the mounting plate.

Preconditions:

- Mounting plate with conductive surface

Required:

- Tool for drilling and thread cutting
- Screwdriver
- Screw and washer assemblies or hexagon socket screws with washers.

1. Prepare mounting plate with corresponding threaded holes.
2. Fit screws and washers (if applicable).
3. Do not yet tighten the screws.
4. Mount the inverter on the prepared mounting plate via keyhole suspension.
5. Only tighten the screws hand-tight.
6. Pre-assemble further units if necessary.
7. Adjust the units.
8. Screw the units onto the mounting plate.

The inverter and any other units are mounted on the mounting plate. You can begin with the wiring.

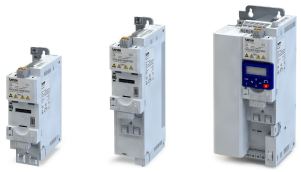
Screw and washer assemblies or hexagon socket screws with washers are recommended..

M5 x ≥ 10 mm for devices up to and including 2.2 kW

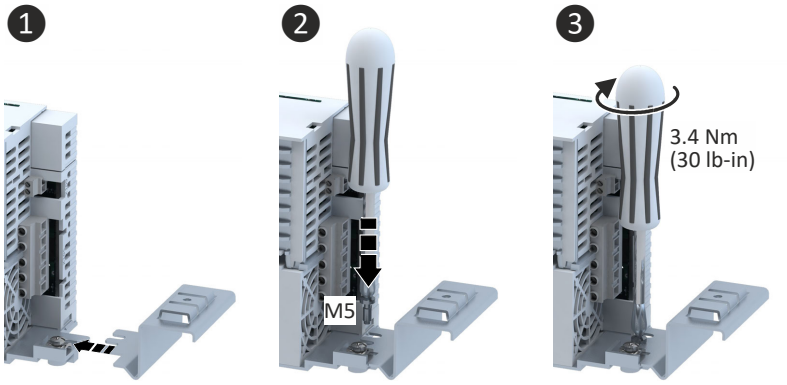
M5 x ≥ 12 mm for devices up to and including 11 kW

M6 x ≥ 16 mm for devices up to and including 22 kW

M8 x ≥ 16 mm for devices up to and including 110 kW

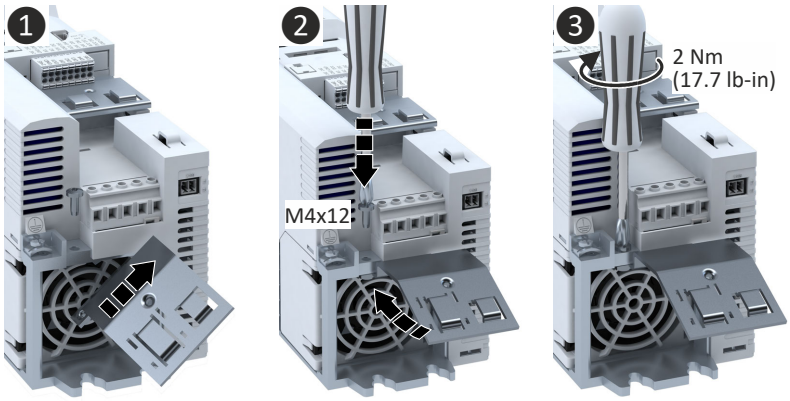


Installation of shield connection sheet for motor cable 0.25 kW to 4 kW (optional accessories)

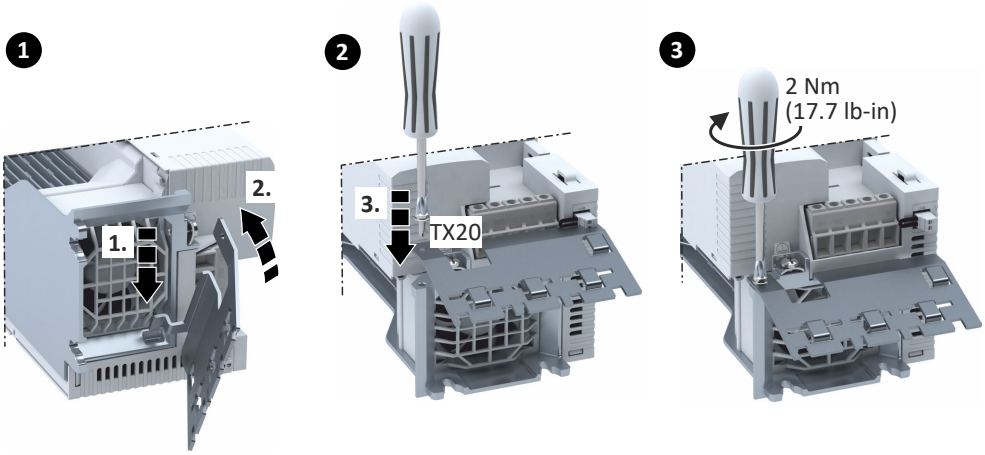


Together with the inverter, the shield connection sheet is screwed onto the mounting plate.

Installation of shield connection sheet for motor cable 5.5 kW (optional accessories)

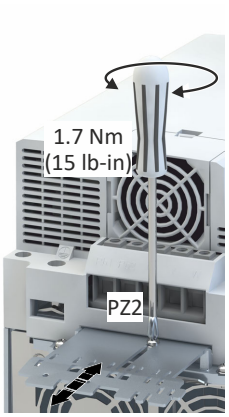


Installation of shield connection sheet for motor cable 7.5 kW to 11 kW (optional accessories)

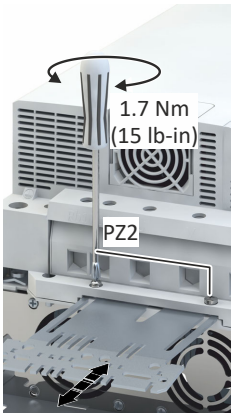


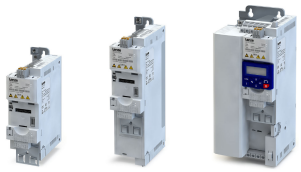
Installation of shield connection sheet for motor cable 15 kW to 45 kW

15 kW to 30 kW



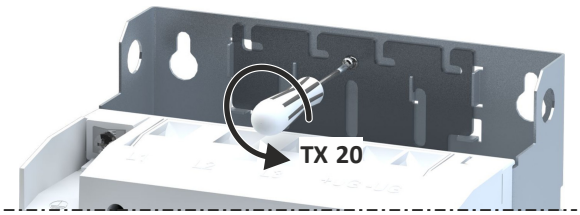
37 kW to 45 kW

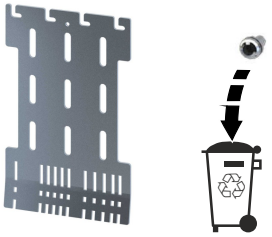




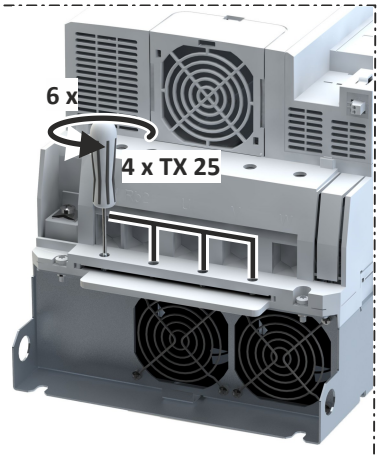
Installation of shield connection sheet for motor cable 55 kW to 110 kW

1

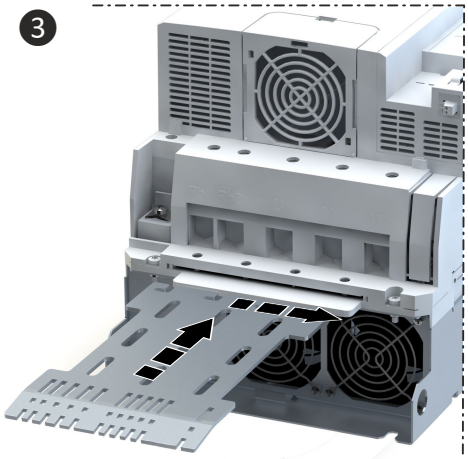




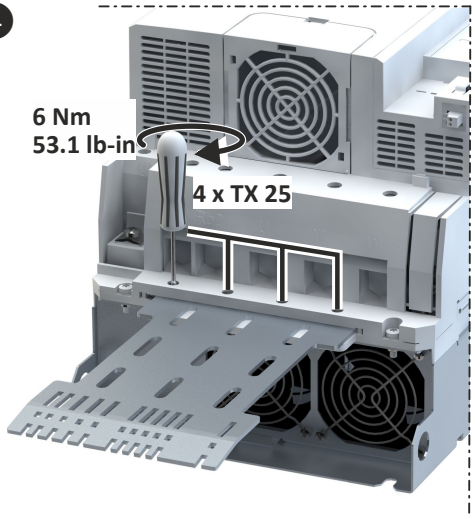
2



3



4



Electrical installation

Important notes

⚠ DANGER!

Dangerous electrical voltage

During operation and up to 20 minutes after power-off, hazardous electrical voltages may be present at the connections of the product.

The leakage current against earth (PE) is > 3.5 mA AC or > 10 mA DC.

Possible consequences: Death or serious injury from electric shock

Protective measures

- Any work on the product must only be carried out in a deenergized state.
- Check that no voltage is present!
- After switching off the mains voltage, observe the signs on the product.
- After switching off, wait until the drive comes to a standstill.
- Implement the measures required by EN 61800-5-1 or EN 60204-1, i.e. fixed installation and standard-compliant PE connection.

⚠ DANGER!

Use of the inverter on a phase earthed mains with a rated mains voltage ≥ 400 V

The protection against accidental contact is not ensured without external measures.

- If protection against accidental contact according to EN 61800-5-1 is required for the control terminals of the inverters and the connections of the plugged device modules, ...
- an additional basic insulation has to be provided.
- the components to be connected have to come with a second basic insulation.

⚠ WARNING!

Dangerous electrical voltage

Device error causes an overvoltage in the system.

- For a voltage supply with DC 24 V (± 20 %), use only a safely separated power supply unit according to the valid SELV/PELV requirements.

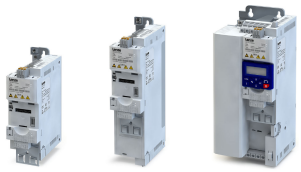
NOTICE

No protection against excessively high mains voltage

The mains input is not fused internally.

Possible consequences: Destruction of the product in the event of excessively high mains voltage.

- Take note of the maximum permissible mains voltage.
- On the mains supply side, use fuses to adequately protect the product against mains fluctuations and voltage peaks.



NOTICE

Overvoltage at devices with 230-V mains connection

An impermissible overvoltage may occur if the central supply of the N conductor is interrupted if the devices are connected to a TN three-phase system.

Possible consequences: Destruction of the device

- Provide for the use of isolating transformers.

NOTICE

The product contains electrostatic sensitive devices.

Possible consequences: Destruction of the device

- Before working in the connection area, the personnel must be free of electrostatic charge.

NOTICE

Use of mains filters and RFI filters in IT systems

Mains filters and RFI filters from Lenze contain components that are interconnected against PE.

Possible consequences: The filters may be destroyed when an earth fault occurs.

Possible consequences: Monitoring of the IT system may be triggered.

- Do not use mains filters and RFI filters from Lenze in IT systems.
- Before using the inverter in the IT system, remove the IT screws.

NOTICE

Overvoltage at components

In case of an earth fault in IT systems, intolerable overvoltages may occur in the plant.

Possible consequences: Destruction of the device.

- Before using the inverter in the IT system, the contact screws must be removed.
- Positions and number of the contact screws depend on the device.

When implementing machines and systems for the use in the UL/CSA scope, you have to observe the relevant special notes.

These notes are marked with "UL marking".

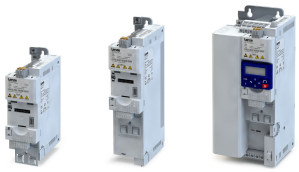
You have to install the devices into housings (e. g. control cabinets) to comply with valid regulations.

Stickers with warning notes must be displayed prominently and close to the device.

Electrical isolation

Ensure a trouble-free operation:

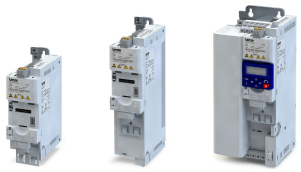
Carry out the total wiring so that the separation of the separate potential areas is preserved.



Preparation

Further data and information

- EMC-compliant installation 📖 48
- Standards and operating conditions 📖 80



EMC-compliant installation

The drive system (inverter and drive) only complies with the directive 2014/30/EU: EMC Directive [UKCA: S.I. 2016/1091 - The Electromagnetic Compatibility Regulations 2016] if it is installed according to the guidelines for CE-typical drive systems.

These guidelines should also be followed in installations requiring FCC Part 15 or ICES 001 compliance.

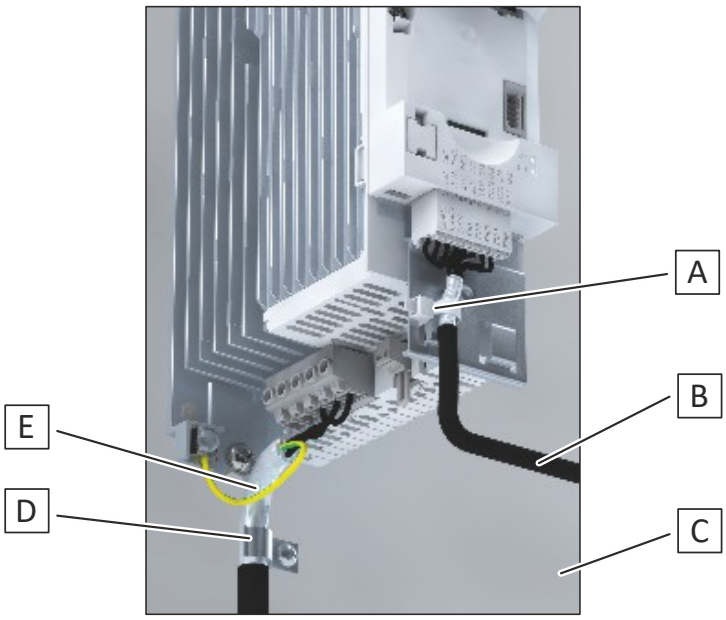
The structure in the control cabinet must support the EMC-compliant installation with shielded motor cables.

- Please use sufficiently conductive shield connections.
- Connect the housing with shielding effect to the grounded mounting plate with a surface as large as possible, e. g. of inverters and RFI filters.
- Use central grounding points.

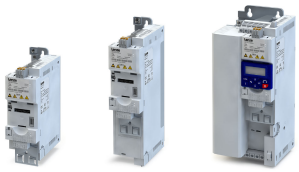
Matching accessories makes effective shielding easier.

- Motor shield plates as alternative shield connections for the motor cable
- Shield clips/shield clamps
- Metallic cable ties

The example below shows the effective wiring:



A	Shield connection of control cable	D	Shield connection of motor cable (alternative: shield connection on optional motor shield plate)
B	Control cable		
C	Mounting plate with conductive surface	E	Motor cable with low capacitance



Mains connection

- Inverters, mains chokes, or mains filters may be connected to the mains via unshielded single cores or unshielded cables.
- Cable between line filter and inverter:

	Cable length	
	≤ 300 mm	**> 300 mm**
Type	unshielded twisted option	always shielded

- In DC-bus operation or DC supply, use shielded cables.

External RFI filters

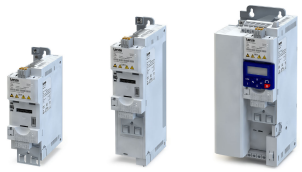
In order to meet the EMC requirements according to EN IEC 61800-3,

- an external RFI filter according to IEC EN 60939 must be used with certain inverters and
- one or both screws marked "IT" on the product must be removed when using certain external RFI filters.

More information can be found under: ▸ Technical data 🕮 80

DC supply

- In DC-bus operation or DC supply, use shielded cables.



Motor cable

EMC-compliant installation must be carried out with shielded low-capacitance motor cables.

Capacitance per unit length

- Cable cross-section ≤ 2.5 mm² (≥ AWG 14): C-core-core/C-core-shield <75/150 pF/m
- Cable cross-section ≤ 4 mm² (≥ AWG 12): C-core-core/C-core-shield <150/300 pF/m

Braid

- Only use motor cables with braids made of tinned or nickel-plated copper.
- Shields made of steel braids are not suitable.
- The overlap rate of the braid must be at least 70 % with an overlap angle of 90 °.

Shield connection

- Apply shielding over a large area.
- Shield mounting with metal cable tie or conductive clip.
- The following is suitable for connecting the shield:
  - The mounting plate
  - A central grounding rail
  - A shield plate, if necessary, optional ▸ Shield mounting kit 📖 226

Cable for motor temperature monitoring

- Shield the cable for motor temperature monitoring (PTC or thermal contact) and install it separately from the motor cable.
- In Lenze system cables, the cable for the brake control is integrated into the motor cable. If this cable is not required, it can also be used to connect the motor temperature monitoring up to a length of 50 m.

Measures on the motor

- Connect the shield with PE over a large area at the terminal box of the motor, e.g. via a metallic EMC cable gland.
- For motors with plug connectors, the large-area shield connection is ensured via the plug connection.

Further supporting measures

- Route the motor cable separately from the mains cables and control cables.
- Lay the motor cable so that it only crosses mains cables and control cables at right angles.
- Do not disconnect the motor cable.
- If the motor cable must be disconnected (e.g. by chokes, contactors, or terminals):
  - Install the shield of the motor cable directly before and behind the point of separation to the mounting plate with a large surface.
  - The unshielded cable ends must not be longer than 100 mm.
  - Mount the separating component at least 100 mm away from other components.

Control cables

- Install the cables so that no induction-sensitive loops arise.
- Distance of shield connections of control cables to shield connections of motor cables and DC cables:
  - At least 50 mm
- Control cables for analog signals:
  - Must always be shielded
  - Connect the shield on one side of the inverter
- Control cables for digital signals:

	Cable length		
	< ca. 5 m	**ca. 5 m ... ca. 30 m**	**> ca. 30 m**
Type	unshielded option	unshielded twisted option	always shielded connected on both sides

Fieldbus cables, networks

Please observe the following recommendations for trouble-free operation, especially in the event of Ethernet-based networks.

- Cables and wiring must meet the specifications and requirements of the network being used to allow reliable operation of the network in typical installations. In this context, also observe the recommendations for action of the respective user organization.
- Lay network cables separately from power cables. Maintain as large a distance as possible to the motor cables which are subject to interference.
- To avoid compensating currents via the shielding of the network cable, install an independent, low-resistance equipotential bonding over the shortest possible distance parallel to the network cable. This applies in particular to long cables.
- Observe bending radii according to manufacturer information. Minimum bending radii of 10 x cable diameter or 20 x diameter for frequent manipulation of the cables are standard.
- Fix longer cables 30 cm after the connection point.
- Before leaving the control cabinet, connect the shield of the network cable with the equipotential bonding system (e. g. mounting plate) on a large surface.

Patch cable/CAT5 cables:

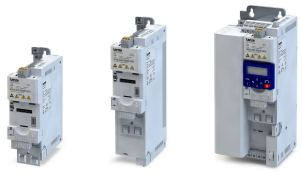
- Cables must comply with CAT5 and be suitable for ≥ 10 Mbps.
- CAT5 cables according to specification establish the shield connection via the RJ45 plug connection. Additional shield connections are not required.
- Patch cables of 25 cm length are suitable for the network connection of inverters ≤ 4 kW installed side by side. When wiring from right to left, a sufficient bending radius can be maintained.
- Only certified, tested and fully assembled patch cables from well-known manufacturers are recommended.

RJ45 plug connections:

- RJ45 plug connections only function properly if they are not subjected to mechanical stress or lateral forces.
- For all communication modules of the i-series, the connection of the cable shielding at the RJ45 sockets is carried out as follows:
  - At the first RJ45 socket, the shielding is directly connected to functional earth (FE).
  - At the second RJ45 socket, the shielding is connected to functional earth (FE) via an RC element.

  This measure prevents potential equalization currents and the resulting interference effects (see also IEC 61158-2, section 11.8.7).

  Note: High-frequency interference is dissipated via the low-impedance capacitor to functional earth (FE), but for low-frequency signals this system has a high loop impedance. Measuring systems that use low impedance test signals therefore indicate too high impedance values for the shielding at the second RJ45 socket



Detecting and eliminating EMC interferences

Trouble	Cause	Remedy
Interferences of analog setpoints of your own or other devices and measuring systems	Unshielded motor cable has been used	Use shielded motor cable
	Shield contact is not extensive enough	Carry out optimal shielding as specified
	Shield of the motor cable is interrupted, e. g. by terminal strips, switches etc.	• Separate components from other component parts with a minimum distance of 100 mm • Use motor chokes or motor filters
	Additional unshielded cables inside the motor cable have been installed, e. g. for motor temperature monitoring	Install and shield additional cables separately
	Too long and unshielded cable ends of the motor cable	Shorten unshielded cable ends to max. 40 mm
Conducted interference level is exceeded on the supply side	Terminal strips for the motor cable are directly located next to the supply terminals	Spatially separate the terminal strips for the motor cable from mains terminals and other control terminals with a minimum distance of 100 mm
	Mounting plate varnished	Optimize PE connection: • Remove varnish • Use zinc-coated mounting plate
	HF short circuit	Check cable routing
Malfunctions of the fieldbus communication or exceedance of the permissible interference levels	Shield contact is not extensive enough	Before leaving the control cabinet, connect the shield of the fieldbus cable with the equipotential bonding system (e. g. mounting plate) on a large surface.
	Shield connection on the inverter only	
	Shield of fieldbus cable connected on one side only	Shield connection on both sides

Connection according to UL

Important notes

⚠WARNING!

- **UL marking**
- The integral solid state short circuit protection included in the inverter does not provide branch circuit protection. Branch circuit protection must be provided in accordance with the National Electrical Code / Canadian Electrical Code and any additional local codes.
- **Marquage UL**
- La protection statique intégrée contre les courts-circuits n'offre pas la même protection que le dispositif de protection du circuit de dérivation. Un tel dispositif doit être fourni, conformément au National Electrical Code / Canadian Electrical Code et aux autres dispositions applicables au niveau local.

⚠WARNING!

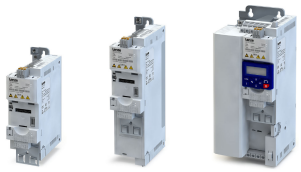
- **UL marking**
- Use 75 °C copper wire only, except for control circuits.
- **Marquage UL**
- Utiliser exclusivement des conducteurs en cuivre 75 °C, sauf pour la partie commande.

⚠WARNING!

- **UL marking**
- Suitable for motor group installation or use on a circuit capable of delivering not more than the RMS symmetrical amperes (SCCR) of the drive at its rated voltage.
- Approved fusing is specified in SCCR tables below.
- **Marquage UL**
- Convient pour l'utilisation sur une installation avec un groupe de moteurs ou sur un circuit capable de fournir au maximum une valeur de courant efficace symétrique en ampères à la tension assignée de l'appareil.
- Les dispositifs de protection adaptés sont spécifiés dans les SCCR tableaux suivants.

⚠WARNING!

- **UL marking**
- The opening of the Branch Circuit Protective Device may be an indication that a fault has been interrupted. To reduce the risk of fire or electric shock, current carrying parts and other components of the controller should be examined and replaced if damaged. If burnout of the current element of an overload relay occurs, the complete overload relay must be replaced.
- **Marquage UL**
- Le déclenchement du dispositif de protection du circuit de dérivation peut être dû à une coupure qui résulte d'un courant de défaut. Pour limiter le risque d'incendie ou de choc électrique, examiner les pièces porteuses de courant et les autres éléments du contrôleur et les remplacer s'ils sont endommagés. En cas de grillage de l'élément traversé par le courant dans un relais de surcharge, le relais tout entier doit être remplacé.



NOTICE

- **UL marking**
- Internal overload protection rated for 125 % of the rated FLA.
- **Marquage UL**
- Protection contre les surcharges conçue pour se déclencher à 125 % de l'intensité assignée à pleine charge.

Fusing data

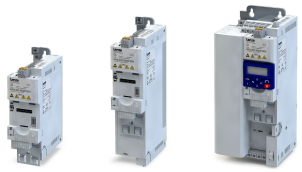
Branch Circuit Protection (BCP) with standard fuses or circuit breakers

Short Circuit Current Ratings (SCCR) with Standard Fuses or Circuit Breaker

(Tested per UL61800-5-1, reference UL file E132659)

These devices are suitable for motor group installation when used with Standard Fuses or Circuit Breaker. For single motor installation, if the fuse value indicated is higher than 400 % of the motor current (FLA), the fuse value has to be calculated. If the value of the fuse is below two standard ratings, the nearest standard ratings less than the calculated value shall apply.

Inverter			Standard Fuses (UL248)			Circuit Breaker (UL489)			
Mains	Rated power		Max. SCCR	Max. rated current	Class	Max. SCCR	Max. rated current	Min. cabinet dimensions	
	kW	hp	kA	A		kA	A	m³	ft³
120 V, 1-ph	0.25	0.33	5	15	CC	5	15		
120 V, 1-ph	0.37	0.5	5	15	CC	5	15		
120 V, 1-ph	0.75	1	5	30	CC, CF, J, T	5	30		
120 V, 1-ph	1.1	1.5	5	30	CC, CF, J, T	5	30		
230 V, 1-ph	0.25	0.33	65	15	CC, CF, J, T	65	15	0.042	1.48
230 V, 1-ph	0.37	0.5	65	15	CC, CF, J, T	65	15	0.042	1.48
230 V, 1-ph	0.55	0.75	65	30	CC, CF, J, T	65	30	0.042	1.48
230 V, 1-ph	0.75	1	65	30	CC, CF, J, T	65	30	0.042	1.48
230 V, 1-ph	1.1	1.5	65	30	CC, CF, J, T	65	30	0.042	1.48
230 V, 1-ph	1.5	2	65	30	CC, CF, J, T	65	30	0.042	1.48
230 V, 1-ph	2.2	3	65	30	CC, CF, J, T	65	30	0.042	1.48
230 V, 1/3-ph	0.25	0.33	65	15	CC, CF, J, T	65	15	0.042	1.48
230 V, 1/3-ph	0.37	0.5	65	15	CC, CF, J, T	65	15	0.042	1.48
230 V, 1/3-ph	0.55	0.75	65	30	CC, CF, J, T	65	30	0.042	1.48
230 V, 1/3-ph	0.75	1	65	30	CC, CF, J, T	65	30	0.042	1.48
230 V, 1/3-ph	1.1	1.5	65	30	CC, CF, J, T	65	30	0.042	1.48
230 V, 1/3-ph	1.5	2	65	30	CC, CF, J, T	65	30	0.042	1.48
230 V, 1/3-ph	2.2	3	65	30	CC, CF, J, T	65	30	0.042	1.48
230 V, 3-ph	4	5	100	40	CC, CF, J, T	65	40	0.042	1.48
230 V, 3-ph	5.5	7.5	100	40	CC, CF, J, T	65	40	0.042	1.48
480 V, 3-ph	0.37	0.5	65	15	CC, CF, J, T	65	15	0.042	1.48
480 V, 3-ph	0.55	0.75	65	15	CC, CF, J, T	65	15	0.042	1.48
480 V, 3-ph	0.75	1	65	15	CC, CF, J, T	65	15	0.042	1.48
480 V, 3-ph	1.1	1.5	65	15	CC, CF, J, T	65	15	0.042	1.48
480 V, 3-ph	1.5	2	65	15	CC, CF, J, T	65	15	0.042	1.48
480 V, 3-ph	2.2	3	65	15	CC, CF, J, T	65	15	0.042	1.48
480 V, 3-ph	3	4	65	35	CC, CF, J, T	65	25	0.042	1.48
480 V, 3-ph	4	5	65	35	CC, CF, J, T	65	25	0.042	1.48
480 V, 3-ph	5.5	7.5	65	30	CC, CF, J, T	65	25	0.042	1.48
480 V, 3-ph	7.5	10	65	40	CC, CF, J, T	65	40	0.042	1.48
480 V, 3-ph	11	15	65	40	CC, CF, J, T	65	40	0.042	1.48
480 V, 3-ph	15	20	65	90	CC, CF, J, T	65	90	0.28	10
480 V, 3-ph	18.5	25	65	90	CC, CF, J, T	65	90	0.28	10
480 V, 3-ph	22	30	65	90	CC, CF, J, T	65	90	0.28	10
480 V, 3-ph	30	40	65	90	CC, CF, J, T	65	90	0.28	10
480 V, 3-ph	37	50	22	125	CF, J, T	35	125	0.57	20
480 V, 3-ph	45	60	22	125	CF, J, T	35	125	0.57	20
480 V, 3-ph	55	75	22	200	CF, J, T	35	200	0.57	20
480 V, 3-ph	75	100	22	200	CF, J, T	35	200	0.57	20
480 V, 3-ph	90	125	22	300	CF, J, T	10	300	0.57	20
480 V, 3-ph	110	150	22	300	CF, J, T	10	300	0.57	20



Short Circuit Current Ratings (SCCR) with Semiconductor Fuses

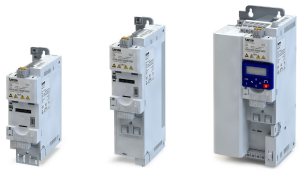
(Tested per UL61800-5-1, reference UL file E132659)

These devices are suitable for standard installation when used with Semiconductor Fuses. For single motor installation, if the fuse value indicated is higher than 400 % of the motor current (FLA), the fuse value has to be calculated. If the value of the fuse is below two standard ratings, the nearest standard ratings less than the calculated value shall apply.

Inverter			Alternate Fuse (Semiconductor Fuse)	
Mains	Rated power		Max. SCCR	Max. rated current
	kW	hp	kA	A
120 V, 1-ph	0.25	0.33		
120 V, 1-ph	0.37	0.5		
120 V, 1-ph	0.75	1		
120 V, 1-ph	1.1	1.5		
230 V, 1-ph	0.25	0.33	100	16
230 V, 1-ph	0.37	0.5	100	16
230 V, 1-ph	0.55	0.75	100	40
230 V, 1-ph	0.75	1	100	40
230 V, 1-ph	1.1	1.5	100	50
230 V, 1-ph	1.5	2	100	50
230 V, 1-ph	2.2	3	100	50
230 V, 1/3-ph	0.25	0.33	100	16
230 V, 1/3-ph	0.37	0.5	100	16
230 V, 1/3-ph	0.55	0.75	100	40
230 V, 1/3-ph	0.75	1	100	40
230 V, 1/3-ph	1.1	1.5	100	40
230 V, 1/3-ph	1.5	2	100	40
230 V, 1/3-ph	2.2	3	100	40
230 V, 3-ph	4	5	100	50
230 V, 3-ph	5.5	7.5	100	50
480 V, 3-ph	0.37	0.5	100	6
480 V, 3-ph	0.55	0.75	100	16
480 V, 3-ph	0.75	1	100	16
480 V, 3-ph	1.1	1.5	100	16
480 V, 3-ph	1.5	2	100	16
480 V, 3-ph	2.2	3	100	20
480 V, 3-ph	3	4	100	40
480 V, 3-ph	4	5	100	40
480 V, 3-ph	5.5	7.5	100	50
480 V, 3-ph	7.5	10	100	63
480 V, 3-ph	11	15	100	80
480 V, 3-ph	15	20	100	100
480 V, 3-ph	18.5	25	100	100
480 V, 3-ph	22	30	100	100
480 V, 3-ph	30	40	100	100
480 V, 3-ph	37	50	100	125
480 V, 3-ph	45	60	100	125
480 V, 3-ph	55	75	100	200
480 V, 3-ph	75	100	100	200
480 V, 3-ph	90	125	100	350
480 V, 3-ph	110	150	100	350

Approved manufacturers for semiconductor fuses

Manufacturer	Max. rated current	Designation
	A	
Eaton/Bussmann	6	FWP-6A14F
	16	FWP-15B, FWP-15A14F
		170M1309, 170M1359, 170M1409
	20	FWP-20B, FWP-20A14F
		170M1310, 170M1360, 170M1410
	40	FWP-40A22F, FWP-40B, FWP-40A14F, FWP-40A
		170M1313, 170M1363, 170M1413
	50	FWP-50A22F, FWP-50B, FWP-50A14F, FWP-50A
		170M1314, 170M1364, 170M1414
	63	FWP-63A22F, FWP-60B, FWP-60A
		170M1315, 170M1365, 170M1415
	80	FWP-80A22F, FWP-80B, FWP-80A
		170M1316, 170M1366, 170M1416
	100	FWP-100A22F, FWP-100B, FWP-100A
		170M1317, 170M1367, 170M1417
	125	FWP-125A
		170M1318, 170M1368, 170M1418
	200	FWP-200A
		170M1320, 170M1370, 170M1420
	350	FWP-350A
Littelfuse	40	L70QS040
	50	L70QS050
	63	L70QS060
	80	L70QS080
	100	L70QS100
	125	L70QS125
	200	L70QS200
	350	L70QS350
Mersen	6	A70QS6-14F, A70QS6-14FI
	16	A60Q15-2
		A70QS16-14F, A70QS16-14FI, A70QS15-22F, A70QS15-22FI
	20	A70QS20-14F, A70QS20-14FI, A70QS20-22F, A70QS20-22FI
	40	A70QS40-14F, A70QS40-14FI, A70QS40-22F, A70QS40-22FI, A70QS40-4
	50	A70QS50-22F, A70QS50-14F, A70QS50-14FI, A70QS50-22FI, A70QS50-4
	63	A70QS63-22F, A70QS63-22FI, A70QS60-4
	80	A70QS80-22F, A70QS80-4, A70QS80-22FI
	100	A70QS100-4, A70QS100-22F, A70QS100-22FI
	125	A70QS125-4, A70QS125-4K
	200	A70QS200-4, A70QS200-4K
	350	A70QS350-4
SIBA	16	5020106.16, 5020206.16
	20	5020106.20, 5020206.20
	40	5020106.40, 5020206.40
	50	5020106.50, 5020206.50
	63	2029220.63
		5020106.63, 5020206.63
	80	2029220.80
	100	2029220.100
	125	2029220.125
	200	2029220.200



Mains connection

Single inverters are connected directly to the **AC system** or via upstream filters. RFI filters are already integrated in many inverters. Depending on the requirements, mains chokes or mains filters can be used.

In a **DC-system**, several inverters are operated in a network. This enables an energy exchange between motor and generator driven single drives.

1-phase mains connection 120 V

The connection plan is valid for the inverters i550-Cxxx/120-1.

The inverters i550-Cxxx/120-1 do not have an integrated RFI filter in the AC mains supply.

In order to meet the EMC requirements according to EN IEC 61800-3, an external EMC filter according to IEC EN 60939 must be used.

The user must verify that the conformity with EN IEC 61800-3 is fulfilled.

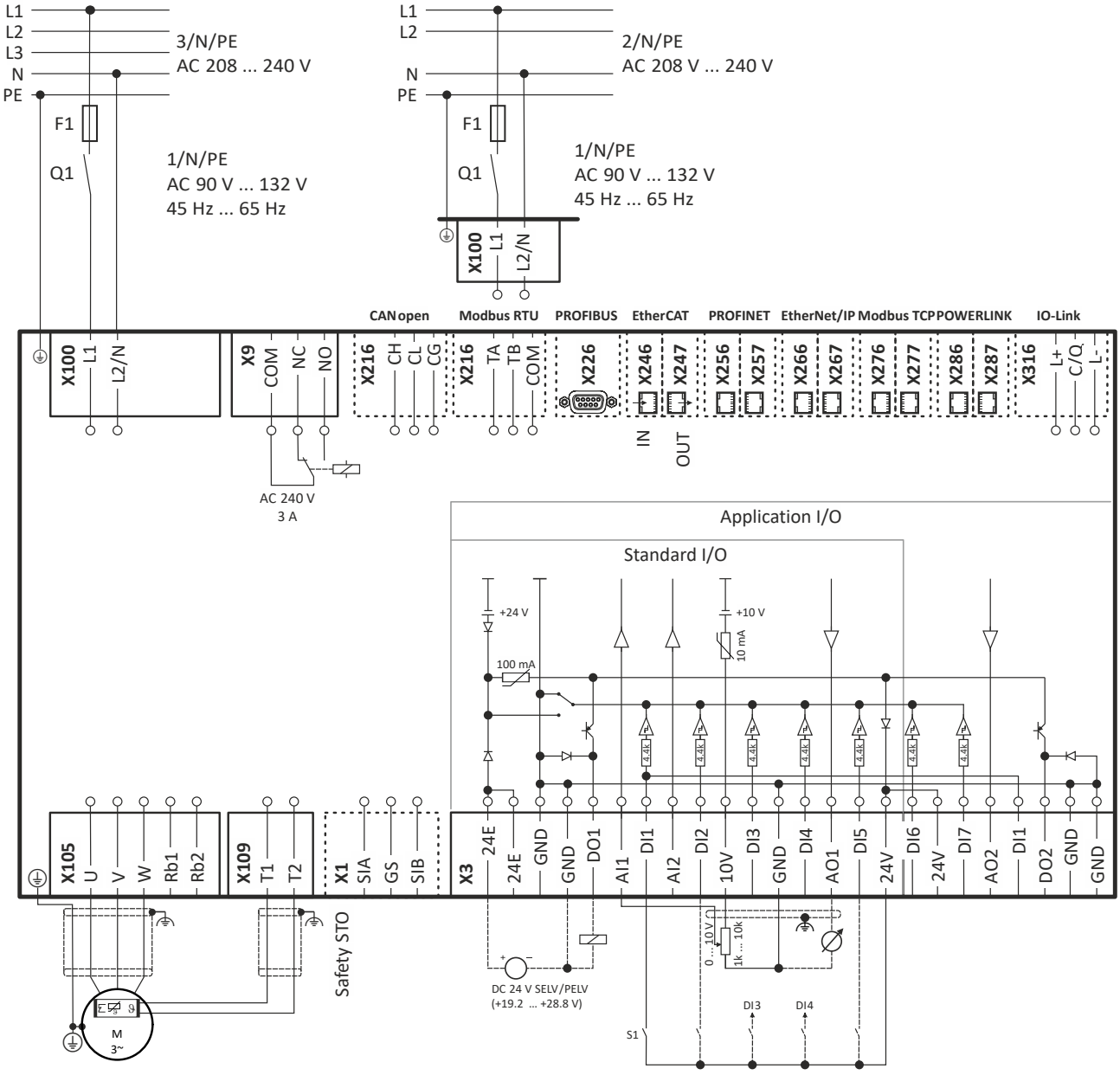
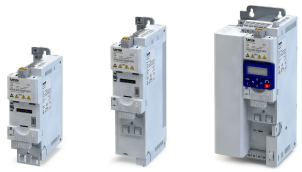


Fig. 2: Wiring example

S1	Start/Stop	Q1	Mains contactor
Fx	Fuses	---	Dashed line = options



1-phase mains connection 230/240 V

The connection plan is valid for the inverters i550-Cxxx/230-1.

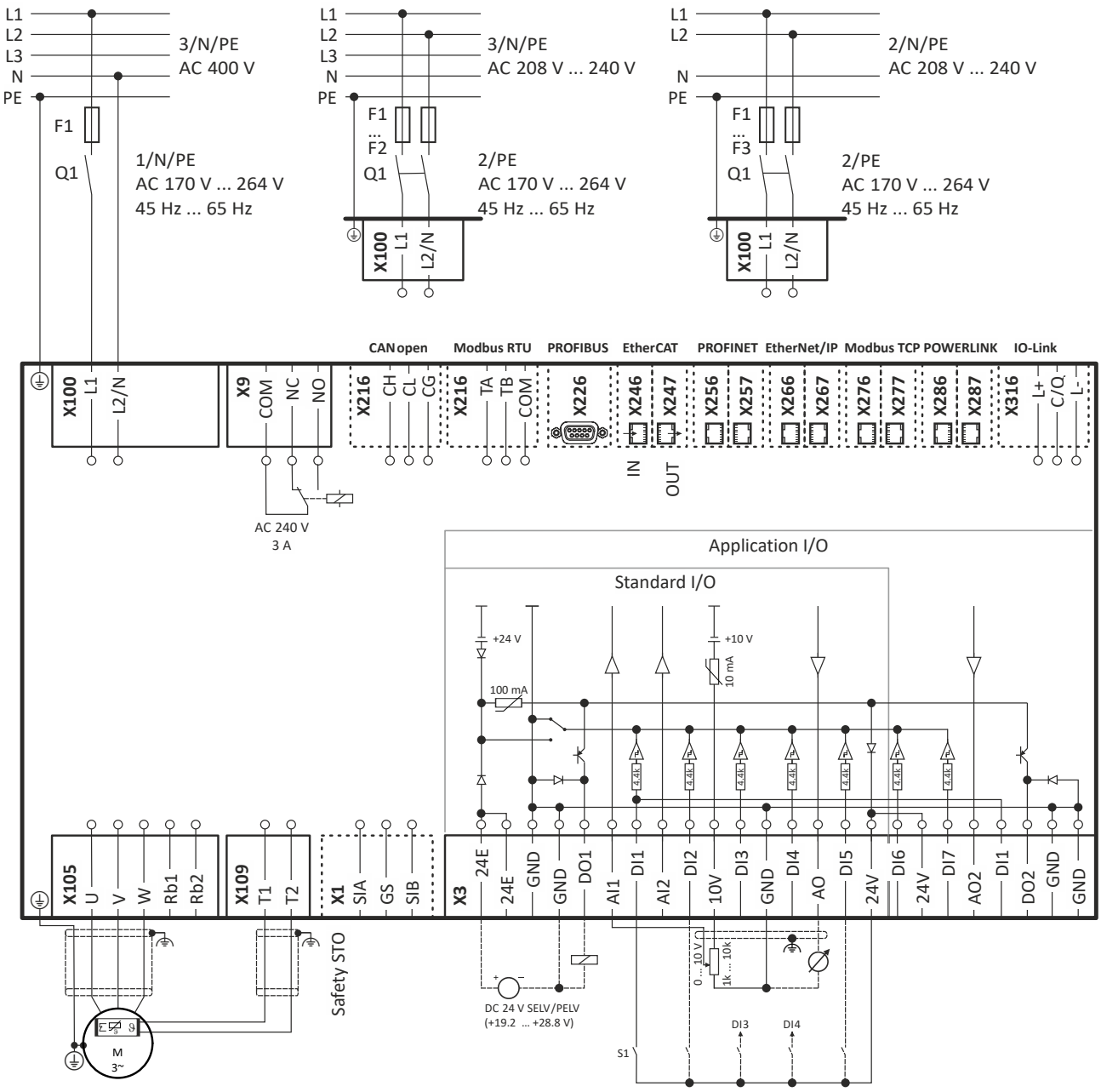


Fig. 3: Wiring example

S1	Start/Stop	Q1	Mains contactor
Fx	Fuses	---	Dashed line = options

The connection plan is valid for the inverters i550-Cxxx/230-2.

The inverters i550-Cxxx/230-2 do not have an integrated RFI filter in the AC mains supply.

In order to meet the EMC requirements according to EN IEC 61800-3, an external EMC filter according to IEC EN 60939 must be used.

The user must verify that the conformity with EN IEC 61800-3 is fulfilled.

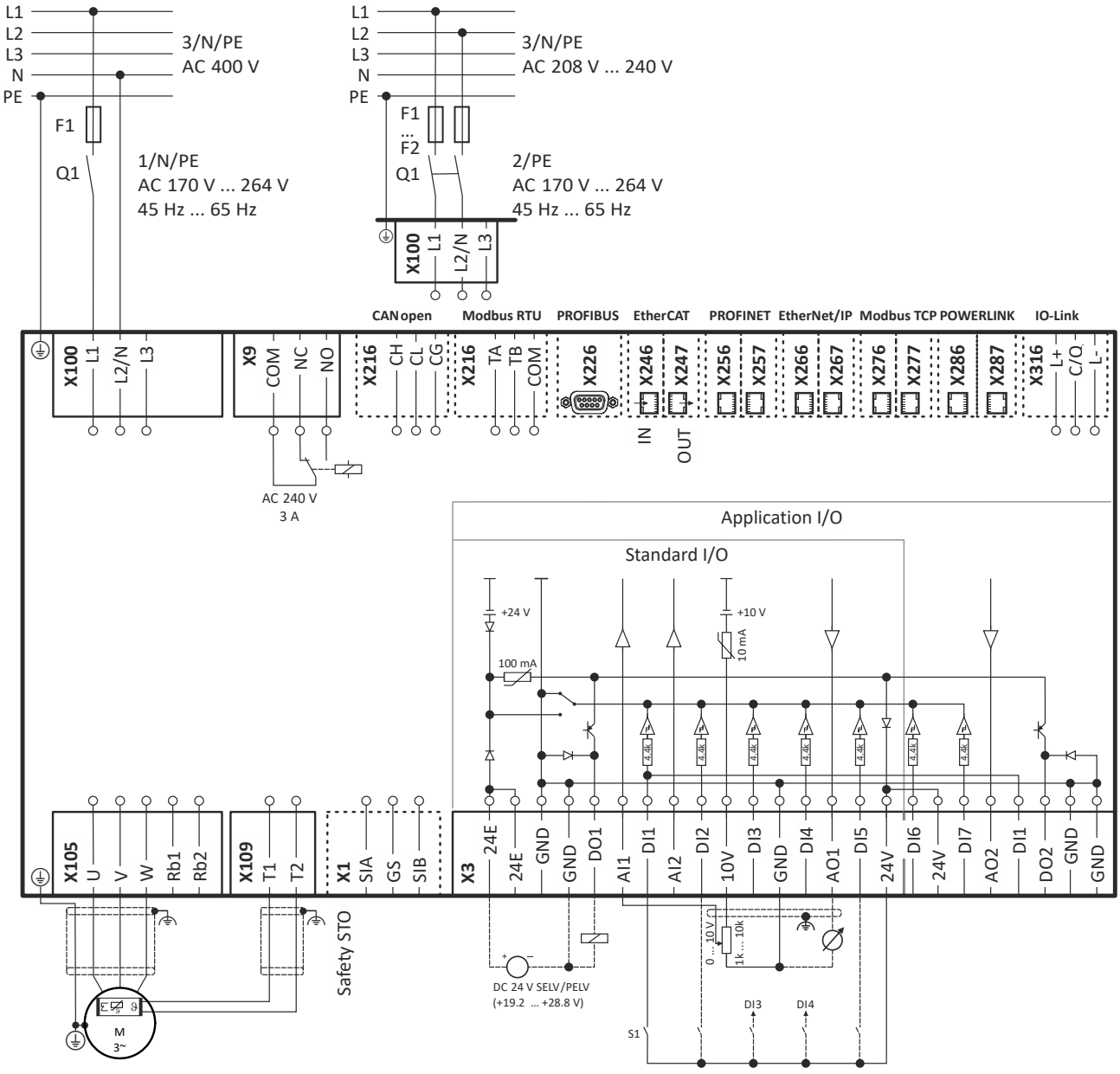
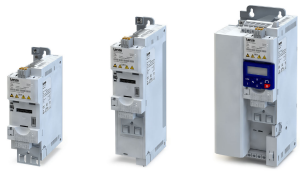


Fig. 4: Wiring example

S1	Start/Stop	Q1	Mains contactor
Fx	Fuses	---	Dashed line = options



3-phase mains connection 230/240 V

The connection plan is valid for the inverters i550-Cxxx/230-3 and i550-Cxxx/230-2.

The inverters i550-Cxxx/230-3 and i550-Cxxx/230-2 do not have an integrated RFI filter in the AC mains supply.

In order to meet the EMC requirements according to EN IEC 61800-3, an external EMC filter according to IEC EN 60939 must be used.

The user must verify that the conformity with EN IEC 61800-3 is fulfilled.

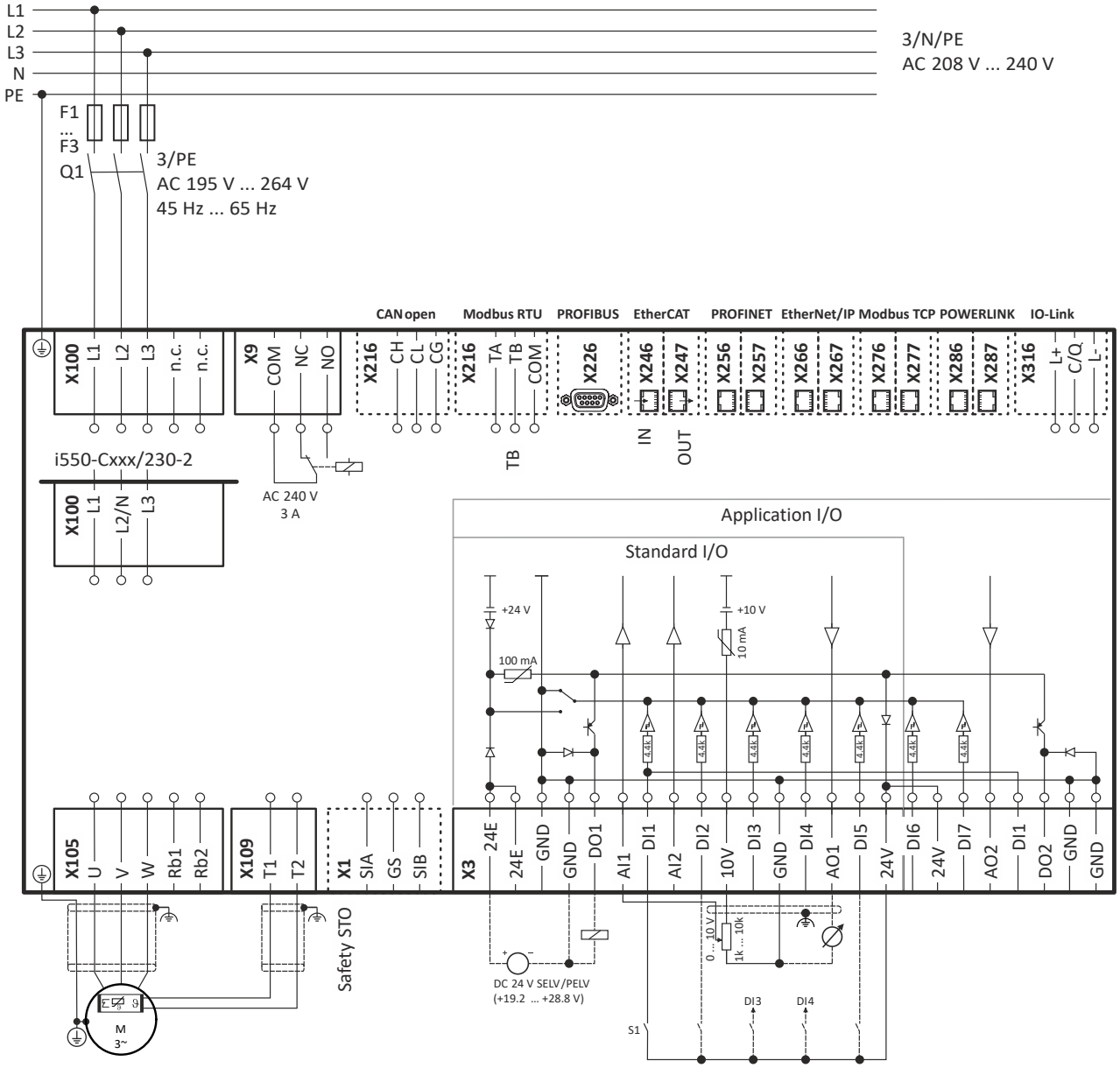


Fig. 5: Wiring example

S1	Start/Stop	Q1	Mains contactor
Fx	Fuses	---	Dashed line = options

3-phase mains connection 400 V

The connection plan is valid for the inverters i550-Cxxx/400-3.

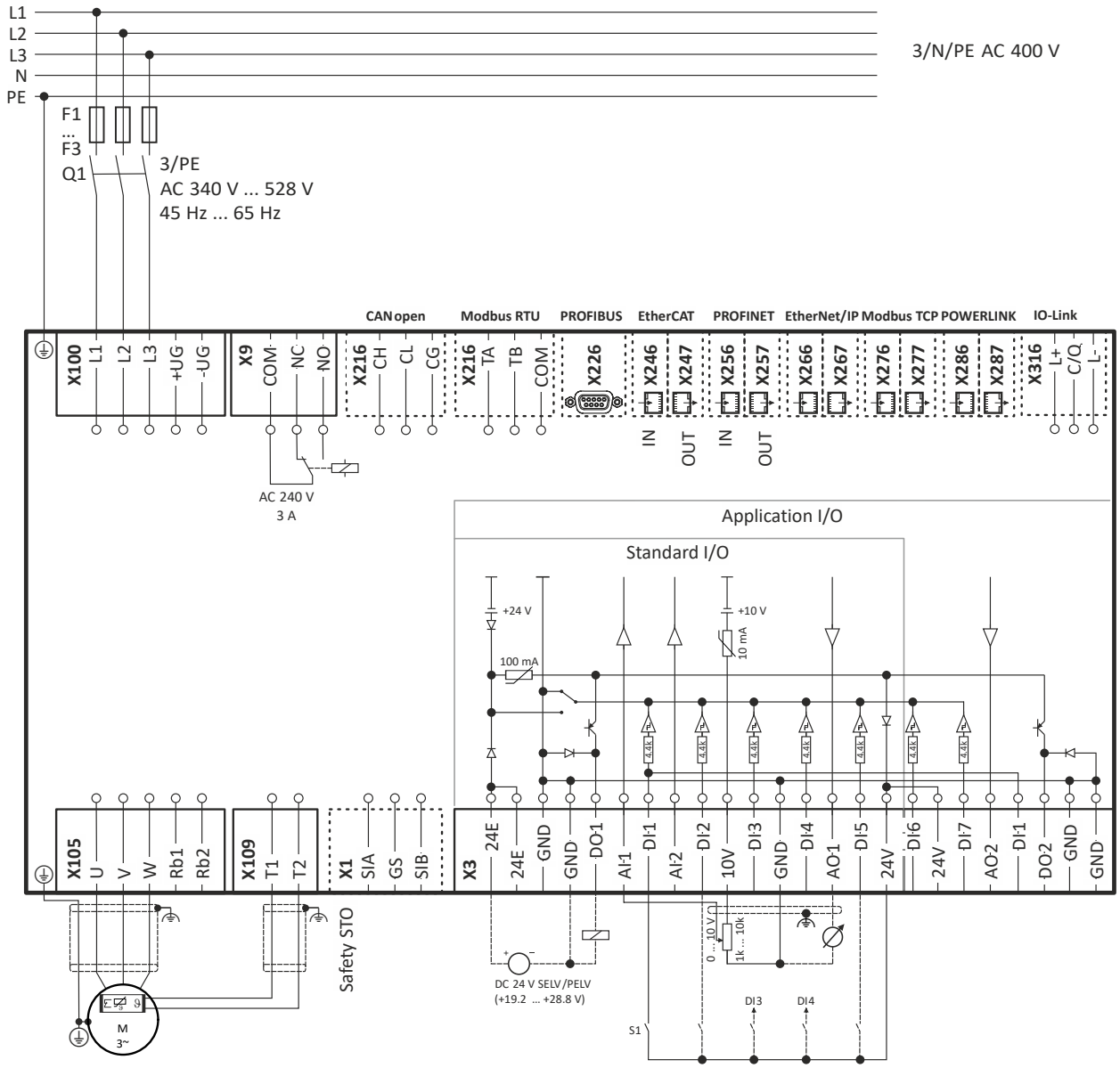
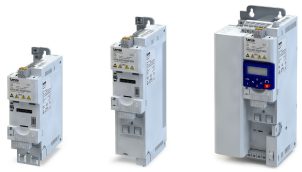


Fig. 6: Wiring example

S1	Start/Stop	Q1	Mains contactor
Fx	Fuses	---	Dashed line = options



3-phase mains connection 480 V

The connection plan is valid for the inverters i550-Cxxx/400-3.

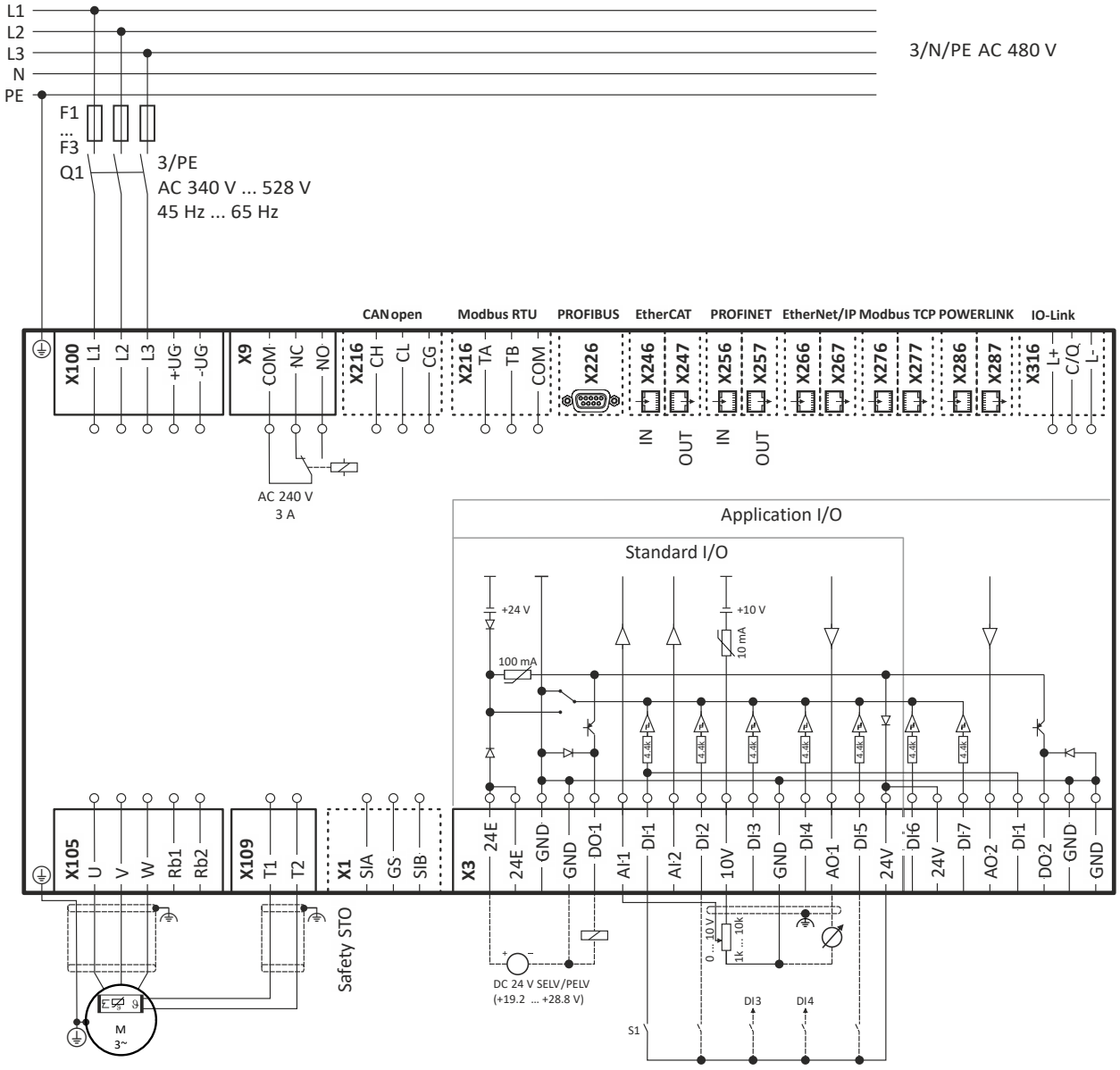


Fig. 7: Wiring example

S1	Start/Stop	Q1	Mains contactor
Fx	Fuses	---	Dashed line = options

Motor connection

Motor cable lengths

- The rated data for the motor cable length must be observed.
- Keep the motor cable as short as possible as this has a positive effect on the drive behaviour and the EMC.
- Several motors connected to an inverter form a group drive.
  In case of group drives, the resulting motor cable length l_{res} is relevant:

  l_{res} [m] = (l_1 + l_2 + l_3 ... l_i) · √i

l_{res}	Resulting length of the motor cables
l_x	Length of the single motor cable
i	Number of the single motor cables

Switching in the motor cable

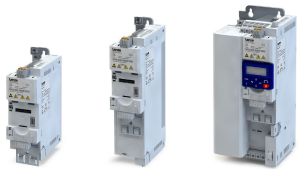
Switching on the motor side of the inverter is permissible:

For safety shutdown (emergency stop).

In case several motors are driven by one inverter (only in V/f operating mode).

Please note the following:

The switching elements on the motor side must be dimensioned for with the maximum occurring load.



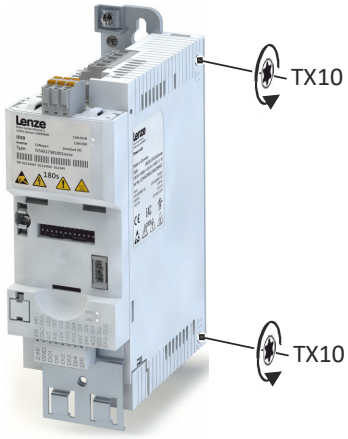
Connection to the IT system

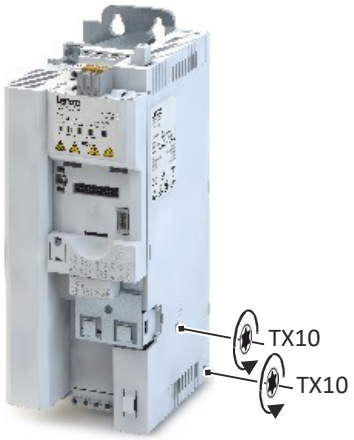
NOTICE

Internal components have earth/ground potential

Possible consequence: The monitoring devices of the IT system will be triggered.

- Upstream an isolation transformer.
- Before connection to an IT system be absolutely sure to remove the screws labeled with "IT" on the product.

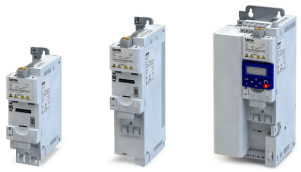
I55AE125x, I55AE137x	I55AE155x, I55AE175x, I55AE211x, I55AE215x, I55AE222x, I55BE230F, I55BE240F
	

I55AE240C, I55AE255x, I55BE275F, I55BE311F	I55BE315F, I55BE318F, I55BE322F, I55BE330F
	

I55AE337F, I55AE345F	I55AE355F, I55AE375F, I55AE390F, I55AE411F
	

Connection of motor temperature monitoring

If the terminal X109 is used, e. g. to connect an external PTC thermistor (PTC) or a thermal contact, ensure at least one basic insulation to the potentials of motor, mains and control terminals to not restrict the safe separation of the control terminals.



Brake resistor connection

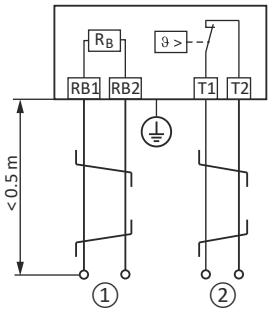
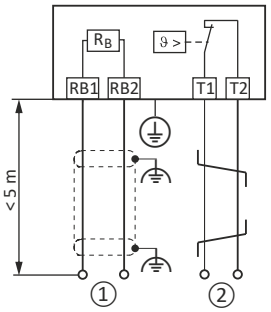
NOTICE

Overload

Overload can destroy the brake resistor.

- Protect the brake resistor of the inverter against overload with suitable parameterization.
- The thermostat of the brake resistor can be used to establish a safety shutdown to disconnect the controller from the mains.

Use intrinsically safe brake resistors to be able to dispense with a separate switch-off device (e.g. a contactor).

Short connection cables up to 0.5 m	Long connection cables up to max. 5 m
Up to a cable length of 0.5 m, the cable for the brake resistor and that of the temperature monitoring can be twisted. Doing so reduces problems due to EMC interference.	The cable of the brake resistor must be shielded. The maximum length is 5 m. Twisting is sufficient for the temperature monitoring cable.
	

① Wiring to the "brake resistor" connection on the component with brake chopper.

② Optional: Wiring to a control contact that is set to monitor the thermal contact.
If the thermal contact responds, the voltage supply to the component with brake chopper must be disconnected (e.g. switch off the control of the mains contactor).

Control connections

In case of long cables and/or high interference the effect of the shielding can be improved. To do this, connect the shield of cables for the analog inputs and outputs at one end of the cable via a capacitor with PE potential (e. g. 10 nF/ 250 V).

Connection description			Control terminals	Relay output	PTC input
Connection			**X3**	**X9**	**X109**
Connection type			Pluggable	Pluggable	Pluggable
Max. Cable cross-section		mm²	1.5	1.5	1.5
Max. Cable cross-section		AWG	16	14	14
Min. Cable cross-section		mm²	0.5	0.5	0.5
Min. Cable cross-section		AWG	22	22	22
Stripping length		mm	9	6	6
Stripping length		in	0.35	0.2	0.2
Required tool			Screwdriver 0.4 x 2.5		

Networks

When planning networks, consider the recommendations listed in the chapter "EMC-compliant installation" for low-interference operation, especially of Ethernet-based networks.

EMC-compliant installation → Fieldbus cables, networks 📖 51

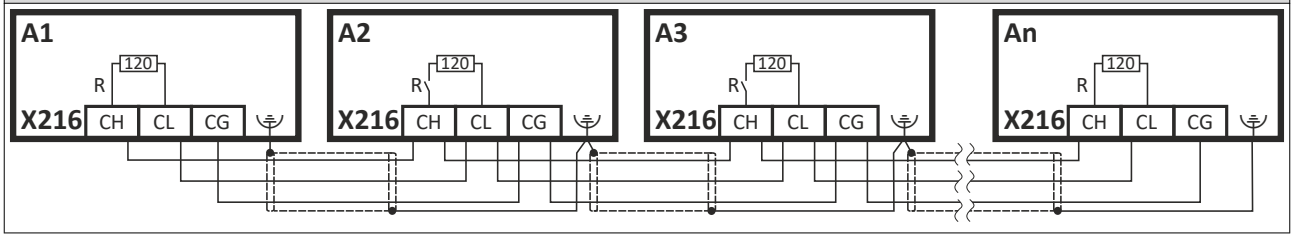
CANopen

The network must be terminated with a 120 Ω resistor at the first and last physical node.

Set the "R" DIP switch to ON at these network nodes.

Typical topologies

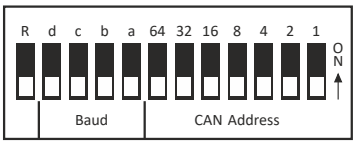
Line



Connection description			CANopen
Connection			**X216**
Connection type			Pluggable
Max. Cable cross-section		mm²	2.5
Max. Cable cross-section		AWG	12
Stripping length		mm	10
Stripping length		in	0.39
Required tool			Screwdriver 0.4 x 2.5

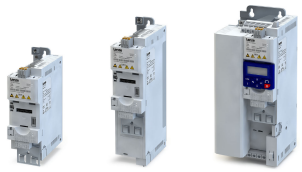
Basic network settings

Use the DIP switch to set the node address and baud rate and to activate the integrated bus terminating resistor.



Bus termination	Baud rate					CAN node address						
R	**d**	**c**	**b**	**a**		**64**	**32**	**16**	**8**	**4**	**2**	**1**
OFF	OFF	ON	OFF	ON	20 kbits/s	**OFF**	**OFF**	**OFF**	**OFF**	**OFF**	**OFF**	**OFF**
Inactive	OFF	OFF	ON	ON	50 kbits/s	Value from parameter						
ON	OFF	OFF	ON	OFF	125 kbits/s	Node address - example:						
Active	OFF	OFF	OFF	ON	250 kbits/s	OFF	OFF	ON	OFF	ON	ON	ON
	OFF	**OFF**	**OFF**	**OFF**	Value from parameter (500 kbits/s)	Node address = 16 + 4 + 2 + 1 = 23						
	OFF	ON	OFF	OFF	1 Mbit/s							
	All other combinations				Value from parameter (500 kbits/s)							

Bold print = default setting



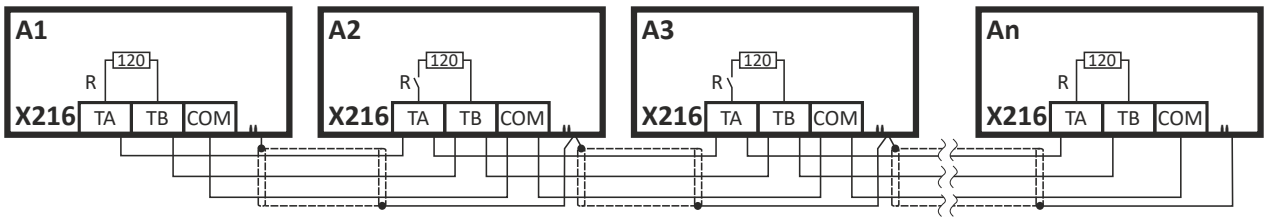
Modbus RTU

The network must be terminated with a 120 Ω resistor at the first and last physical node.

Set the "R" DIP switch to ON at these network nodes.

Typical topologies

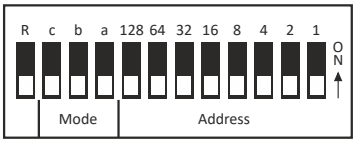
Line



Connection description			**Modbus RTU**
Connection			**X216**
Connection type			Pluggable
Max. Cable cross-section		mm²	2.5
Max. Cable cross-section		AWG	12
Stripping length		mm	10
Stripping length		in	0.39
Required tool			Screwdriver 0.4 x 2.5

Basic network settings

Use the DIP switch to set the node address and baud rate and to activate the integrated bus terminating resistor.

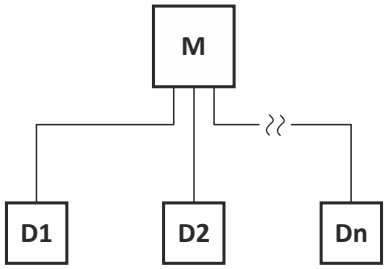


Bus termination		**Baud rate**	**Parity**	**Modbus node address**							
R	**c**	**b**	**a**	**128**	**64**	**32**	**16**	**8**	**4**	**2**	**1**
OFF	n. c.	**OFF**	**OFF**	**OFF**	**OFF**	**OFF**	**OFF**	**OFF**	**OFF**	**OFF**	**OFF**
Inactive		Automatic detection	Automatic detection	Value from parameter							
ON		ON	ON	Node address - example:							
Active		Value from parameter	Value from parameter	OFF	OFF	OFF	ON	OFF	ON	ON	ON
				Node address = 16 + 4 + 2 + 1 = 23							
				Node address > 247: Value from parameter							

Bold print = default setting

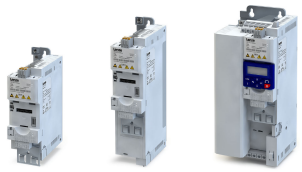
IO-Link

Typical topologies

Tree


M Master D Device

Connection description			IO-Link
Connection			**X316**
Connection type			Pluggable
Max. Cable cross-section		mm²	2.5
Max. Cable cross-section		AWG	12
Stripping length		mm	10
Stripping length		in	0.39
Required tool			Screwdriver 0.4 x 2.5



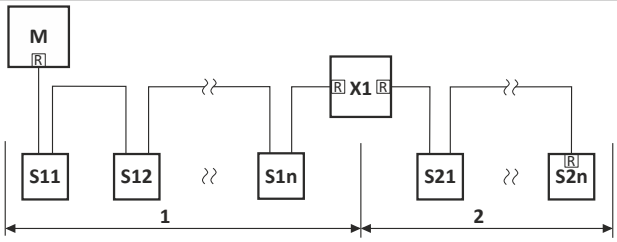
PROFIBUS

The network must be terminated with a resistor at the physically first and last node.

Activate the bus terminating resistor at these nodes in the bus connection plug.

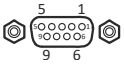
Typical topologies

Line with repeater



M	Master	X	Repeater
S	Slave	R	Activated bus terminating resistor

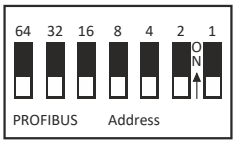
Sub D socket 9-pin - X226

View	Pin	Assignment	Description
	1	Shield	Additional shield connection
	2	n.c.	
	3	RxD/TxD-P	Data line-B (received data/transmitted data +)
	4	RTS	Request To Send (received data/transmitted data, no differential signal)
	5	M5V2	Reference potential (bus terminating resistor -)
	6	P5V2	5 V DC / 30 mA (bus terminating resistor +, OLM, OLP)
	7	n.c.	
	8	RxD/TxD-N	Data line-A (received data/transmitted data -)
	9	n.c.	

Basic network settings

Use the DIP switch to set the station address.

The baud rate is detected automatically.

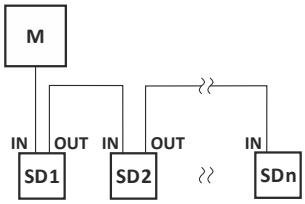


PROFIBUS station address						
64	**32**	**16**	**8**	**4**	**2**	**1**
OFF	**OFF**	**OFF**	**OFF**	**OFF**	**OFF**	**OFF**
Value from parameter						
Station address - example:						
OFF	OFF	ON	OFF	ON	ON	ON
Station address = 16 + 4 + 2 + 1 = 23 Do not set station address = 126 and station address = 127. These station addresses are invalid.						

Bold print = default setting

EtherCAT

Typical topologies

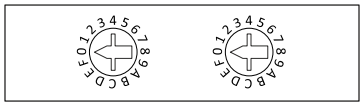
Line


M Master
SD Slave Device

Connection description			EtherCAT	
Connection			**X246**	**X247**
Connection type			RJ45	

Basic network settings

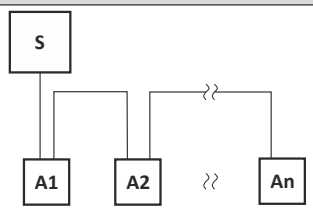
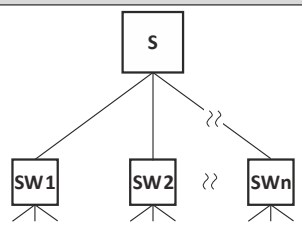
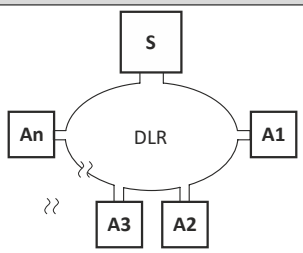
The rotary encoder switch allows you to set an EtherCAT identifier.



Setting	Identifier
0x00	Value from parameter
0x01 ... 0xFF	Switch position

EtherNet/IP

Typical topologies

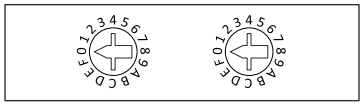
Line	Tree	Ring
		

S Scanner
A Adapter
SW Switch

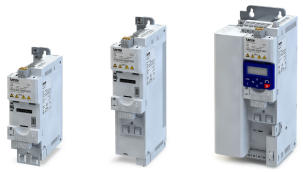
Connection description			EtherNet/IP	
Connection			**X266**	**X267**
Connection type			RJ45	

Basic network settings

The rotary encoder switch allows you to set the last byte of the IP address.

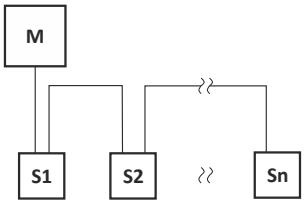
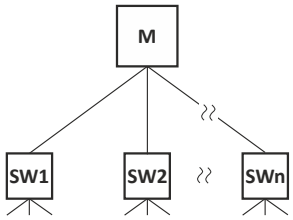


Setting	Value of last byte	Resulting IP address
0x00	Value from parameter	Value from parameter
0x01 ... 0xFE	Switch position	192.168.124.<switch position>
0xFF	Default setting	192.168.124.16



Modbus TCP

Typical topologies

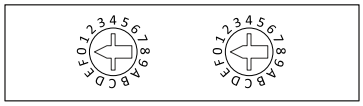
Line	Tree
	

M Master
S Slave
SW Switch

Connection description			Modbus TCP	
Connection			**X276**	**X277**
Connection type			RJ45	

Basic network settings

The rotary encoder switch allows you to set the last byte of the IP address.

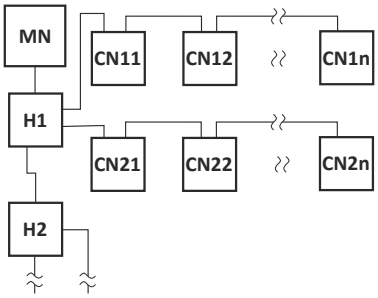


x16 x1

Setting	Value of last byte	Resulting IP address
0x00	Value from parameter	Value from parameter
0x01 ... 0xFE	Switch position	192.168.124.<switch position>
0xFF	Default setting	192.168.124.16

POWERLINK

Typical topologies

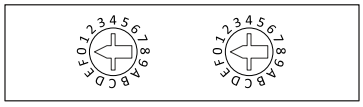
Line


MN	Managing Node	H	Hub
CN	Controlled Node		

Connection description			POWERLINK	
Connection			**X286**	**X287**
Connection type			RJ45	

Basic network settings

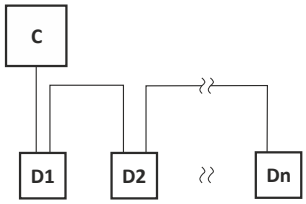
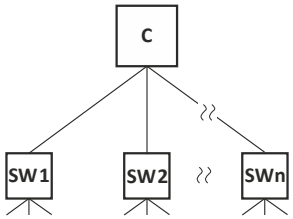
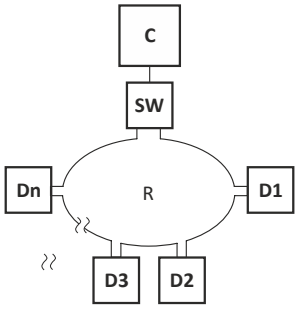
The rotary encoder switch allows you to set the node address (last byte of the IP address).



Setting	Node address	Resulting IP address
0x00	Value from parameter	192.168.100.<parameter value>
0x01 ... 0xEF	Switch position	192.168.100.<switch position>

PROFINET

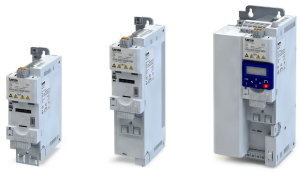
Typical topologies

Line	Tree	Ring
		

C	IO controller	SW	Switch SCALANCE (MRP capable)
D	IO device	R	Redundant domain

Connection description			PROFINET	
Connection			**X256**	**X257**
Connection type			RJ45	

The rotary encoder switch has no function.



Functional safety

⚠ DANGER!

Improper installation of the safety engineering system can cause an uncontrolled starting action of the drives.

Possible consequence: Death or severe injuries

- Safety engineering systems may only be installed and commissioned by qualified personnel.
- The complete wiring must be designed in accordance with EMC requirements.
- All control components (switch, relay, PLC, ...) must comply with the requirements of EN ISO 13849-1 and the EN ISO 13849-2.
- Switches, relays with at least IP54 degree of protection.
- Always mount devices with a degree of protection lower than IP54 in control cabinets with a minimum degree of protection of IP54.
- The wiring must be shielded.
- It is essential to use insulated wire end ferrules for wiring.
- All safety-relevant cables outside the control cabinet must be protected, e.g. by means of a cable duct.
- Ensure that no short circuits can occur according to the specifications of the EN ISO 13849-2.
- All further requirements and measures can be obtained from the EN ISO 13849-1 and the EN ISO 13849-2.
- If an external force acts upon the drive axes, additional brakes are required. Please observe that hanging loads are subject to the force of gravity!
- For safety-related braking functions, use safety-rated brakes only.
- The user has to ensure that the inverter will only be used in its intended application within the specified environmental conditions. This is the only way to comply with the declared safety-related characteristics.

⚠ DANGER!

Automatic restart if the request of the safety function is deactivated.

Possible consequences: Death or severe injuries

- You must provide external measures according to EN ISO 13849-1 which ensure that the drive only restarts after a confirmation.

NOTICE

Overvoltage

Destruction of the safety component

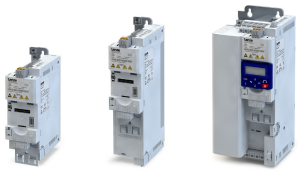
- Make sure that the maximum voltage (maximum rated) at the safe inputs does not exceed 30 V DC.

NOTICE

Excessively high humidity or condensation

Malfunction or destruction of the safety component

- Only commission the safety component when it has acclimated.



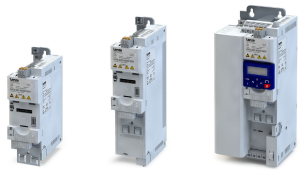
Basic Safety - STO

⚠ DANGER!

With the "Safe torque off" (STO) function, no "emergency switching off" in terms with EN 60204-1 can be executed without additional measures. There is no electrical isolation between the motor and inverter and no service switch or maintenance switch!

Possible consequence: Death or severe injuries

▸ "Emergency switching off" requires electrical isolation, e. g. by a central mains contactor.

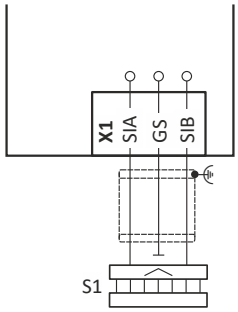


Connection diagram

The connection diagrams shown are only example circuits. The user is responsible for the correct safety-related design and selection of the components!

Active sensors

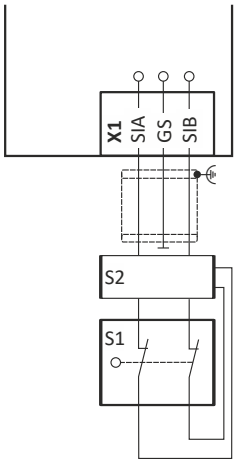
STO

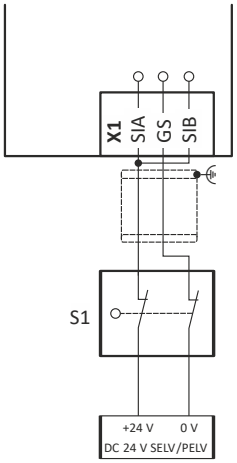


S1 Active sensor - example of lightgrid

Passive sensors

STO



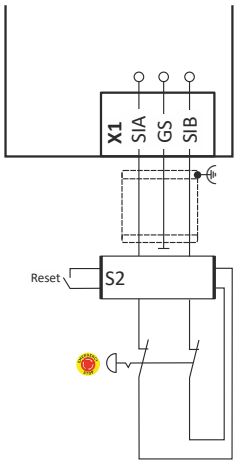
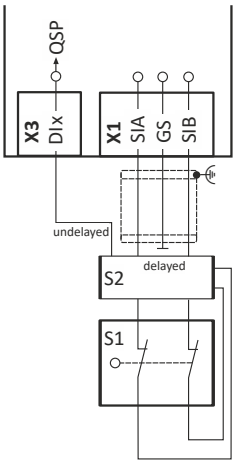
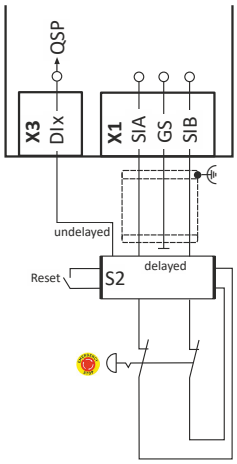


External power supply unit or 24 V output of X3

S1 Passive sensor
S2 Safety switching device

S1 Passive sensor

Passive sensors - further examples

Emergency stop (STO)	SS1c/SS1-t	Emergency stop (SS1c/SS1-t)
		

S2 Safety switching device

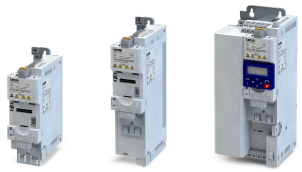
S1 Passive sensor
S2 Safety switching device with delayed contacts

S2 Safety switching device with delayed contacts

Connection data

X1	Specification	Unit	min.	typ.	max.
SIA, SIB	LOW signal	V	-3	0	+5
	HIGH signal	V	+15	+24	+30
	Switch-on time	ms		3	
	Clear time	ms		50	60
	Input current SIA	mA		10	14
	Input current SIB	mA		7	12
	Input peak current	mA		100	
	Test pulse duration	ms			1
	Test pulse interval	ms	10		
GS	Reference potential for SIA and SIB				

Connection description			Basic Safety - STO
Connection			**X1**
Connection type			Pluggable
Max. Cable cross-section		mm²	1.5
Max. Cable cross-section		AWG	16
Min. Cable cross-section		mm²	0.5
Min. Cable cross-section		AWG	22
Stripping length		mm	9
Stripping length		in	0.35
Required tool			Screwdriver 0.4 x 2.5



Technical data

Standards and operating conditions

Conformities and approvals

Conformities			
CE	2009/125/EC		Ecodesign Directive
	2011/65/EU		RoHS Directive
	2014/30/EU		EMC Directive (reference: CE-typical drive system)
	2014/35/EU		Low-Voltage Directive
EAC	TP TC 020/2011		Eurasian conformity: Electromagnetic compatibility of technical means
	TR TC 004/2011		Eurasian conformity: Safety of low voltage equipment
UKCA	S.I. 2008/1597		The Supply of Machinery (Safety) Regulations 2008
	S.I. 2012/3032		The Restriction of the Use of Certain Hazardous Substances in Electrical and Electronic Equipment Regulations 2012
	S.I. 2016/1091		The Electromagnetic Compatibility Regulations 2016
	S.I. 2021/745		The Ecodesign for Energy-Related Products and Energy Information Regulations 2021
Approvals			
UL	UL 61800-5-1		File No. E132659
			For USA and Canada (requirements of the CSA 22.2 No. 274)

Protection of persons and device protection

Degree of protection			Data applies to operationally ready mounted state and not in wire range of terminals
EN	EN IEC 60529	IP20	In the connection area of mains and motor partly IP10
NEMA	NEMA 250	Type 1	Protection against accidental contact only
Insulation resistance			
Overvoltage category	EN IEC 61800-5-1	II	>2000 m amsl
		III	0 … 2000 m amsl
Isolation of control circuits			
	EN IEC 61800-5-1	Safe mains isolation	Double/reinforced insulation
Leakage current			
AC	EN IEC 61800-5-1	> 3.5 mA	Observe regulations and safety instructions!
DC		> 10 mA	
Starting current			
		≤ 3 x rated mains current	
Protective measures			
Earth fault strength			Earth-fault protected depending on operating status
Motor stalling protection			
Short-circuit strength			
Overvoltage resistance			
Motor overtemperature			PTC or thermal contact, I^2xt monitoring

EMC data

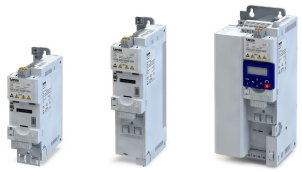
Operation on public supply systems			The machine or system manufacturer is responsible for compliance with the requirements for the machine/system!
< 1 kW	EN IEC 61000-3-2	With mains choke	For 1-phase devices, the use of an active filter is recommended to comply with the limit values!
> 1 kW, mains current ≤ 16 A		No additional measures	
Mains current > 16 A ... ≤ 75 A	EN IEC 61000-3-12	With mains choke or mains filter	For 1-phase devices, the use of an active filter is recommended to comply with the limit values!
Noise emission			
Category C1	EN IEC 61800-3		see rated data
Category C2			
Category C3			
Noise immunity			
	EN IEC 61800-3	Requirements fulfilled	

Motor connection

Requirements for the shielded motor cable			
Capacitance per unit length		< 150/300 pF/m	≥ 4 mm² / AWG 12
		< 75/150 pF/m	≤ 2.5 mm² / AWG 14
Electric strength		Uo/U = 0.6/1.0 kV	U = r.m.s. value from external conductor to external conductor
			Uo = r.m.s. value external conductor to PE
	UL	U ≥ 600 V	U = r.m.s. value from external conductor to external conductor

Environmental conditions

Energy efficiency			
High Efficiency	EN IEC 61800-9-2	Class IE2	
Climate			
Storage	EN 60721-3-1:1997	1K3 (-25 ... +60 °C)	
Transport	EN 60721-3-2:1997	2K3 (-25 ... +70 °C)	
Operation	EN 60721-3-3:1995 + A2:1997	3K3 (-10 ... +60 °C)	Operation at a switching frequency of 2 or 4 kHz: Above +45°C: reduce rated output current by 2.5 %/°C
			Operation at a switching frequency of 8 or 16 kHz: Above +40°C: reduce rated output current by 2.5 %/°C
			relative air humidity <95%, condensation not permissible
		3C3	For chemically active substances
		3S2	For mechanically active substances
Site altitude			
0 ... 1000 m amsl			Without current derating
1000 ... 4000 m amsl			Reduce rated output current by 5 %/1000 m
Pollution			
	EN IEC 61800-5-1	Degree of pollution 2	
	UL 61800-5-1		
Vibration resistance			
Transport	EN 60721-3-2:1997	2M2 (sine, shock)	In original packaging up to 45 kW
Operation	DNV-CG-0339		up to 11 kW
		Amplitude 1 mm	5 ... 13.2 Hz up to 11 kW
		Acceleration resistant up to 0.7 g	13.2 ... 100 Hz up to 11 kW
	EN IEC 61800-5-1	Amplitude 0.075 mm	10 ... 57 Hz
		Acceleration resistant up to 1 g	57 ... 150 Hz



Electrical supply conditions

Power systems			
IT			Apply the measures described for IT systems!
TN			Voltage against earth: max. 300 V
TT			

The connection to different supply forms enables a worldwide application of the inverters.

The following is supported:

- 1-phase mains connection 120 V 📖 83
- 1-phase mains connection 230/240 V 📖 87
- 3-phase mains connection 230/240 V 📖 98
- 3-phase mains connection 230/240 V "Light Duty" 📖 105
- 3-phase mains connection 400 V 📖 108
- 3-phase mains connection 400 V "Light Duty" 📖 126
- 3-phase mains connection 480 V 📖 138
- 3-phase mains connection 480 V "Light Duty" 📖 155

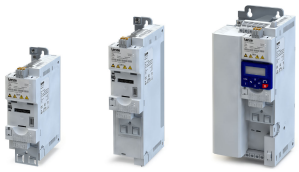
Certification of the integrated safety

The certification of the integrated safety is based on these test fundamentals:

- EN ISO 13849-1: Safety of machinery − Safety-related parts of control systems − Part 1
- EN 60204-1: Safety of machinery − Electrical equipment of machines − Part 1
- EN 61508, Part 1-7: Functional safety of electrical/electronic/programmable electronic safety-related systems
- EN 61800-5-1: Adjustable speed electrical power drive systems − Part 5-1: Safety requirements − Electrical, thermal and energy requirements
- EN 61800-5-2: Adjustable speed electrical power drive systems − Part 5-2: Safety requirements − Functional safety
- EN 62061: Safety of machinery − Functional safety of safety-related electrical/electronic/programmable electronic systems

Declarations of Conformity and certificates can be found on the Internet.

www.Lenze.com



1-phase mains connection 120 V

The inverters i550-Cxxx/120-1 do not have an integrated RFI filter in the AC mains supply.

In order to meet the EMC requirements according to EN IEC 61800-3, an external EMC filter according to IEC EN 60939 must be used.

The user must verify that the conformity with EN IEC 61800-3 is fulfilled.

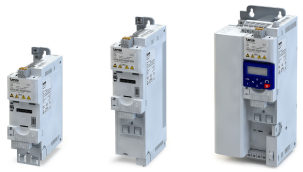
Rated data

The output currents apply to these operating conditions:

- At a switching frequency of 2 kHz or 4 kHz: Max. ambient temperature 45°C.
- At a switching frequency of 8 kHz or 16 kHz: Max. ambient temperature 40 °C.

Technical data

1-phase mains connection 120 V
Rated data



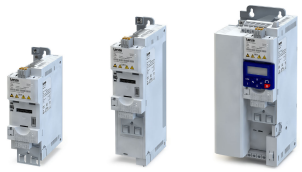
Inverter			i550-C0.25/120-1	i550-C0.37/120-1	i550-C0.75/120-1	i550-C1.1/120-1
Rated power	**P_{rated}**	**kW**	**0.25**	**0.37**	**0.75**	**1.1**
Rated power	**P_{rated}**	**hp**	**0.33**	**0.5**	**1**	**1.5**
Mains voltage range			1/PE AC 90 V ... 132 V, 45 Hz ... 65 Hz			
Output voltage			3 AC 0 - 230/240 V			
Rated mains current						
without mains choke		A	6.8	9.6	16.8	22.9
with mains choke		A	6	8.5	14.7	17.1
Apparent output power		kVA	0.6	0.9	1.6	2.2
Rated output current						
2 kHz		A	1.7	2.4	4.2	6
4 kHz		A	1.7	2.4	4.2	6
8 kHz		A	1.7	2.4	4.2	6
16 kHz		A	1.1	1.6	2.8	4
Power loss						
2 kHz		W	15	19	29	39
4 kHz		W	16	21	29	40
8 kHz		W	18	23	35	47
16 kHz		W	20	24	36	45
Overcurrent cycle 180 s						
Max. output current (≤ 8 kHz)		A	2.6	3.6	6.3	9
Overload time	T_1	s	60	60	60	60
Recovery time	T_2	s	120	120	120	120
Max. output current during the recovery time		A	1.3	1.8	3.2	4.5
Overcurrent cycle 15 s						
Max. output current (≤ 8 kHz)		A	3.4	4.8	8.4	12
Overload time	T_1	s	3	3	3	3
Recovery time	T_2	s	12	12	12	12
Max. output current during the recovery time		A	1.3	1.8	3.2	4.5
Cyclic mains switching			3 times per minute			
Brake chopper						
Max. output current		A	2.2		8.3	
Min. Brake resistor		Ω	180		47	
Max. shielded motor cable length						
without EMC category		m	50			
Category C1 (≤ 8 kHz)		m	-			
Category C2 (≤ 8 kHz)		m	-			
Category C3 (≤ 8 kHz)		m	-			
Max. Unshielded motor cable length						
without EMC category		m	100			

Fusing data (EN 60204-1)

A residual current device (RCD) is optional.

Fusing data for UL/NEC compliant installations: ▸ Fusing data 55

Inverter	Fuse			Circuit breaker			RCD	
	Max. SCCR	Characteristic	Max. rated current	Max. SCCR	Characteristic	Max. rated current		Type
	kA		A	kA		A	mA	
i550-C0.25/120-1	5	gG/gL, gRL	16	5	B, C	16	≥ 30	Typ B
i550-C0.37/120-1	5	gG/gL, gRL	16	5	B, C	16	≥ 30	Typ B
i550-C0.75/120-1	5	gG/gL, gRL	32	5	B, C	32	≥ 30	Typ B
i550-C1.1/120-1	5	gG/gL, gRL	32	5	B, C	32	≥ 30	Typ B



Connection data

Rated power	P_{rated}	kW	0.25 ... 0.37	0.75 ... 1.1
Connection description			**Mains connection**	
Connection			**X100**	
Connection type			Pluggable	
Max. Cable cross-section		mm²	2.5	6
Max. Cable cross-section		AWG	12	10
Stripping length		mm	8	8
Stripping length		in	0.3	0.3
Tightening torque		Nm	0.5	0.7
Tightening torque		lb-in	4.4	6.2
Required tool			Screwdriver 0.5 x 3.0	Screwdriver 0.6 x 3.5

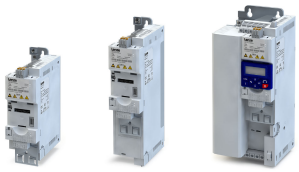
Rated power	P_{rated}	kW	0.25 ... 1.1
Connection description			**PE connection**
Terminal type			**Schraube**
Max. Cable cross-section		mm²	6
Max. Cable cross-section		AWG	10
Stripping length		mm	10
Stripping length		in	0.4
Tightening torque		Nm	2
Tightening torque		lb-in	18
Required tool			Torx key 20

Rated power	P_{rated}	kW	0.25 ... 1.1
Connection description			**Motor connection**
Connection			**X105**
Connection type			Pluggable
Max. Cable cross-section		mm²	2.5
Max. Cable cross-section		AWG	12
Stripping length		mm	8
Stripping length		in	0.3
Tightening torque		Nm	0.5
Tightening torque		lb-in	4.4
Required tool			Screwdriver 0.5 x 3.0

The connection data for the terminal X1 can be found under: ▸ Connection data 📖 79

Brake resistors

Inverter	Brake resistor					
	Order code	Rated resistance	Rated power	Thermal capacity	Dimensions (H x W x D)	Weight
		Ω	W	kWs	mm	kg
i550-C0.25/120-1	ERBM180R050W	180	50	7.5	175 x 20.6 x 40	0.28
i550-C0.25/120-1	ERBP180R200W	180	200	30	240 x 42 x 122	1.0
i550-C0.37/120-1	ERBM180R050W	180	50	7.5	175 x 20.6 x 40	0.28
i550-C0.37/120-1	ERBP180R200W	180	200	30	240 x 42 x 122	1.0
i550-C0.75/120-1	ERBM047R135W	47	135	6.3	216 x 80 x 28	0.67
i550-C0.75/120-1	ERBP047R200W	47	200	30	240 x 42 x 122	1.0
i550-C1.1/120-1	ERBM047R135W	47	135	6.3	216 x 80 x 28	0.67
i550-C1.1/120-1	ERBS047R400W	47	400	60	400 x 114 x 105	2.3



Mains chokes

Inverter	Netzdrossel					
	Order code	No. of phases	Rated current	Inductance	Dimensions (H x W x D)	Weight
			A	mH	mm	kg
i550-C0.25/120-1	ELN1-0500H009	1	9	5	82 x 66 x 75	1.1
i550-C0.37/120-1						
i550-C0.75/120-1	ELN1-0250H018		18	2.5	90 x 96 x 96	2.1
i550-C1.1/120-1						

1-phase mains connection 230/240 V

When selecting the inverters, please note:

The inverters i550-Cxxx/230-1 have an integrated RFI filter in the AC mains supply.

The inverters i550-Cxxx/230-2 **do not have** an integrated RFI filter in the AC mains supply.

In order to meet the EMC requirements according to EN IEC 61800-3, an external EMC filter according to IEC EN 60939 must be used.

The user must verify that the conformity with EN IEC 61800-3 is fulfilled.

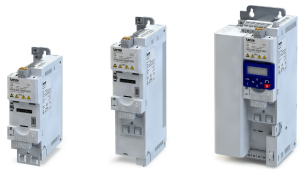
Rated data

The output currents apply to these operating conditions:

- At a switching frequency of 2 kHz or 4 kHz: Max. ambient temperature 45°C.
- At a switching frequency of 8 kHz or 16 kHz: Max. ambient temperature 40 °C.

Technical data

1-phase mains connection 230/240 V
Rated data

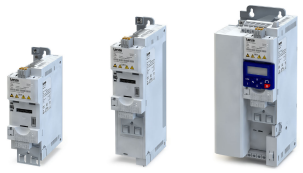


Inverter			**i550-C0.25/230-1**	**i550-C0.25/230-2**	**i550-C0.37/230-1**	**i550-C0.37/230-2**
Rated power	**P_{rated}**	**kW**	**0.25**		**0.37**	
Rated power	**P_{rated}**	**hp**	**0.33**		**0.5**	
Mains voltage range			1/PE AC 170 V ... 264 V, 45 Hz ... 65 Hz			
Output voltage			3 AC 0 - 230/240 V			
Rated mains current						
without mains choke		A	4		5.7	
with mains choke		A	3.6		4.8	
Apparent output power		kVA	0.6		0.9	
Rated output current						
2 kHz		A	-			
4 kHz		A	1.7		2.4	
8 kHz		A	1.7		2.4	
16 kHz		A	1.1		1.6	
Power loss						
2 kHz		W	-			
4 kHz		W	15		18	
8 kHz		W	15		20	
16 kHz		W	19		24	
Overcurrent cycle 180 s						
Max. output current (≤ 8 kHz)		A	2.6	2.6	3.6	3.6
Overload time	T_1	s	60	60	60	60
Recovery time	T_2	s	120	120	120	120
Max. output current during the recovery time		A	1.3	1.3	1.8	1.8
Overcurrent cycle 15 s						
Max. output current (≤ 8 kHz)		A	3.4	3.4	4.8	4.8
Overload time	T_1	s	3	3	3	3
Recovery time	T_2	s	12	12	12	12
Max. output current during the recovery time		A	1.3	1.3	1.8	1.8
Cyclic mains switching			3 times per minute			
Brake chopper						
Max. output current		A	2.2			
Min. Brake resistor		Ω	180			
Max. shielded motor cable length						
without EMC category		m	50			
Category C1 (≤ 8 kHz)		m	3	-	3	-
Category C2 (≤ 8 kHz)		m	15	-	15	-
Category C3 (≤ 8 kHz)		m	15	-	15	-
Max. Unshielded motor cable length						
without EMC category		m	80	100	80	100

Inverter			i550-C0.55/230-1	i550-C0.55/230-2	i550-C0.75/230-1	i550-C0.75/230-2
Rated power	P_{rated}	**kW**	**0.55**		**0.75**	
Rated power	P_{rated}	**hp**	**0.75**		**1**	
Mains voltage range			1/PE AC 170 V ... 264 V, 45 Hz ... 65 Hz			
Output voltage			3 AC 0 - 230/240 V			
Rated mains current						
without mains choke		A	7.6		10	
with mains choke		A	7.1		8.8	
Apparent output power		kVA	1.2		1.6	
Rated output current						
2 kHz		A	3.2		4.2	
4 kHz		A	3.2		4.2	
8 kHz		A	3.2		4.2	
16 kHz		A	2.1		2.8	
Power loss						
2 kHz		W	22		27	
4 kHz		W	23		29	
8 kHz		W	25		33	
16 kHz		W	30		38	
Overcurrent cycle 180 s						
Max. output current (≤ 8 kHz)		A	4.8	4.8	6.3	6.3
Overload time	T_1	s	60	60	60	60
Recovery time	T_2	s	120	120	120	120
Max. output current during the recovery time		A	2.4	2.4	3.2	3.2
Overcurrent cycle 15 s						
Max. output current (≤ 8 kHz)		A	6.4	6.4	8.4	8.4
Overload time	T_1	s	3	3	3	3
Recovery time	T_2	s	12	12	12	12
Max. output current during the recovery time		A	2.4	2.4	3.2	3.2
Cyclic mains switching			3 times per minute			
Brake chopper						
Max. output current		A	3.9			
Min. Brake resistor		Ω	100			
Max. shielded motor cable length						
without EMC category		m	50			
Category C1 (≤ 8 kHz)		m	3	-	3	-
Category C2 (≤ 8 kHz)		m	20	-	20	-
Category C3 (≤ 8 kHz)		m	50	-	50	-
Max. Unshielded motor cable length						
without EMC category		m	100			

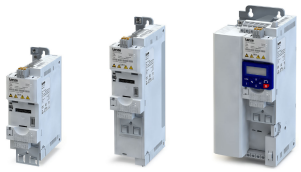
Technical data

1-phase mains connection 230/240 V
Rated data



Inverter			**i550-C1.1/230-1**	**i550-C1.1/230-2**	**i550-C1.5/230-1**	**i550-C1.5/230-2**
Rated power	**P_{rated}**	**kW**	**1.1**		**1.5**	
Rated power	**P_{rated}**	**hp**	**1.5**		**2**	
Mains voltage range			1/PE AC 170 V ... 264 V, 45 Hz ... 65 Hz			
Output voltage			3 AC 0 - 230/240 V			
Rated mains current						
without mains choke		A	14.3		16.7	
with mains choke		A	11.9		13.9	
Apparent output power		kVA	2.2		2.6	
Rated output current						
2 kHz		A	6		7	
4 kHz		A	6		7	
8 kHz		A	6		7	
16 kHz		A	4		4.7	
Power loss						
2 kHz		W	36		41	
4 kHz		W	37		43	
8 kHz		W	42		50	
16 kHz		W	51		59	
Overcurrent cycle 180 s						
Max. output current (≤ 8 kHz)		A	9	9	10.5	10.5
Overload time	T_1	s	60	60	60	60
Recovery time	T_2	s	120	120	120	120
Max. output current during the recovery time		A	4.5	4.5	5.3	5.3
Overcurrent cycle 15 s						
Max. output current (≤ 8 kHz)		A	12	12	14	14
Overload time	T_1	s	3	3	3	3
Recovery time	T_2	s	12	12	12	12
Max. output current during the recovery time		A	4.5	4.5	5.3	5.3
Cyclic mains switching			3 times per minute			
Brake chopper						
Max. output current		A	12			
Min. Brake resistor		Ω	33			
Max. shielded motor cable length						
without EMC category		m	50			
Category C1 (≤ 8 kHz)		m	3	-	3	-
Category C2 (≤ 8 kHz)		m	20	-	20	-
Category C3 (≤ 8 kHz)		m	35	-	35	-
Max. Unshielded motor cable length						
without EMC category		m	100			

Inverter			**i550-C2.2/230-1**	**i550-C2.2/230-2**
Rated power	**P_{rated}**	**kW**	**2.2**	
Rated power	**P_{rated}**	**hp**	**3**	
Mains voltage range			1/PE AC 170 V ... 264 V, 45 Hz ... 65 Hz	
Output voltage			3 AC 0 - 230/240 V	
Rated mains current				
without mains choke		A	22.5	
with mains choke		A	16.9	
Apparent output power		kVA	3.6	
Rated output current				
2 kHz		A	9.6	
4 kHz		A	9.6	
8 kHz		A	9.6	
16 kHz		A	6.4	
Power loss				
2 kHz		W	54	
4 kHz		W	60	
8 kHz		W	70	
16 kHz		W	78	
Overcurrent cycle 180 s				
Max. output current (≤ 8 kHz)		A	14.4	14.4
Overload time	T_1	s	60	60
Recovery time	T_2	s	120	120
Max. output current during the recovery time		A	7.2	7.2
Overcurrent cycle 15 s				
Max. output current (≤ 8 kHz)		A	19.2	19.2
Overload time	T_1	s	3	3
Recovery time	T_2	s	12	12
Max. output current during the recovery time		A	7.2	7.2
Cyclic mains switching			3 times per minute	
Brake chopper				
Max. output current		A	12	
Min. Brake resistor		Ω	33	
Max. shielded motor cable length				
without EMC category		m	50	
Category C1 (≤ 8 kHz)		m	3	-
Category C2 (≤ 8 kHz)		m	20	-
Category C3 (≤ 8 kHz)		m	35	-
Max. Unshielded motor cable length				
without EMC category		m	100	



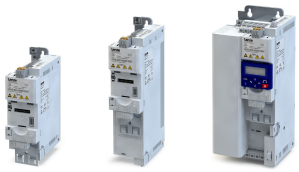
Fusing data (EN 60204-1)

A residual current device (RCD) is optional.

Fusing data for UL/NEC compliant installations: ▸ Fusing data 55

The RCD type "F" is only permitted in 1-phase operation (L/N)!

Inverter	Fuse			Circuit breaker			RCD	
	Max. SCCR	Characteristic	Max. rated current	Max. SCCR	Characteristic	Max. rated current		Type
	kA		A	kA		A	mA	
i550-C0.25/230-1	65	gG/gL, gRL	16	65	B, C	16	≥ 30	Typ B
i550-C0.25/230-1	65	gG/gL, gRL	16	65	B, C	16	≥ 30	Typ F
i550-C0.25/230-2	65	gG/gL, gRL	16	65	B, C	16	≥ 30	Typ B
i550-C0.25/230-2	65	gG/gL, gRL	16	65	B, C	16	≥ 30	Typ F
i550-C0.37/230-1	65	gG/gL, gRL	16	65	B, C	16	≥ 30	Typ B
i550-C0.37/230-1	65	gG/gL, gRL	16	65	B, C	16	≥ 30	Typ F
i550-C0.37/230-2	65	gG/gL, gRL	16	65	B, C	16	≥ 30	Typ B
i550-C0.37/230-2	65	gG/gL, gRL	16	65	B, C	16	≥ 30	Typ F
i550-C0.55/230-1	65	gG/gL, gRL	16	65	B, C	16	≥ 30	Typ B
i550-C0.55/230-1	65	gG/gL, gRL	16	65	B, C	16	≥ 30	Typ F
i550-C0.55/230-2	65	gG/gL, gRL	16	65	B, C	16	≥ 30	Typ B
i550-C0.55/230-2	65	gG/gL, gRL	16	65	B, C	16	≥ 30	Typ F
i550-C0.75/230-1	65	gG/gL, gRL	16	65	B, C	16	≥ 30	Typ B
i550-C0.75/230-1	65	gG/gL, gRL	16	65	B, C	16	≥ 30	Typ F
i550-C0.75/230-2	65	gG/gL, gRL	16	65	B, C	16	≥ 30	Typ B
i550-C0.75/230-2	65	gG/gL, gRL	16	65	B, C	16	≥ 30	Typ F
i550-C1.1/230-1	65	gG/gL, gRL	32	65	B, C	32	≥ 30	Typ B
i550-C1.1/230-1	65	gG/gL, gRL	32	65	B, C	32	≥ 30	Typ F
i550-C1.1/230-2	65	gG/gL, gRL	32	65	B, C	32	≥ 30	Typ B
i550-C1.1/230-2	65	gG/gL, gRL	32	65	B, C	32	≥ 30	Typ F
i550-C1.5/230-1	65	gG/gL, gRL	32	65	B, C	32	≥ 30	Typ B
i550-C1.5/230-1	65	gG/gL, gRL	32	65	B, C	32	≥ 30	Typ F
i550-C1.5/230-2	65	gG/gL, gRL	32	65	B, C	32	≥ 30	Typ B
i550-C1.5/230-2	65	gG/gL, gRL	32	65	B, C	32	≥ 30	Typ F
i550-C2.2/230-1	65	gG/gL, gRL	32	65	B, C	32	≥ 30	Typ B
i550-C2.2/230-1	65	gG/gL, gRL	32	65	B, C	32	≥ 30	Typ F
i550-C2.2/230-2	65	gG/gL, gRL	32	65	B, C	32	≥ 30	Typ B
i550-C2.2/230-2	65	gG/gL, gRL	32	65	B, C	32	≥ 30	Typ F



Connection data

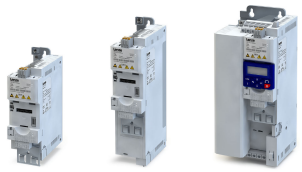
Rated power	P_{rated}	kW	0.25 ... 0.75	1.1 ... 2.2
Connection description			**Mains connection**	
Connection			**X100**	
Connection type			Pluggable	
Max. Cable cross-section		mm²	2.5	6
Max. Cable cross-section		AWG	12	10
Stripping length		mm	8	8
Stripping length		in	0.3	0.3
Tightening torque		Nm	0.5	0.7
Tightening torque		lb-in	4.4	6.2
Required tool			Screwdriver 0.5 x 3.0	Screwdriver 0.6 x 3.5

Rated power	P_{rated}	kW	0.25 ... 2.2
Connection description			**PE connection**
Terminal type			**Schraube**
Max. Cable cross-section		mm²	6
Max. Cable cross-section		AWG	10
Stripping length		mm	10
Stripping length		in	0.4
Tightening torque		Nm	2
Tightening torque		lb-in	18
Required tool			Torx key 20

Rated power	P_{rated}	kW	0.25 ... 2.2
Connection description			**Motor connection**
Connection			**X105**
Connection type			Pluggable
Max. Cable cross-section		mm²	2.5
Max. Cable cross-section		AWG	12
Stripping length		mm	8
Stripping length		in	0.3
Tightening torque		Nm	0.5
Tightening torque		lb-in	4.4
Required tool			Screwdriver 0.5 x 3.0

The connection data for the terminal X1 can be found under: ▸ Connection data 🕮 79

Technical data
1-phase mains connection 230/240 V
Brake resistors



Brake resistors

Inverter	Brake resistor					
	Order code	Rated resistance	Rated power	Thermal capacity	Dimensions (H x W x D)	Weight
		Ω	W	kWs	mm	kg
i550-C0.25/230-1	ERBM180R050W	180	50	7.5	175 x 20.6 x 40	0.28
i550-C0.25/230-1	ERBP180R200W	180	200	30	240 x 42 x 122	1.0
i550-C0.37/230-1	ERBM180R050W	180	50	7.5	175 x 20.6 x 40	0.28
i550-C0.37/230-1	ERBP180R200W	180	200	30	240 x 42 x 122	1.0
i550-C0.55/230-1	ERBM100R086W	100	86	3.4	110 x 80 x 28	0.49
i550-C0.55/230-1	ERBM100R150W	100	150	22.5	238 x 80 x 59	0.54
i550-C0.75/230-1	ERBM100R086W	100	86	3.4	110 x 80 x 28	0.49
i550-C0.75/230-1	ERBM100R150W	100	150	22.5	238 x 80 x 59	0.54
i550-C1.1/230-1	ERBP033R200W	33	200	30	240 x 42 x 122	1.0
i550-C1.1/230-1	ERBP033R300W	33	300	45	320 x 42 x 122	1.4
i550-C1.5/230-1	ERBP033R200W	33	200	30	240 x 42 x 122	1.0
i550-C1.5/230-1	ERBP033R300W	33	300	45	320 x 42 x 122	1.4
i550-C2.2/230-1	ERBP033R200W	33	200	30	240 x 42 x 122	1.0
i550-C2.2/230-1	ERBP033R300W	33	300	45	320 x 42 x 122	1.4
i550-C0.25/230-2	ERBM180R050W	180	50	7.5	175 x 20.6 x 40	0.28
i550-C0.25/230-2	ERBP180R200W	180	200	30	240 x 42 x 122	1.0
i550-C0.37/230-2	ERBM180R050W	180	50	7.5	175 x 20.6 x 40	0.28
i550-C0.37/230-2	ERBP180R200W	180	200	30	240 x 42 x 122	1.0
i550-C0.55/230-2	ERBM100R086W	100	86	3.4	110 x 80 x 28	0.49
i550-C0.55/230-2	ERBM100R150W	100	150	22.5	238 x 80 x 59	0.54
i550-C0.75/230-2	ERBM100R086W	100	86	3.4	110 x 80 x 28	0.49
i550-C0.75/230-2	ERBM100R150W	100	150	22.5	238 x 80 x 59	0.54
i550-C1.1/230-2	ERBP033R200W	33	200	30	240 x 42 x 122	1.0
i550-C1.1/230-2	ERBP033R300W	33	300	45	320 x 42 x 122	1.4
i550-C1.5/230-2	ERBP033R200W	33	200	30	240 x 42 x 122	1.0
i550-C1.5/230-2	ERBP033R300W	33	300	45	320 x 42 x 122	1.4
i550-C2.2/230-2	ERBP033R200W	33	200	30	240 x 42 x 122	1.0
i550-C2.2/230-2	ERBP033R300W	33	300	45	320 x 42 x 122	1.4

Mains chokes

Inverter	Netzdrossel					
	Order code	No. of phases	Rated current	Inductance	Dimensions (H x W x D)	Weight
			A	mH	mm	kg
i550-C0.25/230-1	ELN1-0900H005	1	5	9	82 x 66 x 75	1.1
i550-C0.25/230-2						
i550-C0.37/230-1						
i550-C0.37/230-2						
i550-C0.55/230-1	ELN1-0500H009		9	5		
i550-C0.55/230-2						
i550-C0.75/230-1						
i550-C0.75/230-2						
i550-C1.1/230-1	ELN1-0250H018		18	2.5	90 x 96 x 96	2.1
i550-C1.1/230-2						
i550-C1.5/230-1						
i550-C1.5/230-2						
i550-C2.2/230-1						
i550-C2.2/230-2						

RFI filters / Mains filters

Basic information on RFI filters, mains filters and EMC: from 📖 223

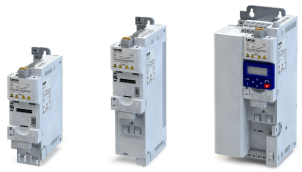
EMC filters can be used both in the side structure and in the substructure.

Maximum motor cable lengths with residual current device (RCD)

Mains connection			1-phase, 230 V		
Inverter			i550-C0.25/230-1 i550-C0.37/230-1	i550-C0.55/230-1 i550-C0.75/230-1	i550-C1.1/230-1 i550-C1.5/230-1 i550-C2.2/230-1
Without RFI filter					
without EMC category Thermal limitation	Max. motor cable length shielded	m	50	50	50
	Max. motor cable length unshielded	m	80	100	100
With integrated RFI filter					
Category C1	Max. motor cable length shielded	m	3	3	3
Category C2		m	15	20	20
	Earth-leakage circuit breaker (optional)	mA	30	30	30
RFI filter Low Leakage					
Category C1	Max. motor cable length shielded	m	5	5	5
	Earth-leakage circuit breaker (optional)	mA	10	10	10
RFI filter Short Distance					
Category C1	Max. motor cable length shielded	m	25	25	25
Category C2		m	50	50	50
	Earth-leakage circuit breaker (optional)	mA	30	30	30
RFI filter Long Distance					
Category C1	Max. motor cable length shielded	m	50	50	50
Category C2		m	50	50	50
	Earth-leakage circuit breaker (optional)	mA	300	300	300

Technical data

1-phase mains connection 230/240 V
RFI filters / Mains filters

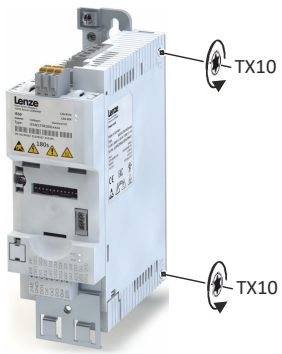


Low Leakage

Inverter	Filter				Max. shielded motor cable length					
	Order code	Rated current	Dimensions (H x W x D)	Weight	C1		C2		C3	
		A	mm	kg	m	kHz				
i550-C0.25/230-1	I0FAE137B100L0000S	6	226 x 60 x 50	0.85	5	4	-	-	-	-
i550-C0.25/230-1	I0FAE137B100L0000S	6	226 x 60 x 50	0.85	5	8	-	-	-	-
i550-C0.25/230-1	I0FAE137B100L0000S	6	226 x 60 x 50	0.85	5	16	-	-	-	-
i550-C0.37/230-1	I0FAE137B100L0000S	6	226 x 60 x 50	0.85	5	4	-	-	-	-
i550-C0.37/230-1	I0FAE137B100L0000S	6	226 x 60 x 50	0.85	5	8	-	-	-	-
i550-C0.37/230-1	I0FAE137B100L0000S	6	226 x 60 x 50	0.85	5	16	-	-	-	-
i550-C0.55/230-1	I0FAE175B100L0000S	10	276 x 60 x 50	1	5	2	-	-	-	-
i550-C0.55/230-1	I0FAE175B100L0000S	10	276 x 60 x 50	1	5	4	-	-	-	-
i550-C0.55/230-1	I0FAE175B100L0000S	10	276 x 60 x 50	1	5	8	-	-	-	-
i550-C0.55/230-1	I0FAE175B100L0000S	10	276 x 60 x 50	1	5	16	-	-	-	-
i550-C0.75/230-1	I0FAE175B100L0000S	10	276 x 60 x 50	1	5	2	-	-	-	-
i550-C0.75/230-1	I0FAE175B100L0000S	10	276 x 60 x 50	1	5	4	-	-	-	-
i550-C0.75/230-1	I0FAE175B100L0000S	10	276 x 60 x 50	1	5	8	-	-	-	-
i550-C0.75/230-1	I0FAE175B100L0000S	10	276 x 60 x 50	1	5	16	-	-	-	-
i550-C1.1/230-1	I0FAE222B100L0000S	22.5	346 x 60 x 50	1.35	5	2	-	-	-	-
i550-C1.1/230-1	I0FAE222B100L0000S	22.5	346 x 60 x 50	1.35	5	4	-	-	-	-
i550-C1.1/230-1	I0FAE222B100L0000S	22.5	346 x 60 x 50	1.35	5	8	-	-	-	-
i550-C1.1/230-1	I0FAE222B100L0000S	22.5	346 x 60 x 50	1.35	5	16	-	-	-	-
i550-C1.5/230-1	I0FAE222B100L0000S	22.5	346 x 60 x 50	1.35	5	2	-	-	-	-
i550-C1.5/230-1	I0FAE222B100L0000S	22.5	346 x 60 x 50	1.35	5	4	-	-	-	-
i550-C1.5/230-1	I0FAE222B100L0000S	22.5	346 x 60 x 50	1.35	5	8	-	-	-	-
i550-C1.5/230-1	I0FAE222B100L0000S	22.5	346 x 60 x 50	1.35	5	16	-	-	-	-
i550-C2.2/230-1	I0FAE222B100L0000S	22.5	346 x 60 x 50	1.35	5	2	-	-	-	-
i550-C2.2/230-1	I0FAE222B100L0000S	22.5	346 x 60 x 50	1.35	5	4	-	-	-	-
i550-C2.2/230-1	I0FAE222B100L0000S	22.5	346 x 60 x 50	1.35	5	8	-	-	-	-
i550-C2.2/230-1	I0FAE222B100L0000S	22.5	346 x 60 x 50	1.35	5	16	-	-	-	-

In order to meet the EMC requirements according to EN IEC 61800-3, the screws marked “IT” on the product must be removed when using the filters listed below.

Filters:	I0FAE137B100L0000S	I0FAE175B100L0000S I0FAE222B100L0000S
Inverters:	I55AE125x, I55AE137x	I55AE155x, I55AE175x, I55AE211x, I55AE215x, I55AE222x

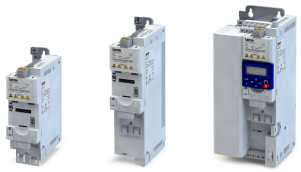


Short distance filter

Inverter	Filter				Max. shielded motor cable length					
	Order code	Rated current	Dimensions (H x W x D)	Weight	C1		C2		C3	
		A	mm	kg	m	kHz	m	kHz		
i550-C0.25/230-1	I0FAE175B100S0000S	10	276 x 60 x 50	0.77	25	4	50	4	-	-
i550-C0.25/230-1	I0FAE175B100S0000S	10	276 x 60 x 50	0.77	25	8	50	8	-	-
i550-C0.25/230-1	I0FAE175B100S0000S	10	276 x 60 x 50	0.77	25	16	50	16	-	-
i550-C0.37/230-1	I0FAE175B100S0000S	10	276 x 60 x 50	0.77	25	4	50	4	-	-
i550-C0.37/230-1	I0FAE175B100S0000S	10	276 x 60 x 50	0.77	25	8	50	8	-	-
i550-C0.37/230-1	I0FAE175B100S0000S	10	276 x 60 x 50	0.77	25	16	50	16	-	-
i550-C0.55/230-1	I0FAE175B100S0000S	10	276 x 60 x 50	0.77	25	2	50	2	-	-
i550-C0.55/230-1	I0FAE175B100S0000S	10	276 x 60 x 50	0.77	25	4	50	4	-	-
i550-C0.55/230-1	I0FAE175B100S0000S	10	276 x 60 x 50	0.77	25	8	50	8	-	-
i550-C0.55/230-1	I0FAE175B100S0000S	10	276 x 60 x 50	0.77	25	16	50	16	-	-
i550-C0.75/230-1	I0FAE175B100S0000S	10	276 x 60 x 50	0.77	25	2	50	2	-	-
i550-C0.75/230-1	I0FAE175B100S0000S	10	276 x 60 x 50	0.77	25	4	50	4	-	-
i550-C0.75/230-1	I0FAE175B100S0000S	10	276 x 60 x 50	0.77	25	8	50	8	-	-
i550-C0.75/230-1	I0FAE175B100S0000S	10	276 x 60 x 50	0.77	25	16	50	16	-	-
i550-C1.1/230-1	I0FAE222B100S0000S	22.5	346 x 60 x 50	1.02	25	2	50	2	-	-
i550-C1.1/230-1	I0FAE222B100S0000S	22.5	346 x 60 x 50	1.02	25	4	50	4	-	-
i550-C1.1/230-1	I0FAE222B100S0000S	22.5	346 x 60 x 50	1.02	25	8	50	8	-	-
i550-C1.1/230-1	I0FAE222B100S0000S	22.5	346 x 60 x 50	1.02	25	16	50	16	-	-
i550-C1.5/230-1	I0FAE222B100S0000S	22.5	346 x 60 x 50	1.02	25	2	50	2	-	-
i550-C1.5/230-1	I0FAE222B100S0000S	22.5	346 x 60 x 50	1.02	25	4	50	4	-	-
i550-C1.5/230-1	I0FAE222B100S0000S	22.5	346 x 60 x 50	1.02	25	8	50	8	-	-
i550-C1.5/230-1	I0FAE222B100S0000S	22.5	346 x 60 x 50	1.02	25	16	50	16	-	-
i550-C2.2/230-1	I0FAE222B100S0000S	22.5	346 x 60 x 50	1.02	25	2	50	2	-	-
i550-C2.2/230-1	I0FAE222B100S0000S	22.5	346 x 60 x 50	1.02	25	4	50	4	-	-
i550-C2.2/230-1	I0FAE222B100S0000S	22.5	346 x 60 x 50	1.02	25	8	50	8	-	-
i550-C2.2/230-1	I0FAE222B100S0000S	22.5	346 x 60 x 50	1.02	25	16	50	16	-	-

Long distance filter

Inverter	Filter				Max. shielded motor cable length					
	Order code	Rated current	Dimensions (H x W x D)	Weight	C1		C2		C3	
		A	mm	kg	m	kHz	m	kHz		
i550-C0.25/230-1	I0FAE175B100D0000S	10	276 x 60 x 50	0.82	50	4	50	4	-	-
i550-C0.25/230-1	I0FAE175B100D0000S	10	276 x 60 x 50	0.82	50	8	50	8	-	-
i550-C0.37/230-1	I0FAE175B100D0000S	10	276 x 60 x 50	0.82	50	4	50	4	-	-
i550-C0.37/230-1	I0FAE175B100D0000S	10	276 x 60 x 50	0.82	50	8	50	8	-	-
i550-C0.55/230-1	I0FAE175B100D0000S	10	276 x 60 x 50	0.82	50	4	50	4	-	-
i550-C0.55/230-1	I0FAE175B100D0000S	10	276 x 60 x 50	0.82	50	8	50	8	-	-
i550-C0.75/230-1	I0FAE175B100D0000S	10	276 x 60 x 50	0.82	50	4	50	4	-	-
i550-C0.75/230-1	I0FAE175B100D0000S	10	276 x 60 x 50	0.82	50	8	50	8	-	-
i550-C1.1/230-1	I0FAE222B100D0000S	22.5	346 x 60 x 50	1.09	50	4	50	4	-	-
i550-C1.1/230-1	I0FAE222B100D0000S	22.5	346 x 60 x 50	1.09	50	8	50	8	-	-
i550-C1.5/230-1	I0FAE222B100D0000S	22.5	346 x 60 x 50	1.09	50	4	50	4	-	-
i550-C1.5/230-1	I0FAE222B100D0000S	22.5	346 x 60 x 50	1.09	50	8	50	8	-	-
i550-C2.2/230-1	I0FAE222B100D0000S	22.5	346 x 60 x 50	1.09	50	4	50	4	-	-
i550-C2.2/230-1	I0FAE222B100D0000S	22.5	346 x 60 x 50	1.09	50	8	50	8	-	-



3-phase mains connection 230/240 V

The inverters i550-Cxxx/230-3 and i550-Cxxx/230-2 do not have an integrated RFI filter in the AC mains supply.

In order to meet the EMC requirements according to EN IEC 61800-3, an external EMC filter according to IEC EN 60939 must be used.

The user must verify that the conformity with EN IEC 61800-3 is fulfilled.

Rated data

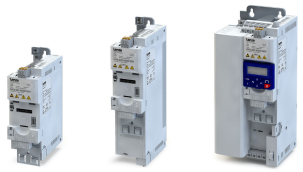
The output currents apply to these operating conditions:

- At a switching frequency of 2 kHz or 4 kHz: Max. ambient temperature 45°C.
- At a switching frequency of 8 kHz or 16 kHz: Max. ambient temperature 40 °C.

Inverter			i550-C0.25/230-2	i550-C0.37/230-2	i550-C0.55/230-2	i550-C0.75/230-2
Rated power	**P_{rated}**	**kW**	**0.25**	**0.37**	**0.55**	**0.75**
Rated power	**P_{rated}**	**hp**	**0.33**	**0.5**	**0.75**	**1**
Mains voltage range			3/PE AC 170 V ... 264 V, 45 Hz ... 65 Hz			
Output voltage			3 AC 0 - 230/240 V			
Rated mains current						
without mains choke		A	2.6	3.9	4.8	6.4
with mains choke		A	2	3	3.8	5.1
Apparent output power		kVA	0.6	0.9	1.2	1.6
Rated output current						
2 kHz		A	-		3.2	4.2
4 kHz		A	1.7	2.4	3.2	4.2
8 kHz		A	1.7	2.4	3.2	4.2
16 kHz		A	1.1	1.6	2.1	2.8
Power loss						
2 kHz		W	-		22	27
4 kHz		W	15	18	23	29
8 kHz		W	15	20	25	33
16 kHz		W	19	24	30	38
Overcurrent cycle 180 s						
Max. output current (≤ 8 kHz)		A	2.6	3.6	4.8	6.3
Overload time	T_1	s	60	60	60	60
Recovery time	T_2	s	120	120	120	120
Max. output current during the recovery time		A	1.3	1.8	2.4	3.2
Overcurrent cycle 15 s						
Max. output current (≤ 8 kHz)		A	3.4	4.8	6.4	8.4
Overload time	T_1	s	3	3	3	3
Recovery time	T_2	s	12	12	12	12
Max. output current during the recovery time		A	1.3	1.8	2.4	3.2
Cyclic mains switching			3 times per minute			
Brake chopper						
Max. output current		A	2.2		3.9	
Min. Brake resistor		Ω	180		100	
Max. shielded motor cable length						
without EMC category		m	50			
Category C1 (≤ 8 kHz)		m	-			
Category C2 (≤ 8 kHz)		m	-			
Category C3 (≤ 8 kHz)		m	-			
Max. Unshielded motor cable length						
without EMC category		m	100			

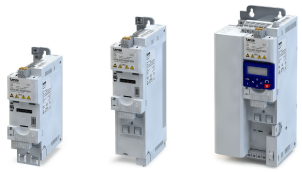
Technical data

3-phase mains connection 230/240 V
Rated data



Inverter			i550-C1.1/230-2	i550-C1.5/230-2	i550-C2.2/230-2	i550-C4.0/230-3
Rated power	P_{rated}	**kW**	**1.1**	**1.5**	**2.2**	**4**
Rated power	P_{rated}	**hp**	**1.5**	**2**	**3**	**5**
Mains voltage range			3/PE AC 170 V ... 264 V, 45 Hz ... 65 Hz			3/PE AC 195 V ... 264 V, 45 Hz ... 65 Hz
Output voltage			3 AC 0 - 230/240 V			
Rated mains current						
without mains choke		A	7.8	9.5	13.6	20.6
with mains choke		A	5.6	6.8	9.8	15.7
Apparent output power		kVA	2.2	2.6	3.6	6.4
Rated output current						
2 kHz		A	6	7	9.6	16.5
4 kHz		A	6	7	9.6	16.5
8 kHz		A	6	7	9.6	16.5
16 kHz		A	4	4.7	6.4	11
Power loss						
2 kHz		W	36	41	54	113
4 kHz		W	37	43	60	115
8 kHz		W	42	50	70	130
16 kHz		W	51	59	78	116
Overcurrent cycle 180 s						
Max. output current (≤ 8 kHz)		A	9	10.5	14.4	24.8
Overload time	T_1	s	60	60	60	60
Recovery time	T_2	s	120	120	120	120
Max. output current during the recovery time		A	4.5	5.3	7.2	12.4
Overcurrent cycle 15 s						
Max. output current (≤ 8 kHz)		A	12	14	19.2	33
Overload time	T_1	s	3	3	3	3
Recovery time	T_2	s	12	12	12	12
Max. output current during the recovery time		A	4.5	5.3	7.2	12.4
Cyclic mains switching			3 times per minute			
Brake chopper						
Max. output current		A	12			26
Min. Brake resistor		Ω	33			15
Max. shielded motor cable length						
without EMC category		m	50			
Category C1 (≤ 8 kHz)		m	-			
Category C2 (≤ 8 kHz)		m	-			
Category C3 (≤ 8 kHz)		m	-			
Max. Unshielded motor cable length						
without EMC category		m	100			

Inverter			i550-C5.5/230-3
Rated power	**P_{rated}**	**kW**	**5.5**
Rated power	**P_{rated}**	**hp**	**7.5**
Mains voltage range			3/PE AC 195 V ... 264 V, 45 Hz ... 65 Hz
Output voltage			3 AC 0 - 230/240 V
Rated mains current			
without mains choke		A	28.8
with mains choke		A	21.9
Apparent output power		kVA	8.7
Rated output current			
2 kHz		A	23
4 kHz		A	23
8 kHz		A	23
16 kHz		A	15.3
Power loss			
2 kHz		W	166
4 kHz		W	175
8 kHz		W	195
16 kHz		W	159
Overcurrent cycle 180 s			
Max. output current (≤ 8 kHz)		A	34.5
Overload time	T_1	s	60
Recovery time	T_2	s	120
Max. output current during the recovery time		A	17.3
Overcurrent cycle 15 s			
Max. output current (≤ 8 kHz)		A	46
Overload time	T_1	s	3
Recovery time	T_2	s	12
Max. output current during the recovery time		A	17.3
Cyclic mains switching			3 times per minute
Brake chopper			
Max. output current		A	26
Min. Brake resistor		Ω	15
Max. shielded motor cable length			
without EMC category		m	50
Category C1 (≤ 8 kHz)		m	-
Category C2 (≤ 8 kHz)		m	-
Category C3 (≤ 8 kHz)		m	-
Max. Unshielded motor cable length			
without EMC category		m	100

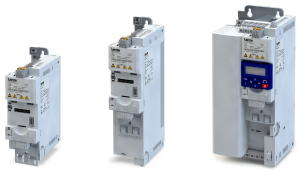


Fusing data (EN 60204-1)

A residual current device (RCD) is optional.

Fusing data for UL/NEC compliant installations: ▸ Fusing data 55

Inverter	Fuse			Circuit breaker			RCD	
	Max. SCCR	Characteristic	Max. rated current	Max. SCCR	Characteristic	Max. rated current		Type
	kA		A	kA		A	mA	
i550-C0.25/230-2	65	gG/gL, gRL	16	65	B, C	16	≥ 30	Typ B
i550-C0.37/230-2	65	gG/gL, gRL	16	65	B, C	16	≥ 30	Typ B
i550-C0.55/230-2	65	gG/gL, gRL	16	65	B, C	16	≥ 30	Typ B
i550-C0.75/230-2	65	gG/gL, gRL	16	65	B, C	16	≥ 30	Typ B
i550-C1.1/230-2	65	gG/gL, gRL	32	65	B, C	32	≥ 30	Typ B
i550-C1.5/230-2	65	gG/gL, gRL	32	65	B, C	32	≥ 30	Typ B
i550-C2.2/230-2	65	gG/gL, gRL	32	65	B, C	32	≥ 30	Typ B
i550-C4.0/230-3	65	gG/gL, gRL	40	65	B, C	40	≥ 300	Typ B
i550-C5.5/230-3	65	gG/gL, gRL	40	65	B, C	40	≥ 300	Typ B



Connection data

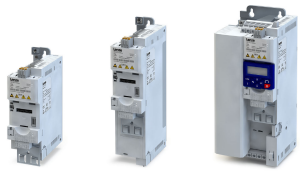
Rated power	P_{rated}	kW	0.25 ... 0.75	1.1 ... 2.2	4 ... 5.5
Connection description			**Mains connection**		
Connection			**X100**		
Connection type			Pluggable		Non-pluggable
Max. Cable cross-section		mm²	2.5	6	6
Max. Cable cross-section		AWG	12	10	10
Stripping length		mm	8	8	9
Stripping length		in	0.3	0.3	0.35
Tightening torque		Nm	0.5	0.7	0.5
Tightening torque		lb-in	4.4	6.2	4.4
Required tool			Screwdriver 0.5 x 3.0	Screwdriver 0.6 x 3.5	

Rated power	P_{rated}	kW	0.25 ... 5.5
Connection description			**PE connection**
Terminal type			**Schraube**
Max. Cable cross-section		mm²	6
Max. Cable cross-section		AWG	10
Stripping length		mm	10
Stripping length		in	0.4
Tightening torque		Nm	2
Tightening torque		lb-in	18
Required tool			Torx key 20

Rated power	P_{rated}	kW	0.25 ... 2.2	4 ... 5.5
Connection description			**Motor connection**	
Connection			**X105**	
Connection type			Pluggable	Non-pluggable
Max. Cable cross-section		mm²	2.5	6
Max. Cable cross-section		AWG	12	10
Stripping length		mm	8	9
Stripping length		in	0.3	0.35
Tightening torque		Nm	0.5	0.5
Tightening torque		lb-in	4.4	4.4
Required tool			Screwdriver 0.5 x 3.0	Screwdriver 0.6 x 3.5

The connection data for the terminal X1 can be found under: ▸ Connection data 🕮 79

Technical data
3-phase mains connection 230/240 V
Brake resistors



Brake resistors

Inverter	Brake resistor					
	Order code	Rated resistance	Rated power	Thermal capacity	Dimensions (H x W x D)	Weight
		Ω	W	kWs	mm	kg
i550-C0.25/230-2	ERBM180R050W	180	50	7.5	175 x 20.6 x 40	0.28
i550-C0.25/230-2	ERBP180R200W	180	200	30	240 x 42 x 122	1.0
i550-C0.37/230-2	ERBM180R050W	180	50	7.5	175 x 20.6 x 40	0.28
i550-C0.37/230-2	ERBP180R200W	180	200	30	240 x 42 x 122	1.0
i550-C0.55/230-2	ERBM100R086W	100	86	3.4	110 x 80 x 28	0.49
i550-C0.55/230-2	ERBM100R150W	100	150	22.5	238 x 80 x 59	0.54
i550-C0.75/230-2	ERBM100R086W	100	86	3.4	110 x 80 x 28	0.49
i550-C0.75/230-2	ERBM100R150W	100	150	22.5	238 x 80 x 59	0.54
i550-C1.1/230-2	ERBP033R200W	33	200	30	240 x 42 x 122	1.0
i550-C1.1/230-2	ERBP033R300W	33	300	45	320 x 42 x 122	1.4
i550-C1.5/230-2	ERBP033R200W	33	200	30	240 x 42 x 122	1.0
i550-C1.5/230-2	ERBP033R300W	33	300	45	320 x 42 x 122	1.4
i550-C2.2/230-2	ERBP033R200W	33	200	30	240 x 42 x 122	1.0
i550-C2.2/230-2	ERBP033R300W	33	300	45	320 x 42 x 122	1.4
i550-C4.0/230-3	ERBS015R800W	15	800	120	710 x 114 x 105	4.0
i550-C4.0/230-3	ERBS015R01K2	15	1200	180	1020 x 114 x 105	5.6
i550-C5.5/230-3	ERBS015R800W	15	800	120	710 x 114 x 105	4.0
i550-C5.5/230-3	ERBS015R01K2	15	1200	180	1020 x 114 x 105	5.6

Mains chokes

Inverter	Netzdrossel					
	Order code	No. of phases	Rated current	Inductance	Dimensions (H x W x D)	Weight
			A	mH	mm	kg
i550-C0.25/230-2	EZAELN3002B153	3	2	14.7	56 x 77 x 100	0.53
i550-C0.37/230-2	EZAELN3004B742		4	7.35	60 x 95 x 117	1.31
i550-C0.55/230-2						
i550-C0.75/230-2	EZAELN3006B492		6	4.9	69 x 95 x 117	1.45
i550-C1.1/230-2						
i550-C1.5/230-2	EZAELN3008B372		8	3.68	85 x 120 x 140	1.9
i550-C2.2/230-2	EZAELN3010B292		10	2.94		2
i550-C4.0/230-3	EZAELN3016B182		16	1.84	95 x 120 x 140	2.7
i550-C5.5/230-3	EZAELN3025B122		25	1.18	110 x 155 x 170	5.8

3-phase mains connection 230/240 V "Light Duty"

The inverters i550-Cxxx/230-3 do not have an integrated RFI filter in the AC mains supply.

In order to meet the EMC requirements according to EN IEC 61800-3, an external EMC filter according to IEC EN 60939 must be used.

The user must verify that the conformity with EN IEC 61800-3 is fulfilled.

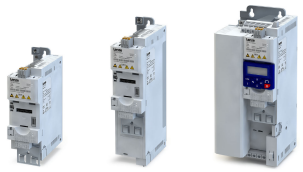
Rated data

The output currents apply to these operating conditions:

- At a switching frequency of 2 kHz or 4 kHz: Ambient temperature above 40 °C with a rated output current reduced by 2.5 %/°C.
- If the load characteristic "Light Duty" and the switching frequencies 8 kHz or 16 kHz are selected, only the values of the load characteristic "Heavy Duty" are reached.

Technical data

3-phase mains connection 230/240 V "Light Duty"
Rated data



Inverter			i550-C4.0/230-3	i550-C5.5/230-3
Rated power	**P_{rated}**	**kW**	**5.5**	**7.5**
Rated power	**P_{rated}**	**hp**	**7.5**	**10**
Mains voltage range			3/PE AC 195 V ... 264 V, 45 Hz ... 65 Hz	
Output voltage			3 AC 0 - 230/240 V	
Rated mains current				
without mains choke		A	25.8	-
with mains choke		A	18.9	24.2
Apparent output power		kVA	8	10.5
Rated output current				
2 kHz		A	20.6	27.6
4 kHz		A	20.6	27.6
8 kHz		A	-	
16 kHz		A	-	
Power loss				
2 kHz		W	124	190
4 kHz		W	131	200
8 kHz		W	-	
16 kHz		W	-	
Overcurrent cycle 180 s				
Max. output current (≤ 8 kHz)		A	24.8	34.5
Overload time	T_1	s	60	60
Recovery time	T_2	s	120	120
Max. output current during the recovery time		A	12.4	17.3
Overcurrent cycle 15 s				
Max. output current (≤ 8 kHz)		A	33	46
Overload time	T_1	s	3	3
Recovery time	T_2	s	12	12
Max. output current during the recovery time		A	12.4	17.3
Cyclic mains switching			3 times per minute	
Brake chopper				
Max. output current		A	26	
Min. Brake resistor		Ω	15	
Max. shielded motor cable length				
without EMC category		m	50	
Category C1 (≤ 8 kHz)		m	-	
Category C2 (≤ 8 kHz)		m	-	
Category C3 (≤ 8 kHz)		m	-	
Max. Unshielded motor cable length				
without EMC category		m	100	

Fusing data (EN 60204-1)

A residual current device (RCD) is optional.

Fusing data for UL/NEC compliant installations: ▸ Fusing data 55

Inverter	Fuse			Circuit breaker			RCD	
	Max. SCCR	Characteristic	Max. rated current	Max. SCCR	Characteristic	Max. rated current		Type
	kA		A	kA		A	mA	
i550-C4.0/230-3	65	gG/gL, gRL	40	65	B, C	40	≥ 300	Typ B
i550-C5.5/230-3	65	gG/gL, gRL	40	65	B, C	40	≥ 300	Typ B

Connection data

See "3-phase mains connection 230/240 V" ▸ Connection data 103

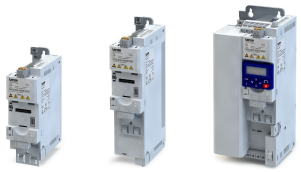
The connection data for the terminal X1 can be found under: ▸ Connection data 79

Brake resistors

Inverter	Brake resistor					
	Order code	Rated resistance	Rated power	Thermal capacity	Dimensions (H x W x D)	Weight
		Ω	W	kWs	mm	kg
i550-C4.0/230-3	ERBS015R800W	15	800	120	710 x 114 x 105	4.0
i550-C4.0/230-3	ERBS015R01K2	15	1200	180	1020 x 114 x 105	5.6
i550-C5.5/230-3	ERBS015R800W	15	800	120	710 x 114 x 105	4.0
i550-C5.5/230-3	ERBS015R01K2	15	1200	180	1020 x 114 x 105	5.6

Mains chokes

Inverter	Netzdrossel					
	Order code	No. of phases	Rated current	Inductance	Dimensions (H x W x D)	Weight
			A	mH	mm	kg
i550-C4.0/230-3	EZAELN3016B182	3	16	1.84	95 x 120 x 140	2.7
i550-C5.5/230-3	EZAELN3025B122		25	1.18	110 x 155 x 170	5.8



3-phase mains connection 400 V

Rated data

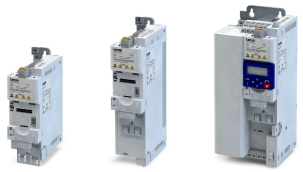
The output currents apply to these operating conditions:

- At a switching frequency of 2 kHz or 4 kHz: Max. ambient temperature 45°C.
- At a switching frequency of 8 kHz or 16 kHz: Max. ambient temperature 40 °C.

Inverter			i550-C0.37/400-3	i550-C0.55/400-3	i550-C0.75/400-3	i550-C1.1/400-3
Rated power	**P_{rated}**	**kW**	**0.37**	**0.55**	**0.75**	**1.1**
Rated power	**P_{rated}**	**hp**	**0.5**	**0.75**	**1**	**1.5**
Mains voltage range			3/PE AC 340 V ... 440 V, 45 Hz ... 65 Hz			
Output voltage			3 AC 0 - 400/480 V			
Rated mains current						
without mains choke		A	1.8	2.5	3.3	4.4
with mains choke		A	1.4	2	2.6	3
Apparent output power		kVA	0.9	1.2	1.6	2.2
Rated output current						
2 kHz		A	-	1.8	2.4	3.2
4 kHz		A	1.3	1.8	2.4	3.2
8 kHz		A	1.3	1.8	2.4	3.2
16 kHz		A	0.9	1.2	1.6	2.1
Power loss						
2 kHz		W	-	24	30	38
4 kHz		W	20	25	32	40
8 kHz		W	24	31	40	51
16 kHz		W	24	31	40	51
Overcurrent cycle 180 s						
Max. output current (≤ 8 kHz)		A	2	2.7	3.6	4.8
Overload time	T_1	s	60	60	60	60
Recovery time	T_2	s	120	120	120	120
Max. output current during the recovery time		A	1	1.4	1.8	2.4
Overcurrent cycle 15 s						
Max. output current (≤ 8 kHz)		A	2.6	3.6	4.8	6.4
Overload time	T_1	s	3	3	3	3
Recovery time	T_2	s	12	12	12	12
Max. output current during the recovery time		A	1	1.4	1.8	2.4
Cyclic mains switching			3 times per minute			
Brake chopper						
Max. output current		A	2	1.9	2	5.2
Min. Brake resistor		Ω	390			150
Max. shielded motor cable length						
without EMC category		m	15	50		
Category C1 (≤ 8 kHz)		m	3			
Category C2 (≤ 8 kHz)		m	15	20		
Category C3 (≤ 8 kHz)		m	15	20		35
Max. Unshielded motor cable length						
without EMC category		m	40	80		100

Technical data

3-phase mains connection 400 V
Rated data

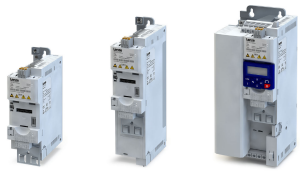


Inverter			i550-C1.5/400-3	i550-C2.2/400-3	i550-C3.0/400-3	i550-C4.0/400-3
Rated power	P_{rated}	**kW**	**1.5**	**2.2**	**3**	**4**
Rated power	P_{rated}	**hp**	**2**	**3**	**4**	**5**
Mains voltage range			3/PE AC 340 V ... 440 V, 45 Hz ... 65 Hz			
Output voltage			3 AC 0 - 400/480 V			
Rated mains current						
without mains choke		A	5.4	7.8	9.6	12.5
with mains choke		A	3.7	5.3	6.9	9
Apparent output power		kVA	2.6	3.8	4.9	6.4
Rated output current						
2 kHz		A	3.9	5.6	7.3	9.5
4 kHz		A	3.9	5.6	7.3	9.5
8 kHz		A	3.9	5.6	7.3	9.5
16 kHz		A	2.6	3.7	4.9	6.3
Power loss						
2 kHz		W	45	62	79	102
4 kHz		W	48	66	85	110
8 kHz		W	61	85	110	140
16 kHz		W	61	85	109	140
Overcurrent cycle 180 s						
Max. output current (≤ 8 kHz)		A	5.9	8.4	11	14.3
Overload time	T_1	s	60	60	60	60
Recovery time	T_2	s	120	120	120	120
Max. output current during the recovery time		A	2.9	4.2	5.5	7.1
Overcurrent cycle 15 s						
Max. output current (≤ 8 kHz)		A	7.8	11.2	14.6	19
Overload time	T_1	s	3	3	3	3
Recovery time	T_2	s	12	12	12	12
Max. output current during the recovery time		A	2.9	4.2	5.5	7.1
Cyclic mains switching			3 times per minute			
Brake chopper						
Max. output current		A	5.2	4.8	8.8	15.4
Min. Brake resistor		Ω	150		82	47
Max. shielded motor cable length						
without EMC category		m	50			
Category C1 (≤ 8 kHz)		m	3		-	
Category C2 (≤ 8 kHz)		m	20			
Category C3 (≤ 8 kHz)		m	35			
Max. Unshielded motor cable length						
without EMC category		m	100			

Inverter			**i550-C5.5/400-3**	**i550-C7.5/400-3**	**i550-C11/400-3**	**i550-C15/400-3**
Rated power	P_{rated}	**kW**	**5.5**	**7.5**	**11**	**15**
Rated power	P_{rated}	**hp**	**7.5**	**10**	**15**	**20**
Mains voltage range			3/PE AC 340 V ... 440 V, 45 Hz ... 65 Hz			
Output voltage			3 AC 0 - 400/480 V			
Rated mains current						
without mains choke		A	17.2	20	28.4	38.7
with mains choke		A	12.4	15.7	22.3	28.8
Apparent output power		kVA	8.7	11	16	22
Rated output current						
2 kHz		A	13	16.5	23.5	32
4 kHz		A	13	16.5	23.5	32
8 kHz		A	13	16.5	23.5	32
16 kHz		A	8.7	11	15.7	21.3
Power loss						
2 kHz		W	137	166	235	340
4 kHz		W	145	172	242	360
8 kHz		W	190	183	258	460
16 kHz		W	189	183	258	469
Overcurrent cycle 180 s						
Max. output current (≤ 8 kHz)		A	19.5	25	35	48
Overload time	T_1	s	60	60	60	60
Recovery time	T_2	s	120	120	120	120
Max. output current during the recovery time		A	9.8	12.4	17.6	24
Overcurrent cycle 15 s						
Max. output current (≤ 8 kHz)		A	26	33	47	64
Overload time	T_1	s	3	3	3	3
Recovery time	T_2	s	12	12	12	12
Max. output current during the recovery time		A	9.8	12.4	17.6	24
Cyclic mains switching			3 times per minute			
Brake chopper						
Max. output current		A	16.6	27		40
Min. Brake resistor		Ω	47	27		18
Max. shielded motor cable length						
without EMC category		m	100			
Category C1 (≤ 8 kHz)		m	-			
Category C2 (≤ 8 kHz)		m	20			
Category C3 (≤ 8 kHz)		m	35	50		35
Max. Unshielded motor cable length						
without EMC category		m	200			

Technical data

3-phase mains connection 400 V
Rated data

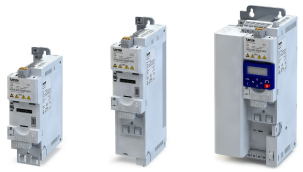


Inverter			i550-C15/400-3	i550-C18/400-3	i550-C18/400-3	i550-C22/400-3
Rated power	P_{rated}	**kW**	**15**	**18.5**		**22**
Rated power	P_{rated}	**hp**	**20**	**25**		**30**
Mains voltage range			3/PE AC 340 V ... 440 V, 45 Hz ... 65 Hz			
Output voltage			3 AC 0 - 400/480 V			
Rated mains current						
without mains choke		A	38.7	48.4		-
with mains choke		A	28.8	36		42
Apparent output power		kVA	22	27		32
Rated output current						
2 kHz		A	32	40		47
4 kHz		A	32	40		47
8 kHz		A	32	40		47
16 kHz		A	21.3	26.6		31.3
Power loss						
2 kHz		W	317	420	395	491
4 kHz		W	328	450	408	520
8 kHz		W	349	570	435	670
16 kHz		W	349	581	435	680
Overcurrent cycle 180 s						
Max. output current (≤ 8 kHz)		A	48	60	60	71
Overload time	T_1	s	60	60	60	60
Recovery time	T_2	s	120	120	120	120
Max. output current during the recovery time		A	24	30	30	35
Overcurrent cycle 15 s						
Max. output current (≤ 8 kHz)		A	64	80	80	94
Overload time	T_1	s	3	3	3	3
Recovery time	T_2	s	12	12	12	12
Max. output current during the recovery time		A	24	30	30	35
Cyclic mains switching			3 times per minute			
Brake chopper						
Max. output current		A	43	52	48	
Min. Brake resistor		Ω	18	15		
Max. shielded motor cable length						
without EMC category		m	100			
Category C1 (≤ 8 kHz)		m	-			
Category C2 (≤ 8 kHz)		m	20			
Category C3 (≤ 8 kHz)		m	35			
Max. Unshielded motor cable length						
without EMC category		m	200			

Inverter			i550-C22/400-3	i550-C30/400-3	i550-C30/400-3	i550-C37/400-3
Rated power	**P_{rated}**	**kW**	**22**	**30**		**37**
Rated power	**P_{rated}**	**hp**	**30**	**40**		**50**
Mains voltage range			3/PE AC 340 V ... 440 V, 45 Hz ... 65 Hz			
Output voltage			3 AC 0 - 400/480 V			
Rated mains current						
without mains choke		A	53	-		
with mains choke		A	42	54.9		68
Apparent output power		kVA	32	41		51
Rated output current						
2 kHz		A	47	61		76
4 kHz		A	47	61		76
8 kHz		A	47	61		76
16 kHz		A	31.3	40.6		50.6
Power loss						
2 kHz		W	463	639	599	790
4 kHz		W	479	680	620	840
8 kHz		W	510	880	661	1100
16 kHz		W	510	884	661	1095
Overcurrent cycle 180 s						
Max. output current (≤ 8 kHz)		A	71	92	92	114
Overload time	T_1	s	60	60	60	60
Recovery time	T_2	s	120	120	120	120
Max. output current during the recovery time		A	35	46	46	57
Overcurrent cycle 15 s						
Max. output current (≤ 8 kHz)		A	94	122	122	152
Overload time	T_1	s	3	3	3	3
Recovery time	T_2	s	12	12	12	12
Max. output current during the recovery time		A	35	46	46	57
Cyclic mains switching			3 times per minute			
Brake chopper						
Max. output current		A	52	97		
Min. Brake resistor		Ω	15	7.5		
Max. shielded motor cable length						
without EMC category		m	100			
Category C1 (≤ 8 kHz)		m	-			
Category C2 (≤ 8 kHz)		m	20			
Category C3 (≤ 8 kHz)		m	35			
Max. Unshielded motor cable length						
without EMC category		m	200			

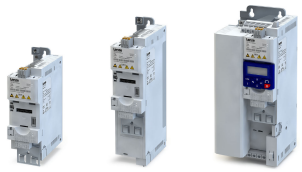
Technical data

3-phase mains connection 400 V
Rated data



Inverter			i550-C45/400-3	i550-C55/400-3	i550-C75/400-3	i550-C90/400-3
Rated power	**P_{rated}**	**kW**	**45**	**55**	**75**	**90**
Rated power	**P_{rated}**	**hp**	**60**	**75**	**100**	**125**
Mains voltage range			3/PE AC 340 V ... 440 V, 45 Hz ... 65 Hz			
Output voltage			3 AC 0 - 400/480 V			
Rated mains current						
without mains choke		A	-			
with mains choke		A	80	99	135	168
Apparent output power		kVA	60	75	100	121
Rated output current						
2 kHz		A	89	110	150	180
4 kHz		A	89	110	150	180
8 kHz		A	89	110	150	162
16 kHz		A	59.3	73.3	100	108
Power loss						
2 kHz		W	920	1137	1539	1841
4 kHz		W	980	1210	1640	1961
8 kHz		W	1280	1580	2140	2312
16 kHz		W	1278	1579	2143	2312
Overcurrent cycle 180 s						
Max. output current (≤ 8 kHz)		A	134	165	225	270
Overload time	T_1	s	60	60	60	60
Recovery time	T_2	s	120	120	120	120
Max. output current during the recovery time		A	67	83	113	135
Overcurrent cycle 15 s						
Max. output current (≤ 8 kHz)		A	178	220	300	360
Overload time	T_1	s	3	3	3	3
Recovery time	T_2	s	12	12	12	12
Max. output current during the recovery time		A	67	83	113	135
Cyclic mains switching			3 times per minute	Once per minute		
Brake chopper						
Max. output current		A	97	154	166	275
Min. Brake resistor		Ω	7.5	4.7		2.3
Max. shielded motor cable length						
without EMC category		m	100	200		
Category C1 (≤ 8 kHz)		m	-			
Category C2 (≤ 8 kHz)		m	20			
Category C3 (≤ 8 kHz)		m	35	100		
Max. Unshielded motor cable length						
without EMC category		m	200	300		

Inverter			**i550-C110/400-3**
Rated power	**P_{rated}**	**kW**	**110**
Rated power	**P_{rated}**	**hp**	**150**
Mains voltage range			3/PE AC 340 V ... 440 V, 45 Hz ... 65 Hz
Output voltage			3 AC 0 - 400/480 V
Rated mains current			
without mains choke		A	-
with mains choke		A	198
Apparent output power		kVA	142
Rated output current			
2 kHz		A	212
4 kHz		A	212
8 kHz		A	191
16 kHz		A	127
Power loss			
2 kHz		W	2163
4 kHz		W	2305
8 kHz		W	2717
16 kHz		W	2717
Overcurrent cycle 180 s			
Max. output current (≤ 8 kHz)		A	318
Overload time	T_1	s	60
Recovery time	T_2	s	120
Max. output current during the recovery time		A	159
Overcurrent cycle 15 s			
Max. output current (≤ 8 kHz)		A	424
Overload time	T_1	s	3
Recovery time	T_2	s	12
Max. output current during the recovery time		A	159
Cyclic mains switching			Once per minute
Brake chopper			
Max. output current		A	275
Min. Brake resistor		Ω	2.3
Max. shielded motor cable length			
without EMC category		m	200
Category C1 (≤ 8 kHz)		m	-
Category C2 (≤ 8 kHz)		m	100
Category C3 (≤ 8 kHz)		m	100
Max. Unshielded motor cable length			
without EMC category		m	300



Fusing data (EN 60204-1)

A residual current device (RCD) is optional.

Fusing data for UL/NEC compliant installations: ▸ Fusing data 55

Inverter	Fuse			Circuit breaker			RCD	
	Max. SCCR	Characteristic	Max. rated current	Max. SCCR	Characteristic	Max. rated current		Type
	kA		A	kA		A	mA	
i550-C0.37/400-3	65	gG/gL, gRL	16	65	B, C	16	≥ 30	Typ B
i550-C0.55/400-3	65	gG/gL, gRL	16	65	B, C	16	≥ 30	Typ B
i550-C0.75/400-3	65	gG/gL, gRL	16	65	B, C	16	≥ 30	Typ B
i550-C1.1/400-3	65	gG/gL, gRL	16	65	B, C	16	≥ 30	Typ B
i550-C1.5/400-3	65	gG/gL, gRL	16	65	B, C	16	≥ 30	Typ B
i550-C2.2/400-3	65	gG/gL, gRL	16	65	B, C	16	≥ 30	Typ B
i550-C3.0/400-3	65	gG/gL, gRL	35	65	B, C	25	≥ 30	Typ B
i550-C4.0/400-3	65	gG/gL, gRL	35	65	B, C	25	≥ 30	Typ B
i550-C5.5/400-3	65	gG/gL, gRL	25	65	B, C	25	≥ 300	Typ B
i550-C7.5/400-3	65	gG/gL, gRL	40	65	B, C	40	≥ 30	Typ B
i550-C11/400-3	65	gG/gL, gRL	40	65	B, C	40	≥ 30	Typ B
i550-C15/400-3	65	gG/gL, gRL	90	65	B, C	90	≥ 300	Typ B
i550-C18/400-3	65	gG/gL, gRL	90	65	B, C	90	≥ 300	Typ B
i550-C22/400-3	65	gG/gL, gRL	90	65	B, C	90	≥ 300	Typ B
i550-C30/400-3	65	gG/gL, gRL	90	65	B, C	90	≥ 300	Typ B
i550-C37/400-3	22	gG/gL, gRL	125	35	B, C	125	≥ 300	Typ B
i550-C45/400-3	22	gG/gL, gRL	125	35	B, C	125	≥ 300	Typ B
i550-C55/400-3	22	gR	200	35	B, C	200	≥ 300	Typ B
i550-C75/400-3	22	gR	200	35	B, C	200	≥ 300	Typ B
i550-C90/400-3	22	gR	300	10	B, C	300	≥ 300	Typ B
i550-C110/400-3	22	gR	300	10	B, C	300	≥ 300	Typ B

Please note that from 30 kW onwards a mains choke must always be used.

Coneection data

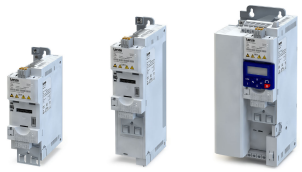
Rated power	P_{rated}	**kW**	**0.37 ... 2.2**	**3 ... 4**	**5.5**	**7.5 ... 11**	**15 ... 30**	**37 ... 45**	**55 ... 75**	**90 ... 110**
Connection description			**Mains connection**							
Connection			**X100**							
Connection type			Pluggable		Non-pluggable					
Max. Cable cross-section		mm²	2.5	4	6	16	35	50	95	150
Max. Cable cross-section		AWG	12	10	10	6	2	1/0	4/0	-
Stripping length		mm	8	8	9	11	18	22	32	41
Stripping length		in	0.3	0.3	0.35	0.43	0.7	0.87	1.26	1.6
Tightening torque		Nm	0.5	0.6	0.5	1.2	3.8	4	10	18
Tightening torque		lb-in	4.4	5.3	4.4	11	34	35	89	160
Required tool			Screwdriver 0.5 x 3.0		Screwdriver 0.6 x 3.5	Screwdriver 0.8 x 4.0	Screwdriver 0.8 x 5.5	Hex key 5.0	Hex key 6.0	Hex key 8.0

Rated power	P_{rated}	**kW**	**0.37 ... 5.5**	**7.5 ... 11**	**15 ... 30**	**37 ... 75**	**90 ... 110**
Connection description			**PE connection**				
Terminal type			**Schraube**				**Bolzen**
Max. Cable cross-section		mm²	6	16	25	35	150
Max. Cable cross-section		AWG	10	6	4	2	300 kcmil
Stripping length		mm	10	11	16	16	-
Stripping length		in	0.4	0.4	0.6	0.6	-
Tightening torque		Nm	2	3.4	4	4	10
Tightening torque		lb-in	18	30	35	35	89
Required tool			Torx key 20	Crosstip screwdriver PZ2			Wrench size 13

Rated power	P_{rated}	**kW**	**0.37 ... 4**	**5.5**	**7.5 ... 11**	**15 ... 30**	**37 ... 45**	**55 ... 75**	**90 ... 110**
Connection description			**Motor connection**						
Connection			**X105**						
Connection type			Pluggable	Non-pluggable					
Max. Cable cross-section		mm²	2.5	6	16	35	50	95	150
Max. Cable cross-section		AWG	12	10	6	2	1/0	4/0	-
Stripping length		mm	8	9	11	18	22	32	41
Stripping length		in	0.3	0.35	0.43	0.7	0.87	1.26	1.6
Tightening torque		Nm	0.5	0.5	1.2	3.8	4	10	18
Tightening torque		lb-in	4.4	4.4	11	34	35	89	160
Required tool			Screwdriver 0.5 x 3.0	Screwdriver 0.6 x 3.5	Screwdriver 0.8 x 4.0	Screwdriver 0.8 x 5.5	Hex key 5.0	Hex key 6.0	Hex key 8.0

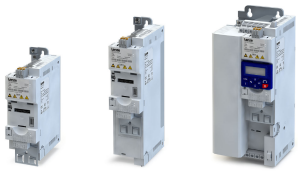
The connection data for the terminal X1 can be found under: ▸ Connection data 📖 79

Technical data
3-phase mains connection 400 V
Brake resistors



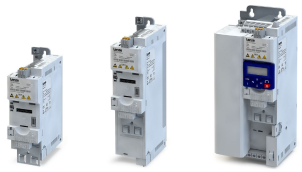
Brake resistors

Inverter	Brake resistor					
	Order code	Rated resistance	Rated power	Thermal capacity	Dimensions (H x W x D)	Weight
		Ω	W	kWs	mm	kg
i550-C0.37/400-3	ERBM470R020W	470	20	3	160 x 40 x 36	0.34
i550-C0.37/400-3	ERBM390R100W	390	100	15	235 x 20.6 x 40	0.37
i550-C0.55/400-3	ERBM390R100W	390	100	15	235 x 20.6 x 40	0.37
i550-C0.75/400-3	ERBM390R100W	390	100	15	235 x 20.6 x 40	0.37
i550-C1.1/400-3	ERBP180R200W	180	200	30	240 x 42 x 122	1.0
i550-C1.1/400-3	ERBP180R300W	180	300	45	320 x 42 x 122	1.4
i550-C1.5/400-3	ERBP180R200W	180	200	30	240 x 42 x 122	1.0
i550-C1.5/400-3	ERBS180R350WNQN000	180	350	53	382 x 124 x 122	2.1
i550-C2.2/400-3	ERBP180R200W	180	200	30	240 x 42 x 122	1.0
i550-C2.2/400-3	ERBP180R300W	180	300	45	320 x 42 x 122	1.4
i550-C2.2/400-3	ERBS180R350WNQN000	180	350	53	382 x 124 x 122	2.1
i550-C5.5/400-3	ERBP047R200W	47	200	30	240 x 42 x 122	1.0
i550-C5.5/400-3	ERBS047R400W	47	400	60	400 x 114 x 105	2.3
i550-C5.5/400-3	ERBS047R800W	47	800	120	710 x 114 x 105	4.0
i550-C37/400-3	ERBG075D01K9	7.5	1900	285	302 x 486 x 236	9.5
i550-C45/400-3	ERBG075D01K9	7.5	1900	285	302 x 486 x 236	9.5
i550-C55/400-3	ERBG005R02K6	5	2600	390	302 x 486 x 326	11.0
i550-C75/400-3	ERBG005R02K6	5	2600	390	302 x 486 x 326	11.0
i550-C90/400-3	ERBG028D04K1	2.8	4100	615	302 x 486 x 426	12.8
i550-C110/400-3	ERBG028D04K1	2.8	4100	615	302 x 486 x 426	12.8
i550-C3.0/400-3	ERBM082R150W	82	150	22.5	238 x 80 x 59	0.70
i550-C3.0/400-3	ERBP082R200W	82	200	30	240 x 42 x 122	1.0
i550-C3.0/400-3	ERBS082R780WNQN000	82	780	117	666 x 124 x 122	3.6
i550-C4.0/400-3	ERBM047R135W	47	135	6.3	216 x 80 x 28	0.67
i550-C4.0/400-3	ERBS047R400W	47	400	60	400 x 114 x 105	2.3
i550-C4.0/400-3	ERBS047R800W	47	800	120	710 x 114 x 105	4.0
i550-C7.5/400-3	ERBP027R200W	27	200	30	240 x 42 x 122	1.0
i550-C7.5/400-3	ERBS027R600W	27	600	90	550 x 114 x 105	3.1
i550-C7.5/400-3	ERBS027R01K4	27	1400	210	1110 x 114 x 105	6.3
i550-C11/400-3	ERBS027R600W	27	600	90	550 x 114 x 105	3.1
i550-C11/400-3	ERBS027R01K2	27	1200	180	1020 x 114 x 105	5.6
i550-C11/400-3	ERBS027R01K4	27	1400	210	1110 x 114 x 105	6.3
i550-C15/400-3	ERBP018R300W	18	300	45	320 x 42 x 122	1.4
i550-C15/400-3	ERBS018R01K4	18	1400	210	1110 x 114 x 105	6.3
i550-C15/400-3	ERBG018R04K3	18	4300	645	302 x 486 x 426	13.5
i550-C18/400-3	ERBS015R800W	15	800	120	710 x 114 x 105	4.0
i550-C18/400-3	ERBS015R02K4	15	2400	360	1020 x 204 x 105	10
i550-C18/400-3	ERBG015R06K2	15	6200	930	302 x 486 x 526	17.0
i550-C22/400-3	ERBS015R800W	15	800	120	710 x 114 x 105	4.0
i550-C22/400-3	ERBS015R02K4	15	2400	360	1020 x 204 x 105	10
i550-C22/400-3	ERBG015R06K2	15	6200	930	302 x 486 x 526	17.0
i550-C30/400-3	ERBG075D01K9	7.5	1900	285	302 x 486 x 236	9.5



Mains chokes

Inverter	Netzdrossel					
	Order code	No. of phases	Rated current	Inductance	Dimensions (H x W x D)	Weight
			A	mH	mm	kg
i550-C0.37/400-3	EZAELN3002B203	3	1.5	19.6	56 x 77 x 100	0.52
i550-C0.55/400-3	EZAELN3002B153		2	14.7		0.53
i550-C0.75/400-3	EZAELN3004B742		4	7.35	60 x 95 x 117	1.31
i550-C1.1/400-3						
i550-C1.5/400-3						
i550-C2.2/400-3	EZAELN3006B492		6	4.9	69 x 95 x 117	1.45
i550-C3.0/400-3	EZAELN3008B372		8	3.68	85 x 120 x 140	1.9
i550-C4.0/400-3	EZAELN3010B292		10	2.94		2
i550-C5.5/400-3	EZAELN3016B182		16	1.84	95 x 120 x 140	2.7
i550-C7.5/400-3						
i550-C11/400-3	EZAELN3025B122		25	1.18	110 x 155 x 170	5.8
i550-C15/400-3	EZAELN3030B981		30	0.98	111 x 155 x 170	5.85
i550-C18/400-3	EZAELN3040B741		40	0.74	102 x 185 x 195	6.8
i550-C22/400-3	EZAELN3045B651		45	0.65	112 x 185 x 200	8.25
i550-C30/400-3	EZAELN3063B471		63	0.47	122 x 185 x 210	9.65
i550-C37/400-3	EZAELN3080B371		80	0.37	125 x 210 x 240	12.5
i550-C45/400-3						
i550-C55/400-3	EZAELN3100B301		100	0.3	154 x 267 x 205	16.3
i550-C75/400-3	EZAELN3160B191		160	0.19	189 x 291 x 215	22.1
i550-C90/400-3	EZAELN3180B171		180	0.17	184 x 316 x 235	25
i550-C110/400-3	EZAELN3200B151		200	0.15	160 x 352 x 265	



RFI filters / Mains filters

Basic information on RFI filters, mains filters and EMC: from 📖 223

EMC filters can be used both in the side structure and in the substructure.

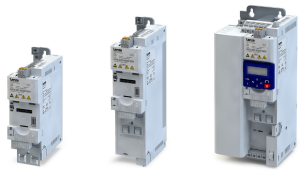
Maximum motor cable lengths with residual current device (RCD)

Mains connection			3-phase, 400 V/480 V			
Inverter			i550-C0.37/400-3	i550-C0.55/400-3 i550-C0.75/400-3	i550-C1.1/400-3 i550-C1.5/400-3 i550-C2.2/400-3 i550-C3.0/400-3 i550-C4.0/400-3	i550-C5.5/400-3
Without RFI filter						
Without EMC category Thermal limitation	Max. Shielded motor cable length	m	15	50	50	100
	Max. Unshielded motor cable length	m	40	80	100	200
With integrated RFI filter						
Category C1	Max. Shielded motor cable length	m	3	3	3 (only 1.1 ... 2.2 kW)	-
Category C2		m	15	20	20	20
	RCD (optional)	mA	30	30	30	300
RFI filter Low Leakage						
Category C1	Max. Shielded motor cable length	m	-	-	-	-
	RCD (optional)	mA	-	-	-	-
RFI filter Short Distance						
Category C1	Max. Shielded motor cable length	m	15	25	25	25
Category C2		m	15	50	50	50
	RCD (optional)	mA	30	30	30	30
RFI filter Long Distance						
Category C1	Max. Shielded motor cable length	m	15	50	50	50
Category C2		m	15	50	50	100
	RCD (optional)	mA	300	300	300	300

Mains connection			3-phase, 400 V/480 V			
Inverter			i550-C7.5/400-3 i550-C11/400-3	i550-C15/400-3 i550-C18/400-3 i550-C22/400-3	i550-C30/400-3 i550-C37/400-3 i550-C45/400-3	i550-C55/400-3 i550-C75/400-3 i550-C90/400-3 i550-C110/400-3
Without RFI filter						
Without EMC category Thermal limitation	Max. Shielded motor cable length	m	100	100	100	200
	Max. Unshielded motor cable length	m	200	200	200	300
With integrated RFI filter						
Category C1	Max. Shielded motor cable length	m	-	-	-	-
Category C2		m	20	20	20	20
	RCD (optional)	mA	300	300	300	300
RFI filter Low Leakage						
Category C1	Max. Shielded motor cable length	m	-	-	-	-
	RCD (optional)	mA	-	-	-	-
RFI filter Short Distance						
Category C1	Max. Shielded motor cable length	m	25	-	-	-
Category C2		m	50	-	-	-
	RCD (optional)	mA	30	-	-	-
RFI filter Long Distance						
Category C1	Max. Shielded motor cable length	m	50	50	50	50
Category C2		m	100	100	100	100
	RCD (optional)	mA	300	300	300	300

From i550-C22/400-3, long distance mains filters are used. Mains filters are a combination of mains choke and RFI filter.

Technical data
3-phase mains connection 400 V
RFI filters / Mains filters

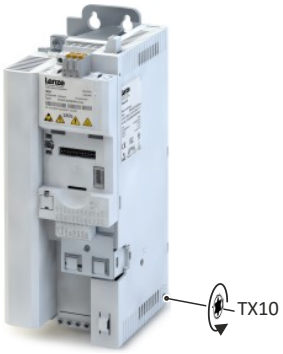


Short distance filter

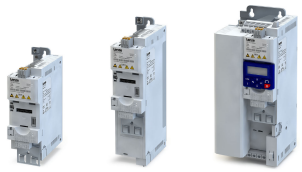
Inverter	Filter				Max. shielded motor cable length					
	Order code	Rated current	Dimensions (H x W x D)	Weight	C1		C2		C3	
		A	mm	kg	m	kHz	m	kHz		
i550-C0.37/400-3	I0FAE175F100S0000S	3.3	276 x 60 x 50	0.82	15	4	15	4	-	-
i550-C0.37/400-3	I0FAE175F100S0000S	3.3	276 x 60 x 50	0.82	15	8	15	8	-	-
i550-C0.37/400-3	I0FAE175F100S0000S	3.3	276 x 60 x 50	0.82	15	16	15	16	-	-
i550-C0.55/400-3	I0FAE175F100S0000S	3.3	276 x 60 x 50	0.82	25	2	50	2	-	-
i550-C0.55/400-3	I0FAE175F100S0000S	3.3	276 x 60 x 50	0.82	25	4	50	4	-	-
i550-C0.55/400-3	I0FAE175F100S0000S	3.3	276 x 60 x 50	0.82	25	8	50	8	-	-
i550-C0.55/400-3	I0FAE175F100S0000S	3.3	276 x 60 x 50	0.82	25	16	50	16	-	-
i550-C0.75/400-3	I0FAE175F100S0000S	3.3	276 x 60 x 50	0.82	25	2	50	2	-	-
i550-C0.75/400-3	I0FAE175F100S0000S	3.3	276 x 60 x 50	0.82	25	4	50	4	-	-
i550-C0.75/400-3	I0FAE175F100S0000S	3.3	276 x 60 x 50	0.82	25	8	50	8	-	-
i550-C0.75/400-3	I0FAE175F100S0000S	3.3	276 x 60 x 50	0.82	25	16	50	16	-	-
i550-C1.1/400-3	I0FAE222F100S0000S	7.8	346 x 60 x 50	1.01	25	2	50	2	-	-
i550-C1.1/400-3	I0FAE222F100S0000S	7.8	346 x 60 x 50	1.01	25	4	50	4	-	-
i550-C1.1/400-3	I0FAE222F100S0000S	7.8	346 x 60 x 50	1.01	25	8	50	8	-	-
i550-C1.1/400-3	I0FAE222F100S0000S	7.8	346 x 60 x 50	1.01	25	16	50	16	-	-
i550-C1.5/400-3	I0FAE222F100S0000S	7.8	346 x 60 x 50	1.01	25	2	50	2	-	-
i550-C1.5/400-3	I0FAE222F100S0000S	7.8	346 x 60 x 50	1.01	25	4	50	4	-	-
i550-C1.5/400-3	I0FAE222F100S0000S	7.8	346 x 60 x 50	1.01	25	8	50	8	-	-
i550-C1.5/400-3	I0FAE222F100S0000S	7.8	346 x 60 x 50	1.01	25	16	50	16	-	-
i550-C2.2/400-3	I0FAE222F100S0000S	7.8	346 x 60 x 50	1.01	25	2	50	2	-	-
i550-C2.2/400-3	I0FAE222F100S0000S	7.8	346 x 60 x 50	1.01	25	4	50	4	-	-
i550-C2.2/400-3	I0FAE222F100S0000S	7.8	346 x 60 x 50	1.01	25	8	50	8	-	-
i550-C2.2/400-3	I0FAE222F100S0000S	7.8	346 x 60 x 50	1.01	25	16	50	16	-	-
i550-C3.0/400-3	I0FAE240F100S0001S	14	346 x 60 x 50	1.42	25	2	50	2	-	-
i550-C3.0/400-3	I0FAE240F100S0001S	14	346 x 60 x 50	1.42	25	4	50	4	-	-
i550-C3.0/400-3	I0FAE240F100S0001S	14	346 x 60 x 50	1.42	25	8	50	8	-	-
i550-C3.0/400-3	I0FAE240F100S0001S	14	346 x 60 x 50	1.42	25	16	50	16	-	-
i550-C4.0/400-3	I0FAE240F100S0001S	14	346 x 60 x 50	1.42	25	2	50	2	-	-
i550-C4.0/400-3	I0FAE240F100S0001S	14	346 x 60 x 50	1.42	25	4	50	4	-	-
i550-C4.0/400-3	I0FAE240F100S0001S	14	346 x 60 x 50	1.42	25	8	50	8	-	-
i550-C4.0/400-3	I0FAE240F100S0001S	14	346 x 60 x 50	1.42	25	16	50	16	-	-
i550-C5.5/400-3	I0FAE255F100S0001S	18.3	346 x 90 x 60	2.05	25	4	50	4	-	-
i550-C5.5/400-3	I0FAE255F100S0001S	18.3	346 x 90 x 60	2.05	25	8	50	8	-	-
i550-C7.5/400-3	I0FAE311F100S0000S	29	371 x 120 x 60	2.35	25	4	50	4	-	-
i550-C7.5/400-3	I0FAE311F100S0000S	29	371 x 120 x 60	2.35	25	8	50	8	-	-
i550-C11/400-3	I0FAE311F100S0000S	29	371 x 120 x 60	2.35	25	4	50	4	-	-
i550-C11/400-3	I0FAE311F100S0000S	29	371 x 120 x 60	2.35	25	8	50	8	-	-

In order to meet the EMC requirements according to EN IEC 61800-3, the lower of the screws marked “IT” on the product must be removed when using the filters listed below.

Filters: I0FAE240F100S0001S
I0FAE255F100S0001S
I0FAE311F100S0000S



Technical data
3-phase mains connection 400 V
RFI filters / Mains filters

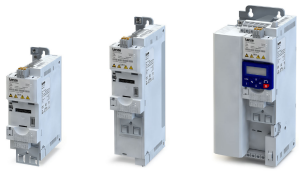


Long distance filter

Inverter	Filter				Max. shielded motor cable length					
	Order code	Rated current	Dimensions (H x W x D)	Weight	C1		C2		C3	
		A	mm	kg	m	kHz	m	kHz		
i550-C0.37/400-3	I0FAE175F100D0000S	3.3	276 x 60 x 50	0.86	15	4	15	4	-	-
i550-C0.37/400-3	I0FAE175F100D0000S	3.3	276 x 60 x 50	0.86	15	8	15	8	-	-
i550-C0.55/400-3	I0FAE175F100D0000S	3.3	276 x 60 x 50	0.86	50	4	50	4	-	-
i550-C0.55/400-3	I0FAE175F100D0000S	3.3	276 x 60 x 50	0.86	50	8	50	8	-	-
i550-C0.75/400-3	I0FAE175F100D0000S	3.3	276 x 60 x 50	0.86	50	4	50	4	-	-
i550-C0.75/400-3	I0FAE175F100D0000S	3.3	276 x 60 x 50	0.86	50	8	50	8	-	-
i550-C1.1/400-3	I0FAE222F100D0000S	7.8	346 x 60 x 50	1.03	50	4	50	4	-	-
i550-C1.1/400-3	I0FAE222F100D0000S	7.8	346 x 60 x 50	1.03	50	8	50	8	-	-
i550-C1.5/400-3	I0FAE222F100D0000S	7.8	346 x 60 x 50	1.03	50	4	50	4	-	-
i550-C1.5/400-3	I0FAE222F100D0000S	7.8	346 x 60 x 50	1.03	50	8	50	8	-	-
i550-C2.2/400-3	I0FAE222F100D0000S	7.8	346 x 60 x 50	1.03	50	4	50	4	-	-
i550-C2.2/400-3	I0FAE222F100D0000S	7.8	346 x 60 x 50	1.03	50	8	50	8	-	-
i550-C3.0/400-3	I0FAE240F100D0001S	14	346 x 60 x 50	1.42	50	4	50	4	-	-
i550-C3.0/400-3	I0FAE240F100D0001S	14	346 x 60 x 50	1.42	50	8	50	8	-	-
i550-C4.0/400-3	I0FAE240F100D0001S	14	346 x 60 x 50	1.42	50	4	50	4	-	-
i550-C4.0/400-3	I0FAE240F100D0001S	14	346 x 60 x 50	1.42	50	8	50	8	-	-
i550-C5.5/400-3	I0FAE255F100D0001S	18.3	346 x 90 x 60	1.65	50	4	100	4	-	-
i550-C5.5/400-3	I0FAE255F100D0001S	18.3	346 x 90 x 60	1.65	50	8	100	8	-	-
i550-C7.5/400-3	I0FAE311F100D0000S	29	371 x 120 x 60	2.05	50	4	100	4	-	-
i550-C7.5/400-3	I0FAE311F100D0000S	29	371 x 120 x 60	2.05	50	8	100	8	-	-
i550-C11/400-3	I0FAE311F100D0000S	29	371 x 120 x 60	2.05	50	4	100	4	-	-
i550-C11/400-3	I0FAE311F100D0000S	29	371 x 120 x 60	2.05	50	8	100	8	-	-
i550-C15/400-3	I0FAE330F100D0001S	69	465 x 180 x 106	9.4	50	4	100	4	-	-
i550-C15/400-3	I0FAE330F100D0001S	69	465 x 180 x 106	9.4	50	8	100	8	-	-
i550-C18/400-3	I0FAE330F100D0001S	69	465 x 180 x 106	9.4	50	4	100	4	-	-
i550-C18/400-3	I0FAE330F100D0001S	69	465 x 180 x 106	9.4	50	8	100	8	-	-
i550-C22/400-3	I0FAE330F100D0001S	69	465 x 180 x 106	9.4	50	4	100	4	-	-
i550-C22/400-3	I0FAE330F100D0001S	69	465 x 180 x 106	9.4	50	8	100	8	-	-
i550-C30/400-3	I0FAE330F100D0001S	69	465 x 180 x 106	9.4	50	4	100	4	-	-
i550-C30/400-3	I0FAE330F100D0001S	69	465 x 180 x 106	9.4	50	8	100	8	-	-
i550-C37/400-3	I0FAE337F100D0000S	69	590 x 250 x 105	25	50	4	100	4	-	-
i550-C37/400-3	I0FAE337F100D0000S	69	590 x 250 x 105	25	50	8	100	8	-	-
i550-C45/400-3	I0FAE345F100D0001S	100	590 x 250 x 105	32	50	2	100	2	-	-
i550-C45/400-3	I0FAE345F100D0001S	100	590 x 250 x 105	32	50	4	100	4	-	-
i550-C55/400-3	I0FAE355F100D0001S	120	700 x 250 x 105	36	50	4	100	4	-	-
i550-C55/400-3	I0FAE355F100D0001S	120	700 x 250 x 105	36	50	8	100	8	-	-
i550-C75/400-3	I0FAE375F100D0001S	162	700 x 250 x 105	41.5	50	4	100	4	-	-
i550-C75/400-3	I0FAE375F100D0001S	162	700 x 250 x 105	41.5	50	8	100	8	-	-
i550-C90/400-3	I0FAE411F100D0001S	234	855 x 250 x 130	63	-	-	100	4	-	-
i550-C90/400-3	I0FAE411F100D0001S	234	855 x 250 x 130	63	-	-	100	8	-	-
i550-C110/400-3	I0FAE411F100D0001S	234	855 x 250 x 130	63	-	-	100	4	-	-
i550-C110/400-3	I0FAE411F100D0001S	234	855 x 250 x 130	63	-	-	100	8	-	-

Sine filters

Inverter		Sine filters		
	Switching frequency	Order code	Rated inductance	Max. output frequency
	kHz		mH	Hz
i550-C0.37/400-3	4 8	EZS3-004A200	11.0	150
i550-C0.55/400-3				
i550-C0.75/400-3				
i550-C1.1/400-3				
i550-C1.5/400-3		EZS3-010A200	5.10	
i550-C2.2/400-3				
i550-C3.0/400-3				
i550-C4.0/400-3		EZS3-017A200	3.07	
i550-C5.5/400-3				
i550-C7.5/400-3		EZS3-024A200	2.50	
i550-C11/400-3		EZS3-032A200	2.00	
i550-C15/400-3		EZS3-037A200	1.70	
i550-C18/400-3		EZS3-048A200	1.20	
i550-C22/400-3		EZS3-048A200	1.20	
i550-C30/400-3		EZS3-061A200	1.00	
i550-C37/400-3		EZS3-090A200	0.8	
i550-C45/400-3		EZS3-090A200	0.8	
i550-C55/400-3	2 4	EZS3-115A200	0.7	
i550-C75/400-3		EZS3-150A200	0.5	



3-phase mains connection 400 V "Light Duty"

Rated data

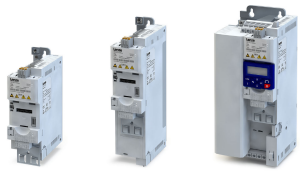
The output currents apply to these operating conditions:

- At a switching frequency of 2 kHz or 4 kHz: Ambient temperature above 40 °C with a rated output current reduced by 2.5 %/°C.
- If the load characteristic "Light Duty" and the switching frequencies 8 kHz or 16 kHz are selected, only the values of the load characteristic "Heavy Duty" are reached.

Inverter			i550-C3.0/400-3	i550-C4.0/400-3	i550-C5.5/400-3	i550-C7.5/400-3
Rated power	P_{rated}	**kW**	**4**	**5.5**	**7.5**	**11**
Rated power	P_{rated}	**hp**	**5**	**7.5**	**10**	**15**
Mains voltage range			3/PE AC 340 V ... 440 V, 45 Hz ... 65 Hz			
Output voltage			3 AC 0 - 400/480 V			
Rated mains current						
without mains choke		A	10.3	14	18.3	28
with mains choke		A	8.2	11	14.5	22
Apparent output power		kVA	5.9	8	10.5	15
Rated output current						
2 kHz		A	8.8	11.9	15.6	23
4 kHz		A	8.8	11.9	15.6	23
8 kHz		A	-			
16 kHz		A	-			
Power loss						
2 kHz		W	94	125	163	235
4 kHz		W	100	133	173	242
8 kHz		W	-			
16 kHz		W	-			
Overcurrent cycle 180 s						
Max. output current (≤ 8 kHz)		A	11	14.3	19.5	23.6
Overload time	T_1	s	60	60	60	60
Recovery time	T_2	s	120	120	120	120
Max. output current during the recovery time		A	5.5	7.1	9.8	12.4
Overcurrent cycle 15 s						
Max. output current (≤ 8 kHz)		A	14.6	19	26	33
Overload time	T_1	s	3	3	3	3
Recovery time	T_2	s	12	12	12	12
Max. output current during the recovery time		A	5.5	7.1	9.8	12.4
Cyclic mains switching			3 times per minute			
Brake chopper						
Max. output current		A	8.8	15.4	16.6	27
Min. Brake resistor		Ω	82	47		27
Max. shielded motor cable length						
without EMC category		m	50		100	
Category C1 (≤ 8 kHz)		m	-			
Category C2 (≤ 8 kHz)		m	20			
Category C3 (≤ 8 kHz)		m	35			50
Max. Unshielded motor cable length						
without EMC category		m	100		200	

Technical data

3-phase mains connection 400 V "Light Duty"
Rated data

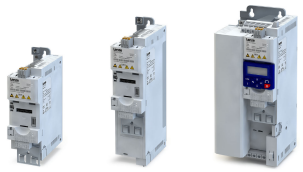


Inverter			i550-C11/400-3	i550-C15/400-3	i550-C15/400-3	i550-C18/400-3
Rated power	P_{rated}	**kW**	**15**	**18.5**		**22**
Rated power	P_{rated}	**hp**	**20**	**25**		**30**
Mains voltage range			3/PE AC 340 V ... 440 V, 45 Hz ... 65 Hz			
Output voltage			3 AC 0 - 400/480 V			
Rated mains current						
without mains choke		A	-	48		-
with mains choke		A	27.1	36		43
Apparent output power		kVA	19	26		32
Rated output current						
2 kHz		A	28.2	38.4		48
4 kHz		A	28.2	38.4		48
8 kHz		A	-			
16 kHz		A	-			
Power loss						
2 kHz		W	329	404	395	501
4 kHz		W	340	430	408	533
8 kHz		W	-			
16 kHz		W	-			
Overcurrent cycle 180 s						
Max. output current (≤ 8 kHz)		A	35	48	48	60
Overload time	T_1	s	60	60	60	60
Recovery time	T_2	s	120	120	120	120
Max. output current during the recovery time		A	17.6	24	24	30
Overcurrent cycle 15 s						
Max. output current (≤ 8 kHz)		A	47	64	64	80
Overload time	T_1	s	3	3	3	3
Recovery time	T_2	s	12	12	12	12
Max. output current during the recovery time		A	17.6	24	24	30
Cyclic mains switching			3 times per minute			
Brake chopper						
Max. output current		A	27	40	43	52
Min. Brake resistor		Ω	27	18		15
Max. shielded motor cable length						
without EMC category		m	100			
Category C1 (≤ 8 kHz)		m	-			
Category C2 (≤ 8 kHz)		m	20			
Category C3 (≤ 8 kHz)		m	50	35		
Max. Unshielded motor cable length						
without EMC category		m	200			

Inverter			i550-C18/400-3	i550-C22/400-3	i550-C22/400-3	i550-C30/400-3
Rated power	P_{rated}	**kW**	**22**	**30**		**37**
Rated power	P_{rated}	**hp**	**30**	**40**		**50**
Mains voltage range			3/PE AC 340 V ... 440 V, 45 Hz ... 65 Hz			
Output voltage			3 AC 0 - 400/480 V			
Rated mains current						
without mains choke		A	54.5	-	64	-
with mains choke		A	43	55		69
Apparent output power		kVA	32	38		49
Rated output current						
2 kHz		A	48	56.4		73.2
4 kHz		A	48	56.4		73.2
8 kHz		A	-			
16 kHz		A	-			
Power loss						
2 kHz		W	463	585	599	761
4 kHz		W	479	623	620	810
8 kHz		W	-			
16 kHz		W	-			
Overcurrent cycle 180 s						
Max. output current (≤ 8 kHz)		A	60	71	71	92
Overload time	T_1	s	60	60	60	60
Recovery time	T_2	s	120	120	120	120
Max. output current during the recovery time		A	30	35	35	46
Overcurrent cycle 15 s						
Max. output current (≤ 8 kHz)		A	80	94	94	122
Overload time	T_1	s	3	3	3	3
Recovery time	T_2	s	12	12	12	12
Max. output current during the recovery time		A	30	35	35	46
Cyclic mains switching			3 times per minute			
Brake chopper						
Max. output current		A	48		52	97
Min. Brake resistor		Ω	15			7.5
Max. shielded motor cable length						
without EMC category		m	100			
Category C1 (≤ 8 kHz)		m	-			
Category C2 (≤ 8 kHz)		m	20			
Category C3 (≤ 8 kHz)		m	35			
Max. Unshielded motor cable length						
without EMC category		m	200			

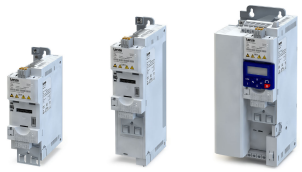
Technical data

3-phase mains connection 400 V "Light Duty"
Rated data



Inverter			i550-C37/400-3	i550-C45/400-3	i550-C55/400-3	i550-C75/400-3
Rated power	P_{rated}	**kW**	**45**	**55**	**75**	**90**
Rated power	P_{rated}	**hp**	**60**	**75**	**100**	**125**
Mains voltage range			3/PE AC 340 V ... 440 V, 45 Hz ... 65 Hz			
Output voltage			3 AC 0 - 400/480 V			
Rated mains current						
without mains choke		A	-			
with mains choke		A	86	100	119	160
Apparent output power		kVA	61	72	89	121
Rated output current						
2 kHz		A	91.2	107	132	180
4 kHz		A	91.2	107	132	180
8 kHz		A	-			
16 kHz		A	-			
Power loss						
2 kHz		W	942	1101	1358	1841
4 kHz		W	1004	1171	1446	1961
8 kHz		W	-			
16 kHz		W	-			
Overcurrent cycle 180 s						
Max. output current (≤ 8 kHz)		A	114	134	165	225
Overload time	T_1	s	60	60	60	60
Recovery time	T_2	s	120	120	120	120
Max. output current during the recovery time		A	57	67	83	113
Overcurrent cycle 15 s						
Max. output current (≤ 8 kHz)		A	152	178	220	300
Overload time	T_1	s	3	3	3	3
Recovery time	T_2	s	12	12	12	12
Max. output current during the recovery time		A	57	67	83	113
Cyclic mains switching			3 times per minute		Once per minute	
Brake chopper						
Max. output current		A	97		154	166
Min. Brake resistor		Ω	7.5		4.7	
Max. shielded motor cable length						
without EMC category		m	100		200	
Category C1 (≤ 8 kHz)		m	-			
Category C2 (≤ 8 kHz)		m	20			
Category C3 (≤ 8 kHz)		m	35		100	
Max. Unshielded motor cable length						
without EMC category		m	200		300	

Inverter			**i550-C90/400-3**	**i550-C110/400-3**
Rated power	**P_{rated}**	**kW**	**110**	**132**
Rated power	**P_{rated}**	**hp**	**150**	**175**
Mains voltage range			3/PE AC 340 V ... 440 V, 45 Hz ... 65 Hz	
Output voltage			3 AC 0 - 400/480 V	
Rated mains current				
without mains choke		A	-	
with mains choke		A	200	234
Apparent output power		kVA	145	171
Rated output current				
2 kHz		A	216	254
4 kHz		A	216	254
8 kHz		A	-	
16 kHz		A	-	
Power loss				
2 kHz		W	2203	2589
4 kHz		W	2348	2760
8 kHz		W	-	
16 kHz		W	-	
Overcurrent cycle 180 s				
Max. output current (≤ 8 kHz)		A	270	318
Overload time	T_1	s	60	60
Recovery time	T_2	s	120	120
Max. output current during the recovery time		A	135	159
Overcurrent cycle 15 s				
Max. output current (≤ 8 kHz)		A	360	424
Overload time	T_1	s	3	3
Recovery time	T_2	s	12	12
Max. output current during the recovery time		A	135	159
Cyclic mains switching			Once per minute	
Brake chopper				
Max. output current		A	275	
Min. Brake resistor		Ω	2.3	
Max. shielded motor cable length				
without EMC category		m	200	
Category C1 (≤ 8 kHz)		m	-	
Category C2 (≤ 8 kHz)		m	20	100
Category C3 (≤ 8 kHz)		m	100	
Max. Unshielded motor cable length				
without EMC category		m	300	



Fusing data (EN 60204-1)

A residual current device (RCD) is optional.

Fusing data for UL/NEC compliant installations: ▸ Fusing data 55

Inverter	Fuse			Circuit breaker			RCD	
	Max. SCCR	Characteristic	Max. rated current	Max. SCCR	Characteristic	Max. rated current		Type
	kA		A	kA		A	mA	
i550-C3.0/400-3	65	gG/gL, gRL	35	65	B, C	25	≥ 30	Typ B
i550-C4.0/400-3	65	gG/gL, gRL	35	65	B, C	25	≥ 30	Typ B
i550-C5.5/400-3	65	gG/gL, gRL	25	65	B, C	25	≥ 300	Typ B
i550-C7.5/400-3	65	gG/gL, gRL	40	65	B, C	40	≥ 30	Typ B
i550-C11/400-3	65	gG/gL, gRL	40	65	B, C	40	≥ 30	Typ B
i550-C15/400-3	65	gG/gL, gRL	90	65	B, C	90	≥ 300	Typ B
i550-C18/400-3	65	gG/gL, gRL	90	65	B, C	90	≥ 300	Typ B
i550-C22/400-3	65	gG/gL, gRL	90	65	B, C	90	≥ 300	Typ B
i550-C30/400-3	65	gG/gL, gRL	90	65	B, C	90	≥ 300	Typ B
i550-C37/400-3	22	gG/gL, gRL	125	35	B, C	125	≥ 300	Typ B
i550-C45/400-3	22	gG/gL, gRL	125	35	B, C	125	≥ 300	Typ B
i550-C55/400-3	22	gR	200	35	B, C	200	≥ 300	Typ B
i550-C75/400-3	22	gR	200	35	B, C	200	≥ 300	Typ B
i550-C90/400-3	22	gR	300	10	B, C	300	≥ 300	Typ B
i550-C110/400-3	22	gR	300	10	B, C	300	≥ 300	Typ B

Please note that from 37 kW onwards a mains choke must always be used.

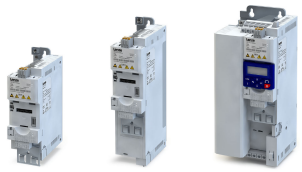
Connection data

See "3-phase mains connection 400 V" ▸ Coneection data 117

The connection data for the terminal X1 can be found under: ▸ Connection data 79

Brake resistors

Inverter	Brake resistor					
	Order code	Rated resistance	Rated power	Thermal capacity	Dimensions (H x W x D)	Weight
		Ω	W	kWs	mm	kg
i550-C5.5/400-3	ERBP047R200W	47	200	30	240 x 42 x 122	1.0
i550-C5.5/400-3	ERBS047R400W	47	400	60	400 x 114 x 105	2.3
i550-C5.5/400-3	ERBS047R800W	47	800	120	710 x 114 x 105	4.0
i550-C37/400-3	ERBG075D01K9	7.5	1900	285	302 x 486 x 236	9.5
i550-C45/400-3	ERBG075D01K9	7.5	1900	285	302 x 486 x 236	9.5
i550-C55/400-3	ERBG005R02K6	5	2600	390	302 x 486 x 326	11.0
i550-C75/400-3	ERBG005R02K6	5	2600	390	302 x 486 x 326	11.0
i550-C90/400-3	ERBG028D04K1	2.8	4100	615	302 x 486 x 426	12.8
i550-C110/400-3	ERBG028D04K1	2.8	4100	615	302 x 486 x 426	12.8
i550-C3.0/400-3	ERBM082R150W	82	150	22.5	238 x 80 x 59	0.70
i550-C3.0/400-3	ERBP082R200W	82	200	30	240 x 42 x 122	1.0
i550-C3.0/400-3	ERBS082R780WNQN000	82	780	117	666 x 124 x 122	3.6
i550-C4.0/400-3	ERBM047R135W	47	135	6.3	216 x 80 x 28	0.67
i550-C4.0/400-3	ERBS047R400W	47	400	60	400 x 114 x 105	2.3
i550-C4.0/400-3	ERBS047R800W	47	800	120	710 x 114 x 105	4.0
i550-C7.5/400-3	ERBP027R200W	27	200	30	240 x 42 x 122	1.0
i550-C7.5/400-3	ERBS027R600W	27	600	90	550 x 114 x 105	3.1
i550-C7.5/400-3	ERBS027R01K4	27	1400	210	1110 x 114 x 105	6.3
i550-C11/400-3	ERBS027R600W	27	600	90	550 x 114 x 105	3.1
i550-C11/400-3	ERBS027R01K2	27	1200	180	1020 x 114 x 105	5.6
i550-C11/400-3	ERBS027R01K4	27	1400	210	1110 x 114 x 105	6.3
i550-C15/400-3	ERBP018R300W	18	300	45	320 x 42 x 122	1.4
i550-C15/400-3	ERBS018R01K4	18	1400	210	1110 x 114 x 105	6.3
i550-C15/400-3	ERBG018R04K3	18	4300	645	302 x 486 x 426	13.5
i550-C18/400-3	ERBS015R800W	15	800	120	710 x 114 x 105	4.0
i550-C18/400-3	ERBS015R02K4	15	2400	360	1020 x 204 x 105	10
i550-C18/400-3	ERBG015R06K2	15	6200	930	302 x 486 x 526	17.0
i550-C22/400-3	ERBS015R800W	15	800	120	710 x 114 x 105	4.0
i550-C22/400-3	ERBS015R02K4	15	2400	360	1020 x 204 x 105	10
i550-C22/400-3	ERBG015R06K2	15	6200	930	302 x 486 x 526	17.0
i550-C30/400-3	ERBG075D01K9	7.5	1900	285	302 x 486 x 236	9.5



Mains chokes

Inverter	Netzdrossel					
	Order code	No. of phases	Rated current	Inductance	Dimensions (H x W x D)	Weight
			A	mH	mm	kg
i550-C3.0/400-3	EZAELN3010B292	3	10	2.94	85 x 120 x 140	2
i550-C4.0/400-3	EZAELN3016B182		16	1.84	95 x 120 x 140	2.7
i550-C5.5/400-3						
i550-C7.5/400-3	EZAELN3025B122		25	1.18	110 x 155 x 170	5.8
i550-C11/400-3	EZAELN3030B981		30	0.98	111 x 155 x 170	5.85
i550-C15/400-3	EZAELN3040B741		40	0.74	102 x 185 x 195	6.8
i550-C18/400-3	EZAELN3045B651		45	0.65	112 x 185 x 200	8.25
i550-C22/400-3	EZAELN3063B471		63	0.47	122 x 185 x 210	9.65
i550-C30/400-3	EZAELN3080B371		80	0.37	125 x 210 x 240	12.5
i550-C37/400-3	EZAELN3090B331		90	0.33	130 x 267 x 205	10.95
i550-C45/400-3	EZAELN3100B301		100	0.3	154 x 267 x 205	16.3
i550-C55/400-3	EZAELN3125B241		125	0.24	160 x 291 x 215	17.1
i550-C75/400-3	EZAELN3160B191		160	0.19	189 x 291 x 215	22.1
i550-C90/400-3	EZAELN3200B151		200	0.15	160 x 352 x 265	25
i550-C110/400-3	EZAELN3250B121		250	0.12	176 x 352 x 265	31

RFI filters / Mains filters

Basic information on RFI filters, mains filters and EMC: from 📖 223

EMC filters can be used both in the side structure and in the substructure.

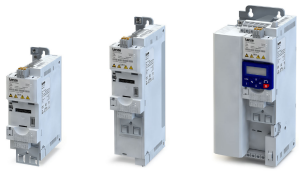
Maximum motor cable lengths with residual current device (RCD)

Mains connection			3-phase, 400 V/480 V, Light Duty				
Inverter			i550-C3.0/400-3 i550-C4.0/400-3	i550-C5.5/400-3	i550-C7.5/400-3 i550-C11/400-3	i550-C15/400-3 i550-C18/400-3 i550-C22/400-3 i550-C30/400-3 i550-C37/400-3 i550-C45/400-3	i550-C55/400-3 i550-C75/400-3 i550-C90/400-3 i550-C110/400-3
Without RFI filter							
Without EMC category Thermal limitation	Max. motor cable length shielded	m	50	100	100	100	200
	Max. motor cable length unshielded	m	100	200	200	200	300
With integrated RFI filter							
Category C1	Max. motor cable length shielded	m	-	-	-	-	-
Category C2		m	20	20	20	20	20
	RCD (optional)	mA	30	300	300	300	300
RFI filter Low Leakage							
Category C1	Max. motor cable length shielded	m	-	-	-	-	-
	RCD (optional)	mA	-	-	-	-	-
RFI filter Short Distance							
Category C1	Max. motor cable length shielded	m	25	25	25	-	-
Category C2		m	50	50	50	-	-
	RCD (optional)	mA	30	30	30	-	-
RFI filter Long Distance							
Category C1	Max. motor cable length shielded	m	50	50	50	-	-
Category C2		m	100	100	100	-	-
	RCD (optional)	mA	300	300	300	-	-

From i550-C18/400-3, long distance mains filters are used. Mains filters are a combination of mains choke and RFI filter.

Technical data

3-phase mains connection 400 V "Light Duty"
RFI filters / Mains filters

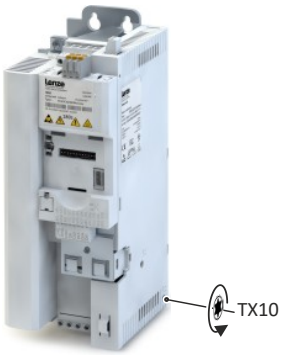


Short distance filter

Inverter	Filter				Max. shielded motor cable length					
	Order code	Rated current	Dimensions (H x W x D)	Weight	C1		C2		C3	
		A	mm	kg	m	kHz	m	kHz		
i550-C3.0/400-3	I0FAE240F100S0001S	14	346 x 60 x 50	1.42	25	2	50	2	-	-
i550-C3.0/400-3	I0FAE240F100S0001S	14	346 x 60 x 50	1.42	25	4	50	4	-	-
i550-C4.0/400-3	I0FAE240F100S0001S	14	346 x 60 x 50	1.42	25	2	50	2	-	-
i550-C4.0/400-3	I0FAE240F100S0001S	14	346 x 60 x 50	1.42	25	4	50	4	-	-
i550-C5.5/400-3	I0FAE255F100S0001S	18.3	346 x 90 x 60	2.05	25	4	50	4	-	-
i550-C7.5/400-3	I0FAE311F100S0000S	29	371 x 120 x 60	2.35	25	4	50	4	-	-
i550-C11/400-3	I0FAE311F100S0000S	29	371 x 120 x 60	2.35	25	4	50	4	-	-

In order to meet the EMC requirements according to EN IEC 61800-3, the lower of the screws marked “IT” on the product must be removed when using the filters listed below.

Filters: I0FAE240F100S0001S
I0FAE255F100S0001S
I0FAE311F100S0000S

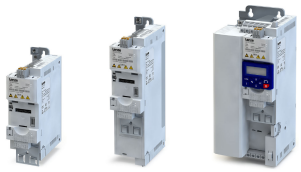


Long distance filter

Inverter	Filter				Max. shielded motor cable length					
	Order code	Rated current	Dimensions (H x W x D)	Weight	C1		C2		C3	
		A	mm	kg	m	kHz	m	kHz		
i550-C3.0/400-3	I0FAE240F100D0001S	14	346 x 60 x 50	1.42	50	4	50	4	-	-
i550-C4.0/400-3	I0FAE240F100D0001S	14	346 x 60 x 50	1.42	50	4	50	4	-	-
i550-C5.5/400-3	I0FAE255F100D0001S	18.3	346 x 90 x 60	1.65	50	4	100	4	-	-
i550-C7.5/400-3	I0FAE311F100D0000S	29	371 x 120 x 60	2.05	50	4	100	4	-	-
i550-C11/400-3	I0FAE311F100D0000S	29	371 x 120 x 60	2.05	50	4	100	4	-	-
i550-C15/400-3	I0FAE330F100D0001S	69	465 x 180 x 106	9.4	50	4	100	4	-	-
i550-C18/400-3	I0FAE330F100D0001S	69	465 x 180 x 106	9.4	50	4	100	4	-	-
i550-C22/400-3	I0FAE330F100D0001S	69	465 x 180 x 106	9.4	50	4	100	4	-	-
i550-C30/400-3	I0FAE330F100D0001S	69	465 x 180 x 106	9.4	50	4	100	4	-	-
i550-C37/400-3	I0FAE345F100D0001S	100	590 x 250 x 105	32	50	4	100	4	-	-
i550-C45/400-3	I0FAE345F100D0001S	100	590 x 250 x 105	32	50	2	100	2	-	-
i550-C45/400-3	I0FAE345F100D0001S	100	590 x 250 x 105	32	50	4	100	4	-	-
i550-C55/400-3	I0FAE355F100D0001S	120	700 x 250 x 105	36	50	4	100	4	-	-
i550-C75/400-3	I0FAE375F100D0001S	162	700 x 250 x 105	41.5	50	4	100	4	-	-
i550-C90/400-3	I0FAE411F100D0001S	234	855 x 250 x 130	63	-	-	100	4	-	-
i550-C110/400-3	I0FAE411F100D0001S	234	855 x 250 x 130	63	-	-	100	4	-	-

Sine filter

Inverter		Sine filter		
	Switching frequency	Order code	Rated inductance	Max. output frequency
	kHz		mH	Hz
i550-C3.0/400-3	4	EZS3-010A200	5.10	150
i550-C4.0/400-3		EZS3-017A200	3.07	
i550-C5.5/400-3				
i550-C7.5/400-3		EZS3-024A200	2.50	
i550-C11/400-3		EZS3-032A200	2.00	
i550-C15/400-3		EZS3-048A200	1.20	
i550-C18/400-3		EZS3-048A200	1.20	
i550-C22/400-3		EZS3-061A200	1.00	
i550-C30/400-3		EZS3-090A200	0.8	
i550-C37/400-3		EZS3-090A200	0.8	
i550-C45/400-3		EZS3-115A200	0.7	
i550-C55/400-3		EZS3-150A200	0.5	
i550-C75/400-3		EZS3-180A200	0.4	90



3-phase mains connection 480 V

Rated data

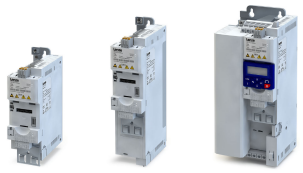
The output currents apply to these operating conditions:

- At a switching frequency of 2 kHz or 4 kHz: Max. ambient temperature 45°C.
- At a switching frequency of 8 kHz or 16 kHz: Max. ambient temperature 40 °C.

Inverter			i550-C0.37/400-3	i550-C0.55/400-3	i550-C0.75/400-3	i550-C1.1/400-3
Rated power	**P_{rated}**	**kW**	**0.37**	**0.55**	**0.75**	**1.1**
Rated power	**P_{rated}**	**hp**	**0.5**	**0.75**	**1**	**1.5**
Mains voltage range			3/PE AC 432 V ... 528 V, 45 Hz ... 65 Hz			
Output voltage			3 AC 0 - 400/480 V			
Rated mains current						
without mains choke		A	1.5	2.1	2.8	3.7
with mains choke		A	1.2	1.7	2.2	2.5
Apparent output power		kVA	0.9	1.2	1.6	2.2
Rated output current						
2 kHz		A	-	1.6	2.1	3
4 kHz		A	1.1	1.6	2.1	3
8 kHz		A	1.1	1.6	2.1	3
16 kHz		A	0.7	1.1	1.4	2
Power loss						
2 kHz		W	-	24	30	38
4 kHz		W	20	25	32	40
8 kHz		W	24	31	40	51
16 kHz		W	24	31	40	51
Overcurrent cycle 180 s						
Max. output current (≤ 8 kHz)		A	1.7	2.4	3.2	4.5
Overload time	T_1	s	60	60	60	60
Recovery time	T_2	s	120	120	120	120
Max. output current during the recovery time		A	0.8	1.2	1.6	2.3
Overcurrent cycle 15 s						
Max. output current (≤ 8 kHz)		A	2.2	3.2	4.2	6
Overload time	T_1	s	3	3	3	3
Recovery time	T_2	s	12	12	12	12
Max. output current during the recovery time		A	0.8	1.2	1.6	2.3
Cyclic mains switching			3 times per minute			
Brake chopper						
Max. output current		A	2	1.9	2	5.2
Min. Brake resistor		Ω	390			150
Max. shielded motor cable length						
without EMC category		m	15	50		
Category C1 (≤ 8 kHz)		m	3			
Category C2 (≤ 8 kHz)		m	15	20		
Category C3 (≤ 8 kHz)		m	15	20		35
Max. Unshielded motor cable length						
without EMC category		m	40	80		100

Technical data

3-phase mains connection 480 V
Rated data

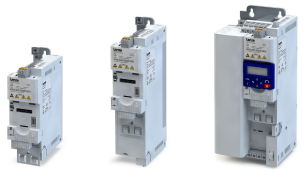


Inverter			i550-C1.5/400-3	i550-C2.2/400-3	i550-C3.0/400-3	i550-C4.0/400-3
Rated power	P_{rated}	**kW**	**1.5**	**2.2**	**3**	**4**
Rated power	P_{rated}	**hp**	**2**	**3**	**4**	**5**
Mains voltage range			3/PE AC 432 V ... 528 V, 45 Hz ... 65 Hz			
Output voltage			3 AC 0 - 400/480 V			
Rated mains current						
without mains choke		A	4.5	6.5	8	10.5
with mains choke		A	3.1	4.4	5.8	7.5
Apparent output power		kVA	2.6	3.8	4.9	6.4
Rated output current						
2 kHz		A	3.5	4.8	6.3	8.2
4 kHz		A	3.5	4.8	6.3	8.2
8 kHz		A	3.5	4.8	6.3	8.2
16 kHz		A	2.3	3.2	4.2	5.5
Power loss						
2 kHz		W	45	62	79	102
4 kHz		W	48	66	85	110
8 kHz		W	61	85	110	140
16 kHz		W	61	85	109	140
Overcurrent cycle 180 s						
Max. output current (≤ 8 kHz)		A	5.3	7.2	9.5	12.3
Overload time	T_1	s	60	60	60	60
Recovery time	T_2	s	120	120	120	120
Max. output current during the recovery time		A	2.6	3.6	4.7	6.2
Overcurrent cycle 15 s						
Max. output current (≤ 8 kHz)		A	7	9.6	12.6	16.4
Overload time	T_1	s	3	3	3	3
Recovery time	T_2	s	12	12	12	12
Max. output current during the recovery time		A	2.6	3.6	4.7	6.2
Cyclic mains switching			3 times per minute			
Brake chopper						
Max. output current		A	5.2	4.8	8.8	15.4
Min. Brake resistor		Ω	150		82	47
Max. shielded motor cable length						
without EMC category		m	50			
Category C1 (≤ 8 kHz)		m	3		-	
Category C2 (≤ 8 kHz)		m	20			
Category C3 (≤ 8 kHz)		m	35			
Max. Unshielded motor cable length						
without EMC category		m	100			

Inverter			i550-C5.5/400-3	i550-C7.5/400-3	i550-C11/400-3	i550-C15/400-3
Rated power	**P_{rated}**	**kW**	**5.5**	**7.5**	**11**	**15**
Rated power	**P_{rated}**	**hp**	**7.5**	**10**	**15**	**20**
Mains voltage range			3/PE AC 432 V ... 528 V, 45 Hz ... 65 Hz			
Output voltage			3 AC 0 - 400/480 V			
Rated mains current						
without mains choke		A	14.3	16.6	23.7	32.3
with mains choke		A	10.3	13.1	18.6	24
Apparent output power		kVA	8.7	11	16	22
Rated output current						
2 kHz		A	11	14	21	27
4 kHz		A	11	14	21	27
8 kHz		A	11	14	21	27
16 kHz		A	7.3	9.3	14	18
Power loss						
2 kHz		W	137	166	235	340
4 kHz		W	145	172	242	360
8 kHz		W	190	183	258	460
16 kHz		W	189	183	258	469
Overcurrent cycle 180 s						
Max. output current (≤ 8 kHz)		A	16.5	21	31.5	40.5
Overload time	T_1	s	60	60	60	60
Recovery time	T_2	s	120	120	120	120
Max. output current during the recovery time		A	8.3	10.5	15.8	20.3
Overcurrent cycle 15 s						
Max. output current (≤ 8 kHz)		A	22	28	42	54
Overload time	T_1	s	3	3	3	3
Recovery time	T_2	s	12	12	12	12
Max. output current during the recovery time		A	8.3	10.5	15.8	20.3
Cyclic mains switching			3 times per minute			
Brake chopper						
Max. output current		A	16.6	27		40
Min. Brake resistor		Ω	47	27		18
Max. shielded motor cable length						
without EMC category		m	100			
Category C1 (≤ 8 kHz)		m	-			
Category C2 (≤ 8 kHz)		m	20			
Category C3 (≤ 8 kHz)		m	35	50		35
Max. Unshielded motor cable length						
without EMC category		m	200			

Technical data

3-phase mains connection 480 V
Rated data

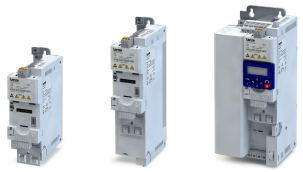


Inverter			i550-C15/400-3	i550-C18/400-3	i550-C18/400-3	i550-C22/400-3
Rated power	P_{rated}	**kW**	**15**	**18.5**		**22**
Rated power	P_{rated}	**hp**	**20**	**25**		**30**
Mains voltage range			3/PE AC 432 V ... 528 V, 45 Hz ... 65 Hz			
Output voltage			3 AC 0 - 400/480 V			
Rated mains current						
without mains choke		A	32.3	40.3		47.4
with mains choke		A	24	30		35.3
Apparent output power		kVA	22	27		32
Rated output current						
2 kHz		A	27	34		40.4
4 kHz		A	27	34		40.4
8 kHz		A	27	34		40.4
16 kHz		A	18	22.6		26.9
Power loss						
2 kHz		W	317	420	395	491
4 kHz		W	328	450	408	520
8 kHz		W	349	570	435	670
16 kHz		W	349	581	435	680
Overcurrent cycle 180 s						
Max. output current (≤ 8 kHz)		A	40.5	51	51	61
Overload time	T_1	s	60	60	60	60
Recovery time	T_2	s	120	120	120	120
Max. output current during the recovery time		A	20.3	25.5	25.5	30
Overcurrent cycle 15 s						
Max. output current (≤ 8 kHz)		A	54	68	68	81
Overload time	T_1	s	3	3	3	3
Recovery time	T_2	s	12	12	12	12
Max. output current during the recovery time		A	20.3	25.5	25.5	30
Cyclic mains switching			3 times per minute			
Brake chopper						
Max. output current		A	43	52	48	
Min. Brake resistor		Ω	18	15		
Max. shielded motor cable length						
without EMC category		m	100			
Category C1 (≤ 8 kHz)		m	-			
Category C2 (≤ 8 kHz)		m	20			
Category C3 (≤ 8 kHz)		m	35			
Max. Unshielded motor cable length						
without EMC category		m	200			

Inverter			i550-C22/400-3	i550-C30/400-3	i550-C30/400-3	i550-C37/400-3
Rated power	**P_{rated}**	**kW**	**22**	**30**		**37**
Rated power	**P_{rated}**	**hp**	**30**	**40**		**50**
Mains voltage range			3/PE AC 432 V ... 528 V, 45 Hz ... 65 Hz			
Output voltage			3 AC 0 - 400/480 V			
Rated mains current						
without mains choke		A	44.2	-	61.5	-
with mains choke		A	35.3	45.7		57
Apparent output power		kVA	32	41		51
Rated output current						
2 kHz		A	40.4	52		65
4 kHz		A	40.4	52		65
8 kHz		A	40.4	52		65
16 kHz		A	26.9	34.6		43.3
Power loss						
2 kHz		W	463	639	599	790
4 kHz		W	479	680	620	840
8 kHz		W	510	880	661	1100
16 kHz		W	510	884	661	1095
Overcurrent cycle 180 s						
Max. output current (≤ 8 kHz)		A	61	78	78	98
Overload time	T_1	s	60	60	60	60
Recovery time	T_2	s	120	120	120	120
Max. output current during the recovery time		A	30	39	39	49
Overcurrent cycle 15 s						
Max. output current (≤ 8 kHz)		A	81	104	104	130
Overload time	T_1	s	3	3	3	3
Recovery time	T_2	s	12	12	12	12
Max. output current during the recovery time		A	30	39	39	49
Cyclic mains switching			3 times per minute			
Brake chopper						
Max. output current		A	52	97		
Min. Brake resistor		Ω	15	7.5		
Max. shielded motor cable length						
without EMC category		m	100			
Category C1 (≤ 8 kHz)		m	-			
Category C2 (≤ 8 kHz)		m	20			
Category C3 (≤ 8 kHz)		m	35			
Max. Unshielded motor cable length						
without EMC category		m	200			

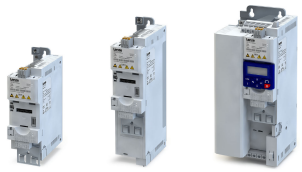
Technical data

3-phase mains connection 480 V
Rated data



Inverter			i550-C45/400-3	i550-C55/400-3	i550-C75/400-3	i550-C90/400-3
Rated power	**P_{rated}**	**kW**	**45**	**55**	**75**	**90**
Rated power	**P_{rated}**	**hp**	**60**	**75**	**100**	**125**
Mains voltage range			3/PE AC 432 V ... 528 V, 45 Hz ... 65 Hz			
Output voltage			3 AC 0 - 400/480 V			
Rated mains current						
without mains choke		A	-			
with mains choke		A	66.7	83	113	146
Apparent output power		kVA	60	75	100	121
Rated output current						
2 kHz		A	77	96	124	156
4 kHz		A	77	96	124	156
8 kHz		A	77	96	124	140
16 kHz		A	51.3	63.9	83.1	93.6
Power loss						
2 kHz		W	920	1137	1539	1841
4 kHz		W	980	1210	1640	1961
8 kHz		W	1280	1580	2140	2312
16 kHz		W	1278	1579	2143	2312
Overcurrent cycle 180 s						
Max. output current (≤ 8 kHz)		A	116	144	186	234
Overload time	T_1	s	60	60	60	60
Recovery time	T_2	s	120	120	120	120
Max. output current during the recovery time		A	58	72	93	117
Overcurrent cycle 15 s						
Max. output current (≤ 8 kHz)		A	154	192	248	312
Overload time	T_1	s	3	3	3	3
Recovery time	T_2	s	12	12	12	12
Max. output current during the recovery time		A	58	72	93	117
Cyclic mains switching			3 times per minute	Once per minute		
Brake chopper						
Max. output current		A	97	154	166	275
Min. Brake resistor		Ω	7.5	4.7		2.3
Max. shielded motor cable length						
without EMC category		m	100	200		
Category C1 (≤ 8 kHz)		m	-			
Category C2 (≤ 8 kHz)		m	20			
Category C3 (≤ 8 kHz)		m	35	100		
Max. Unshielded motor cable length						
without EMC category		m	200	300		

Inverter			**i550-C110/400-3**
Rated power	**P_{rated}**	**kW**	**110**
Rated power	**P_{rated}**	**hp**	**150**
Mains voltage range			3/PE AC 432 V ... 528 V, 45 Hz ... 65 Hz
Output voltage			3 AC 0 - 400/480 V
Rated mains current			
without mains choke		A	-
with mains choke		A	168
Apparent output power		kVA	142
Rated output current			
2 kHz		A	180
4 kHz		A	180
8 kHz		A	162
16 kHz		A	108
Power loss			
2 kHz		W	2163
4 kHz		W	2305
8 kHz		W	2717
16 kHz		W	2717
Overcurrent cycle 180 s			
Max. output current (≤ 8 kHz)		A	270
Overload time	T_1	s	60
Recovery time	T_2	s	120
Max. output current during the recovery time		A	135
Overcurrent cycle 15 s			
Max. output current (≤ 8 kHz)		A	360
Overload time	T_1	s	3
Recovery time	T_2	s	12
Max. output current during the recovery time		A	135
Cyclic mains switching			Once per minute
Brake chopper			
Max. output current		A	275
Min. Brake resistor		Ω	2.3
Max. shielded motor cable length			
without EMC category		m	200
Category C1 (≤ 8 kHz)		m	-
Category C2 (≤ 8 kHz)		m	100
Category C3 (≤ 8 kHz)		m	100
Max. Unshielded motor cable length			
without EMC category		m	300



Fusing data (EN 60204-1)

A residual current device (RCD) is optional.

Fusing data for UL/NEC compliant installations: ▸ Fusing data 55

Inverter	Fuse			Circuit breaker			RCD	
	Max. SCCR	Characteristic	Max. rated current	Max. SCCR	Characteristic	Max. rated current		Type
	kA		A	kA		A	mA	
i550-C0.37/400-3	65	gG/gL, gRL	16	65	B, C	16	≥ 30	Typ B
i550-C0.55/400-3	65	gG/gL, gRL	16	65	B, C	16	≥ 30	Typ B
i550-C0.75/400-3	65	gG/gL, gRL	16	65	B, C	16	≥ 30	Typ B
i550-C1.1/400-3	65	gG/gL, gRL	16	65	B, C	16	≥ 30	Typ B
i550-C1.5/400-3	65	gG/gL, gRL	16	65	B, C	16	≥ 30	Typ B
i550-C2.2/400-3	65	gG/gL, gRL	16	65	B, C	16	≥ 30	Typ B
i550-C3.0/400-3	65	gG/gL, gRL	35	65	B, C	25	≥ 30	Typ B
i550-C4.0/400-3	65	gG/gL, gRL	35	65	B, C	25	≥ 30	Typ B
i550-C5.5/400-3	65	gG/gL, gRL	25	65	B, C	25	≥ 300	Typ B
i550-C7.5/400-3	65	gG/gL, gRL	40	65	B, C	40	≥ 30	Typ B
i550-C11/400-3	65	gG/gL, gRL	40	65	B, C	40	≥ 30	Typ B
i550-C15/400-3	65	gG/gL, gRL	90	65	B, C	90	≥ 300	Typ B
i550-C18/400-3	65	gG/gL, gRL	90	65	B, C	90	≥ 300	Typ B
i550-C22/400-3	65	gG/gL, gRL	90	65	B, C	90	≥ 300	Typ B
i550-C30/400-3	65	gG/gL, gRL	90	65	B, C	90	≥ 300	Typ B
i550-C37/400-3	22	gG/gL, gRL	125	35	B, C	125	≥ 300	Typ B
i550-C45/400-3	22	gG/gL, gRL	125	35	B, C	125	≥ 300	Typ B
i550-C55/400-3	22	gR	200	35	B, C	200	≥ 300	Typ B
i550-C75/400-3	22	gR	200	35	B, C	200	≥ 300	Typ B
i550-C90/400-3	22	gR	300	10	B, C	300	≥ 300	Typ B
i550-C110/400-3	22	gR	300	10	B, C	300	≥ 300	Typ B

Please note that from 37 kW onwards a mains choke must always be used.

Connection data

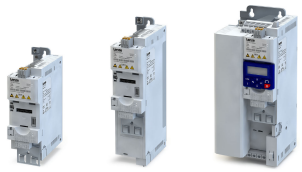
Rated power	P_{rated}	kW	0.37 ... 2.2	3 ... 4	5.5	7.5 ... 11	15 ... 30	37 ... 45	55 ... 75	90 ... 110
Connection description			**Mains connection**							
Connection			**X100**							
Connection type			Pluggable		Non-pluggable					
Max. Cable cross-section		mm²	2.5	4	6	16	35	50	95	150
Max. Cable cross-section		AWG	12	10	10	6	2	1/0	4/0	-
Stripping length		mm	8	8	9	11	18	22	32	41
Stripping length		in	0.3	0.3	0.35	0.43	0.7	0.87	1.26	1.6
Tightening torque		Nm	0.5	0.6	0.5	1.2	3.8	4	10	18
Tightening torque		lb-in	4.4	5.3	4.4	11	34	35	89	160
Required tool			Screwdriver 0.5 x 3.0		Screwdriver 0.6 x 3.5	Screwdriver 0.8 x 4.0	Screwdriver 0.8 x 5.5	Hex key 5.0	Hex key 6.0	Hex key 8.0

Rated power	P_{rated}	kW	0.37 ... 5.5	7.5 ... 11	15 ... 30	37 ... 75	90 ... 110
Connection description			**PE connection**				
Terminal type			**Schraube**				**Bolzen**
Max. Cable cross-section		mm²	6	16	25	35	150
Max. Cable cross-section		AWG	10	6	4	2	300 kcmil
Stripping length		mm	10	11	16	16	-
Stripping length		in	0.4	0.4	0.6	0.6	-
Tightening torque		Nm	2	3.4	4	4	10
Tightening torque		lb-in	18	30	35	35	89
Required tool			Torx key 20	Crosstip screwdriver PZ2			Wrench size 13

Rated power	P_{rated}	kW	0.37 ... 4	5.5	7.5 ... 11	15 ... 30	37 ... 45	55 ... 75	90 ... 110
Connection description			**Motor connection**						
Connection			**X105**						
Connection type			Pluggable	Non-pluggable					
Max. Cable cross-section		mm²	2.5	6	16	35	50	95	150
Max. Cable cross-section		AWG	12	10	6	2	1/0	4/0	-
Stripping length		mm	8	9	11	18	22	32	41
Stripping length		in	0.3	0.35	0.43	0.7	0.87	1.26	1.6
Tightening torque		Nm	0.5	0.5	1.2	3.8	4	10	18
Tightening torque		lb-in	4.4	4.4	11	34	35	89	160
Required tool			Screwdriver 0.5 x 3.0	Screwdriver 0.6 x 3.5	Screwdriver 0.8 x 4.0	Screwdriver 0.8 x 5.5	Hex key 5.0	Hex key 6.0	Hex key 8.0

The connection data for the terminal X1 can be found under: ▸ Connection data 📖 79

Technical data
3-phase mains connection 480 V
Brake resistors

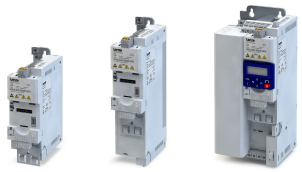


Brake resistors

Inverter	Brake resistor					
	Order code	Rated resistance	Rated power	Thermal capacity	Dimensions (H x W x D)	Weight
		Ω	W	kWs	mm	kg
i550-C0.37/400-3	ERBM470R020W	470	20	3	160 x 40 x 36	0.34
i550-C0.37/400-3	ERBM390R100W	390	100	15	235 x 20.6 x 40	0.37
i550-C0.55/400-3	ERBM390R100W	390	100	15	235 x 20.6 x 40	0.37
i550-C0.75/400-3	ERBM390R100W	390	100	15	235 x 20.6 x 40	0.37
i550-C1.1/400-3	ERBP180R200W	180	200	30	240 x 42 x 122	1.0
i550-C1.1/400-3	ERBP180R300W	180	300	45	320 x 42 x 122	1.4
i550-C1.5/400-3	ERBP180R200W	180	200	30	240 x 42 x 122	1.0
i550-C1.5/400-3	ERBS180R350WNQN000	180	350	53	382 x 124 x 122	2.1
i550-C2.2/400-3	ERBP180R200W	180	200	30	240 x 42 x 122	1.0
i550-C2.2/400-3	ERBP180R300W	180	300	45	320 x 42 x 122	1.4
i550-C2.2/400-3	ERBS180R350WNQN000	180	350	53	382 x 124 x 122	2.1
i550-C5.5/400-3	ERBP047R200W	47	200	30	240 x 42 x 122	1.0
i550-C5.5/400-3	ERBS047R400W	47	400	60	400 x 114 x 105	2.3
i550-C5.5/400-3	ERBS047R800W	47	800	120	710 x 114 x 105	4.0
i550-C37/400-3	ERBG075D01K9	7.5	1900	285	302 x 486 x 236	9.5
i550-C45/400-3	ERBG075D01K9	7.5	1900	285	302 x 486 x 236	9.5
i550-C55/400-3	ERBG005R02K6	5	2600	390	302 x 486 x 326	11.0
i550-C75/400-3	ERBG005R02K6	5	2600	390	302 x 486 x 326	11.0
i550-C90/400-3	ERBG028D04K1	2.8	4100	615	302 x 486 x 426	12.8
i550-C110/400-3	ERBG028D04K1	2.8	4100	615	302 x 486 x 426	12.8
i550-C3.0/400-3	ERBM082R150W	82	150	22.5	238 x 80 x 59	0.70
i550-C3.0/400-3	ERBP082R200W	82	200	30	240 x 42 x 122	1.0
i550-C3.0/400-3	ERBS082R780WNQN000	82	780	117	666 x 124 x 122	3.6
i550-C4.0/400-3	ERBM047R135W	47	135	6.3	216 x 80 x 28	0.67
i550-C4.0/400-3	ERBS047R400W	47	400	60	400 x 114 x 105	2.3
i550-C4.0/400-3	ERBS047R800W	47	800	120	710 x 114 x 105	4.0
i550-C7.5/400-3	ERBP027R200W	27	200	30	240 x 42 x 122	1.0
i550-C7.5/400-3	ERBS027R600W	27	600	90	550 x 114 x 105	3.1
i550-C7.5/400-3	ERBS027R01K4	27	1400	210	1110 x 114 x 105	6.3
i550-C11/400-3	ERBS027R600W	27	600	90	550 x 114 x 105	3.1
i550-C11/400-3	ERBS027R01K2	27	1200	180	1020 x 114 x 105	5.6
i550-C11/400-3	ERBS027R01K4	27	1400	210	1110 x 114 x 105	6.3
i550-C15/400-3	ERBP018R300W	18	300	45	320 x 42 x 122	1.4
i550-C15/400-3	ERBS018R01K4	18	1400	210	1110 x 114 x 105	6.3
i550-C15/400-3	ERBG018R04K3	18	4300	645	302 x 486 x 426	13.5
i550-C18/400-3	ERBS015R800W	15	800	120	710 x 114 x 105	4.0
i550-C18/400-3	ERBS015R02K4	15	2400	360	1020 x 204 x 105	10
i550-C18/400-3	ERBG015R06K2	15	6200	930	302 x 486 x 526	17.0
i550-C22/400-3	ERBS015R800W	15	800	120	710 x 114 x 105	4.0
i550-C22/400-3	ERBS015R02K4	15	2400	360	1020 x 204 x 105	10
i550-C22/400-3	ERBG015R06K2	15	6200	930	302 x 486 x 526	17.0
i550-C30/400-3	ERBG075D01K9	7.5	1900	285	302 x 486 x 236	9.5

Mains chokes

Inverter	Netzdrossel					
	Order code	No. of phases	Rated current	Inductance	Dimensions (H x W x D)	Weight
			A	mH	mm	kg
i550-C0.37/400-3	EZAELN3002B203	3	1.5	19.6	56 x 77 x 100	0.52
i550-C0.55/400-3	EZAELN3002B153		2	14.7		0.53
i550-C0.75/400-3	EZAELN3004B742		4	7.35	60 x 95 x 117	1.31
i550-C1.1/400-3						
i550-C1.5/400-3						
i550-C2.2/400-3	EZAELN3006B492		6	4.9	69 x 95 x 117	1.45
i550-C3.0/400-3						
i550-C4.0/400-3	EZAELN3008B372		8	3.68	85 x 120 x 140	1.9
i550-C5.5/400-3	EZAELN3016B182		16	1.84	95 x 120 x 140	2.7
i550-C7.5/400-3						
i550-C11/400-3	EZAELN3020B152		20	1.47	95 x 155 x 165	3.8
i550-C15/400-3	EZAELN3025B122		25	1.18	110 x 155 x 170	5.8
i550-C18/400-3	EZAELN3030B981		30	0.98	111 x 155 x 170	5.85
i550-C22/400-3	EZAELN3040B741		40	0.74	102 x 185 x 195	6.8
i550-C30/400-3	EZAELN3050B591		50	0.59	112 x 185 x 210	8.35
i550-C37/400-3	EZAELN3063B471		63	0.47	122 x 185 x 210	9.65
i550-C45/400-3	EZAELN3080B371		80	0.37	125 x 210 x 240	12.5
i550-C55/400-3	EZAELN3090B331		90	0.33	130 x 267 x 205	10.95
i550-C75/400-3	EZAELN3125B241		125	0.24	160 x 291 x 215	17.1
i550-C90/400-3	EZAELN3160B191		160	0.19	189 x 291 x 215	22.1
i550-C110/400-3	EZAELN3180B171		180	0.17	184 x 316 x 235	25



RFI filters / Mains filters

Basic information on RFI filters, mains filters and EMC: from 📖 223

EMC filters can be used both in the side structure and in the substructure.

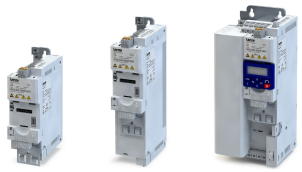
Maximum motor cable lengths with residual current device (RCD)

Mains connection			3-phase, 400 V/480 V			
Inverter			i550-C0.37/400-3	i550-C0.55/400-3 i550-C0.75/400-3	i550-C1.1/400-3 i550-C1.5/400-3 i550-C2.2/400-3 i550-C3.0/400-3 i550-C4.0/400-3	i550-C5.5/400-3
Without RFI filter						
Without EMC category Thermal limitation	Max. Shielded motor cable length	m	15	50	50	100
	Max. Unshielded motor cable length	m	40	80	100	200
With integrated RFI filter						
Category C1	Max. Shielded motor cable length	m	3	3	3 (only 1.1 ... 2.2 kW)	-
Category C2		m	15	20	20	20
	RCD (optional)	mA	30	30	30	300
RFI filter Low Leakage						
Category C1	Max. Shielded motor cable length	m	-	-	-	-
	RCD (optional)	mA	-	-	-	-
RFI filter Short Distance						
Category C1	Max. Shielded motor cable length	m	15	25	25	25
Category C2		m	15	50	50	50
	RCD (optional)	mA	30	30	30	30
RFI filter Long Distance						
Category C1	Max. Shielded motor cable length	m	15	50	50	50
Category C2		m	15	50	50	100
	RCD (optional)	mA	300	300	300	300

Mains connection			3-phase, 400 V/480 V			
Inverter			i550-C7.5/400-3 i550-C11/400-3	i550-C15/400-3 i550-C18/400-3 i550-C22/400-3	i550-C30/400-3 i550-C37/400-3 i550-C45/400-3	i550-C55/400-3 i550-C75/400-3 i550-C90/400-3 i550-C110/400-3
Without RFI filter						
Without EMC category Thermal limitation	Max. Shielded motor cable length	m	100	100	100	200
	Max. Unshielded motor cable length	m	200	200	200	300
With integrated RFI filter						
Category C1	Max. Shielded motor cable length	m	-	-	-	-
Category C2		m	20	20	20	20
	RCD (optional)	mA	300	300	300	300
RFI filter Low Leakage						
Category C1	Max. Shielded motor cable length	m	-	-	-	-
	RCD (optional)	mA	-	-	-	-
RFI filter Short Distance						
Category C1	Max. Shielded motor cable length	m	25	-	-	-
Category C2		m	50	-	-	-
	RCD (optional)	mA	30	-	-	-
RFI filter Long Distance						
Category C1	Max. Shielded motor cable length	m	50	50	50	50
Category C2		m	100	100	100	100
	RCD (optional)	mA	300	300	300	300

From i550-C22/400-3, long distance mains filters are used. Mains filters are a combination of mains choke and RFI filter.

Technical data
3-phase mains connection 480 V
RFI filters / Mains filters

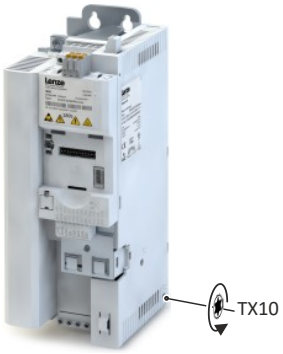


Short distance filter

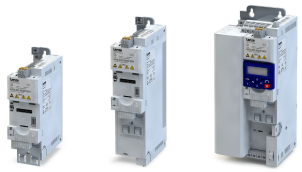
Inverter	Filter				Max. shielded motor cable length					
	Order code	Rated current	Dimensions (H x W x D)	Weight	C1		C2		C3	
		A	mm	kg	m	kHz	m	kHz		
i550-C0.37/400-3	I0FAE175F100S0000S	3.3	276 x 60 x 50	0.82	15	4	15	4	-	-
i550-C0.37/400-3	I0FAE175F100S0000S	3.3	276 x 60 x 50	0.82	15	8	15	8	-	-
i550-C0.37/400-3	I0FAE175F100S0000S	3.3	276 x 60 x 50	0.82	15	16	15	16	-	-
i550-C0.55/400-3	I0FAE175F100S0000S	3.3	276 x 60 x 50	0.82	25	2	50	2	-	-
i550-C0.55/400-3	I0FAE175F100S0000S	3.3	276 x 60 x 50	0.82	25	4	50	4	-	-
i550-C0.55/400-3	I0FAE175F100S0000S	3.3	276 x 60 x 50	0.82	25	8	50	8	-	-
i550-C0.55/400-3	I0FAE175F100S0000S	3.3	276 x 60 x 50	0.82	25	16	50	16	-	-
i550-C0.75/400-3	I0FAE175F100S0000S	3.3	276 x 60 x 50	0.82	25	2	50	2	-	-
i550-C0.75/400-3	I0FAE175F100S0000S	3.3	276 x 60 x 50	0.82	25	4	50	4	-	-
i550-C0.75/400-3	I0FAE175F100S0000S	3.3	276 x 60 x 50	0.82	25	8	50	8	-	-
i550-C0.75/400-3	I0FAE175F100S0000S	3.3	276 x 60 x 50	0.82	25	16	50	16	-	-
i550-C1.1/400-3	I0FAE222F100S0000S	7.8	346 x 60 x 50	1.01	25	2	50	2	-	-
i550-C1.1/400-3	I0FAE222F100S0000S	7.8	346 x 60 x 50	1.01	25	4	50	4	-	-
i550-C1.1/400-3	I0FAE222F100S0000S	7.8	346 x 60 x 50	1.01	25	8	50	8	-	-
i550-C1.1/400-3	I0FAE222F100S0000S	7.8	346 x 60 x 50	1.01	25	16	50	16	-	-
i550-C1.5/400-3	I0FAE222F100S0000S	7.8	346 x 60 x 50	1.01	25	2	50	2	-	-
i550-C1.5/400-3	I0FAE222F100S0000S	7.8	346 x 60 x 50	1.01	25	4	50	4	-	-
i550-C1.5/400-3	I0FAE222F100S0000S	7.8	346 x 60 x 50	1.01	25	8	50	8	-	-
i550-C1.5/400-3	I0FAE222F100S0000S	7.8	346 x 60 x 50	1.01	25	16	50	16	-	-
i550-C2.2/400-3	I0FAE222F100S0000S	7.8	346 x 60 x 50	1.01	25	2	50	2	-	-
i550-C2.2/400-3	I0FAE222F100S0000S	7.8	346 x 60 x 50	1.01	25	4	50	4	-	-
i550-C2.2/400-3	I0FAE222F100S0000S	7.8	346 x 60 x 50	1.01	25	8	50	8	-	-
i550-C2.2/400-3	I0FAE222F100S0000S	7.8	346 x 60 x 50	1.01	25	16	50	16	-	-
i550-C3.0/400-3	I0FAE240F100S0001S	14	346 x 60 x 50	1.42	25	2	50	2	-	-
i550-C3.0/400-3	I0FAE240F100S0001S	14	346 x 60 x 50	1.42	25	4	50	4	-	-
i550-C3.0/400-3	I0FAE240F100S0001S	14	346 x 60 x 50	1.42	25	8	50	8	-	-
i550-C3.0/400-3	I0FAE240F100S0001S	14	346 x 60 x 50	1.42	25	16	50	16	-	-
i550-C4.0/400-3	I0FAE240F100S0001S	14	346 x 60 x 50	1.42	25	2	50	2	-	-
i550-C4.0/400-3	I0FAE240F100S0001S	14	346 x 60 x 50	1.42	25	4	50	4	-	-
i550-C4.0/400-3	I0FAE240F100S0001S	14	346 x 60 x 50	1.42	25	8	50	8	-	-
i550-C4.0/400-3	I0FAE240F100S0001S	14	346 x 60 x 50	1.42	25	16	50	16	-	-
i550-C5.5/400-3	I0FAE255F100S0001S	18.3	346 x 90 x 60	2.05	25	4	50	4	-	-
i550-C5.5/400-3	I0FAE255F100S0001S	18.3	346 x 90 x 60	2.05	25	8	50	8	-	-
i550-C7.5/400-3	I0FAE311F100S0000S	29	371 x 120 x 60	2.35	25	4	50	4	-	-
i550-C7.5/400-3	I0FAE311F100S0000S	29	371 x 120 x 60	2.35	25	8	50	8	-	-
i550-C11/400-3	I0FAE311F100S0000S	29	371 x 120 x 60	2.35	25	4	50	4	-	-
i550-C11/400-3	I0FAE311F100S0000S	29	371 x 120 x 60	2.35	25	8	50	8	-	-

In order to meet the EMC requirements according to EN IEC 61800-3, the lower of the screws marked “IT” on the product must be removed when using the filters listed below.

Filters: I0FAE240F100S0001S
I0FAE255F100S0001S
I0FAE311F100S0000S

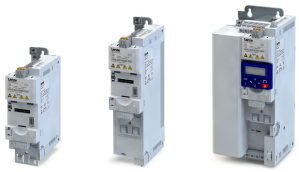


Technical data
3-phase mains connection 480 V
RFI filters / Mains filters



Long Distance filter

Inverter	Filter				Max. shielded motor cable length					
	Order code	Rated current	Dimensions (H x W x D)	Weight	C1		C2		C3	
		A	mm	kg	m	kHz	m	kHz		
i550-C0.37/400-3	I0FAE175F100D0000S	3.3	276 x 60 x 50	0.86	15	4	15	4	-	-
i550-C0.37/400-3	I0FAE175F100D0000S	3.3	276 x 60 x 50	0.86	15	8	15	8	-	-
i550-C0.55/400-3	I0FAE175F100D0000S	3.3	276 x 60 x 50	0.86	50	4	50	4	-	-
i550-C0.55/400-3	I0FAE175F100D0000S	3.3	276 x 60 x 50	0.86	50	8	50	8	-	-
i550-C0.75/400-3	I0FAE175F100D0000S	3.3	276 x 60 x 50	0.86	50	4	50	4	-	-
i550-C0.75/400-3	I0FAE175F100D0000S	3.3	276 x 60 x 50	0.86	50	8	50	8	-	-
i550-C1.1/400-3	I0FAE222F100D0000S	7.8	346 x 60 x 50	1.03	50	4	50	4	-	-
i550-C1.1/400-3	I0FAE222F100D0000S	7.8	346 x 60 x 50	1.03	50	8	50	8	-	-
i550-C1.5/400-3	I0FAE222F100D0000S	7.8	346 x 60 x 50	1.03	50	4	50	4	-	-
i550-C1.5/400-3	I0FAE222F100D0000S	7.8	346 x 60 x 50	1.03	50	8	50	8	-	-
i550-C2.2/400-3	I0FAE222F100D0000S	7.8	346 x 60 x 50	1.03	50	4	50	4	-	-
i550-C2.2/400-3	I0FAE222F100D0000S	7.8	346 x 60 x 50	1.03	50	8	50	8	-	-
i550-C3.0/400-3	I0FAE240F100D0001S	14	346 x 60 x 50	1.42	50	4	50	4	-	-
i550-C3.0/400-3	I0FAE240F100D0001S	14	346 x 60 x 50	1.42	50	8	50	8	-	-
i550-C4.0/400-3	I0FAE240F100D0001S	14	346 x 60 x 50	1.42	50	4	50	4	-	-
i550-C4.0/400-3	I0FAE240F100D0001S	14	346 x 60 x 50	1.42	50	8	50	8	-	-
i550-C5.5/400-3	I0FAE255F100D0001S	18.3	346 x 90 x 60	1.65	50	4	100	4	-	-
i550-C5.5/400-3	I0FAE255F100D0001S	18.3	346 x 90 x 60	1.65	50	8	100	8	-	-
i550-C7.5/400-3	I0FAE311F100D0000S	29	371 x 120 x 60	2.05	50	4	100	4	-	-
i550-C7.5/400-3	I0FAE311F100D0000S	29	371 x 120 x 60	2.05	50	8	100	8	-	-
i550-C11/400-3	I0FAE311F100D0000S	29	371 x 120 x 60	2.05	50	4	100	4	-	-
i550-C11/400-3	I0FAE311F100D0000S	29	371 x 120 x 60	2.05	50	8	100	8	-	-
i550-C15/400-3	I0FAE330F100D0001S	69	465 x 180 x 106	9.4	50	4	100	4	-	-
i550-C15/400-3	I0FAE330F100D0001S	69	465 x 180 x 106	9.4	50	8	100	8	-	-
i550-C18/400-3	I0FAE330F100D0001S	69	465 x 180 x 106	9.4	50	4	100	4	-	-
i550-C18/400-3	I0FAE330F100D0001S	69	465 x 180 x 106	9.4	50	8	100	8	-	-
i550-C22/400-3	I0FAE330F100D0001S	69	465 x 180 x 106	9.4	50	4	100	4	-	-
i550-C22/400-3	I0FAE330F100D0001S	69	465 x 180 x 106	9.4	50	8	100	8	-	-
i550-C30/400-3	I0FAE330F100D0001S	69	465 x 180 x 106	9.4	50	4	100	4	-	-
i550-C30/400-3	I0FAE330F100D0001S	69	465 x 180 x 106	9.4	50	8	100	8	-	-
i550-C37/400-3	I0FAE337F100D0000S	69	590 x 250 x 105	25	50	4	100	4	-	-
i550-C37/400-3	I0FAE337F100D0000S	69	590 x 250 x 105	25	50	8	100	8	-	-
i550-C45/400-3	I0FAE345F100D0001S	100	590 x 250 x 105	32	50	2	100	2	-	-
i550-C45/400-3	I0FAE345F100D0001S	100	590 x 250 x 105	32	50	4	100	4	-	-
i550-C55/400-3	I0FAE355F100D0001S	120	700 x 250 x 105	36	50	4	100	4	-	-
i550-C55/400-3	I0FAE355F100D0001S	120	700 x 250 x 105	36	50	8	100	8	-	-
i550-C75/400-3	I0FAE375F100D0001S	162	700 x 250 x 105	41.5	50	4	100	4	-	-
i550-C75/400-3	I0FAE375F100D0001S	162	700 x 250 x 105	41.5	50	8	100	8	-	-
i550-C90/400-3	I0FAE411F100D0001S	234	855 x 250 x 130	63	-	-	100	4	-	-
i550-C90/400-3	I0FAE411F100D0001S	234	855 x 250 x 130	63	-	-	100	8	-	-
i550-C110/400-3	I0FAE411F100D0001S	234	855 x 250 x 130	63	-	-	100	4	-	-
i550-C110/400-3	I0FAE411F100D0001S	234	855 x 250 x 130	63	-	-	100	8	-	-



3-phase mains connection 480 V "Light Duty"

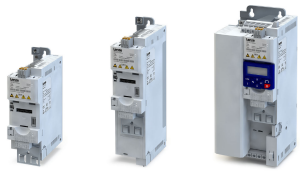
Rated data

The output currents apply to these operating conditions:

- At a switching frequency of 2 kHz or 4 kHz: Ambient temperature above 40 °C with a rated output current reduced by 2.5 %/°C.
- If the load characteristic "Light Duty" and the switching frequencies 8 kHz or 16 kHz are selected, only the values of the load characteristic "Heavy Duty" are reached.

Technical data

3-phase mains connection 480 V "Light Duty"
Rated data

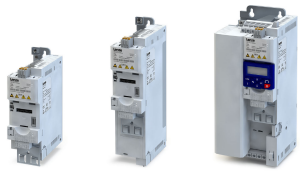


Inverter			i550-C3.0/400-3	i550-C4.0/400-3	i550-C5.5/400-3	i550-C7.5/400-3
Rated power	**P_{rated}**	**kW**	**4**	**5.5**	**7.5**	**11**
Rated power	**P_{rated}**	**hp**	**5**	**7.5**	**10**	**15**
Mains voltage range			3/PE AC 432 V ... 528 V, 45 Hz ... 65 Hz			
Output voltage			3 AC 0 - 400/480 V			
Rated mains current						
without mains choke		A	8.6	11.2	15.3	22
with mains choke		A	6.8	8.8	12.1	17.2
Apparent output power		kVA	5.9	8	10.5	15
Rated output current						
2 kHz		A	7.6	9.8	13.2	18.3
4 kHz		A	7.6	9.8	13.2	18.3
8 kHz		A	-			
16 kHz		A	-			
Power loss						
2 kHz		W	94	125	163	235
4 kHz		W	100	133	173	242
8 kHz		W	-			
16 kHz		W	-			
Overcurrent cycle 180 s						
Max. output current (≤ 8 kHz)		A	9.5	12.3	16.5	21
Overload time	T_1	s	60	60	60	60
Recovery time	T_2	s	120	120	120	120
Max. output current during the recovery time		A	4.7	6.2	8.3	10.5
Overcurrent cycle 15 s						
Max. output current (≤ 8 kHz)		A	12.6	16.4	22	28
Overload time	T_1	s	3	3	3	3
Recovery time	T_2	s	12	12	12	12
Max. output current during the recovery time		A	4.7	6.2	8.3	10.5
Cyclic mains switching			3 times per minute			
Brake chopper						
Max. output current		A	8.8	15.4	16.6	27
Min. Brake resistor		Ω	82	47		27
Max. shielded motor cable length						
without EMC category		m	50		100	
Category C1 (≤ 8 kHz)		m	-			
Category C2 (≤ 8 kHz)		m	20			
Category C3 (≤ 8 kHz)		m	35			50
Max. Unshielded motor cable length						
without EMC category		m	100		200	

Inverter			i550-C11/400-3	i550-C15/400-3	i550-C15/400-3	i550-C18/400-3
Rated power	P_{rated}	**kW**	**15**	**18.5**		**22**
Rated power	P_{rated}	**hp**	**20**	**25**		**30**
Mains voltage range			3/PE AC 432 V ... 528 V, 45 Hz ... 65 Hz			
Output voltage			3 AC 0 - 400/480 V			
Rated mains current						
without mains choke		A	-	40		-
with mains choke		A	22.6	30		38
Apparent output power		kVA	19	26		32
Rated output current						
2 kHz		A	25.2	32.4		40.8
4 kHz		A	25.2	32.4		40.8
8 kHz		A	-			
16 kHz		A	-			
Power loss						
2 kHz		W	329	404	395	501
4 kHz		W	340	430	408	533
8 kHz		W	-			
16 kHz		W	-			
Overcurrent cycle 180 s						
Max. output current (≤ 8 kHz)		A	31.5	40.5	40.5	51
Overload time	T_1	s	60	60	60	60
Recovery time	T_2	s	120	120	120	120
Max. output current during the recovery time		A	15.8	20.3	20.3	25.5
Overcurrent cycle 15 s						
Max. output current (≤ 8 kHz)		A	42	54	54	68
Overload time	T_1	s	3	3	3	3
Recovery time	T_2	s	12	12	12	12
Max. output current during the recovery time		A	15.8	20.3	20.3	25.5
Cyclic mains switching			3 times per minute			
Brake chopper						
Max. output current		A	27	40	43	52
Min. Brake resistor		Ω	27	18		15
Max. shielded motor cable length						
without EMC category		m	100			
Category C1 (≤ 8 kHz)		m	-			
Category C2 (≤ 8 kHz)		m	20			
Category C3 (≤ 8 kHz)		m	50	35		
Max. Unshielded motor cable length						
without EMC category		m	200			

Technical data

3-phase mains connection 480 V "Light Duty"
Rated data

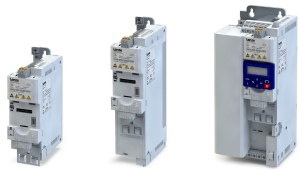


Inverter			i550-C18/400-3	i550-C22/400-3	i550-C22/400-3	i550-C30/400-3
Rated power	**P_{rated}**	**kW**	**22**	**30**		**37**
Rated power	**P_{rated}**	**hp**	**30**	**40**		**50**
Mains voltage range			3/PE AC 432 V ... 528 V, 45 Hz ... 65 Hz			
Output voltage			3 AC 0 - 400/480 V			
Rated mains current						
without mains choke		A	46.3	-	55	-
with mains choke		A	38	46		59
Apparent output power		kVA	32	38		49
Rated output current						
2 kHz		A	40.8	48.5		62.4
4 kHz		A	40.8	48.5		62.4
8 kHz		A	-			
16 kHz		A	-			
Power loss						
2 kHz		W	463	585	599	761
4 kHz		W	479	623	620	810
8 kHz		W	-			
16 kHz		W	-			
Overcurrent cycle 180 s						
Max. output current (≤ 8 kHz)		A	51	61	61	78
Overload time	T_1	s	60	60	60	60
Recovery time	T_2	s	120	120	120	120
Max. output current during the recovery time		A	25.5	30	30	39
Overcurrent cycle 15 s						
Max. output current (≤ 8 kHz)		A	68	81	81	104
Overload time	T_1	s	3	3	3	3
Recovery time	T_2	s	12	12	12	12
Max. output current during the recovery time		A	25.5	30	30	39
Cyclic mains switching			3 times per minute			
Brake chopper						
Max. output current		A	48		52	97
Min. Brake resistor		Ω	15			7.5
Max. shielded motor cable length						
without EMC category		m	100			
Category C1 (≤ 8 kHz)		m	-			
Category C2 (≤ 8 kHz)		m	20			
Category C3 (≤ 8 kHz)		m	35			
Max. Unshielded motor cable length						
without EMC category		m	200			

Inverter			i550-C37/400-3	i550-C45/400-3	i550-C55/400-3	i550-C75/400-3
Rated power	P_{rated}	**kW**	**45**	**55**	**75**	**90**
Rated power	P_{rated}	**hp**	**60**	**75**	**100**	**125**
Mains voltage range			3/PE AC 432 V ... 528 V, 45 Hz ... 65 Hz			
Output voltage			3 AC 0 - 400/480 V			
Rated mains current						
without mains choke		A	-			
with mains choke		A	73	86	105	135
Apparent output power		kVA	61	72	89	121
Rated output current						
2 kHz		A	78	92.4	115	149
4 kHz		A	78	92.4	115	149
8 kHz		A	-			
16 kHz		A	-			
Power loss						
2 kHz		W	942	1101	1358	1841
4 kHz		W	1004	1171	1446	1961
8 kHz		W	-			
16 kHz		W	-			
Overcurrent cycle 180 s						
Max. output current (≤ 8 kHz)		A	98	116	144	186
Overload time	T_1	s	60	60	60	60
Recovery time	T_2	s	120	120	120	120
Max. output current during the recovery time		A	49	58	72	93
Overcurrent cycle 15 s						
Max. output current (≤ 8 kHz)		A	130	154	192	248
Overload time	T_1	s	3	3	3	3
Recovery time	T_2	s	12	12	12	12
Max. output current during the recovery time		A	49	58	72	93
Cyclic mains switching			3 times per minute		Once per minute	
Brake chopper						
Max. output current		A	97		154	166
Min. Brake resistor		Ω	7.5		4.7	
Max. shielded motor cable length						
without EMC category		m	100		200	
Category C1 (≤ 8 kHz)		m	-			
Category C2 (≤ 8 kHz)		m	20			
Category C3 (≤ 8 kHz)		m	35		100	
Max. Unshielded motor cable length						
without EMC category		m	200		300	

Technical data

3-phase mains connection 480 V "Light Duty"
Rated data



Inverter			i550-C90/400-3	i550-C110/400-3
Rated power	**P_{rated}**	**kW**	**110**	**132**
Rated power	**P_{rated}**	**hp**	**150**	**175**
Mains voltage range			3/PE AC 432 V ... 528 V, 45 Hz ... 65 Hz	
Output voltage			3 AC 0 - 400/480 V	
Rated mains current				
without mains choke		A	-	
with mains choke		A	175	200
Apparent output power		kVA	145	171
Rated output current				
2 kHz		A	187	216
4 kHz		A	187	216
8 kHz		A	-	
16 kHz		A	-	
Power loss				
2 kHz		W	2203	2589
4 kHz		W	2348	2760
8 kHz		W	-	
16 kHz		W	-	
Overcurrent cycle 180 s				
Max. output current (≤ 8 kHz)		A	234	270
Overload time	T_1	s	60	60
Recovery time	T_2	s	120	120
Max. output current during the recovery time		A	117	135
Overcurrent cycle 15 s				
Max. output current (≤ 8 kHz)		A	312	360
Overload time	T_1	s	3	3
Recovery time	T_2	s	12	12
Max. output current during the recovery time		A	117	135
Cyclic mains switching			Once per minute	
Brake chopper				
Max. output current		A	275	
Min. Brake resistor		Ω	2.3	
Max. shielded motor cable length				
without EMC category		m	200	
Category C1 (≤ 8 kHz)		m	-	
Category C2 (≤ 8 kHz)		m	20	100
Category C3 (≤ 8 kHz)		m	100	
Max. Unshielded motor cable length				
without EMC category		m	300	

Fusing data (EN 60204-1)

A residual current device (RCD) is optional.

Fusing data for UL/NEC compliant installations: ▸ Fusing data 55

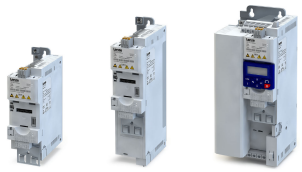
Inverter	Fuse			Circuit breaker			RCD	
	Max. SCCR	Characteristic	Max. rated current	Max. SCCR	Characteristic	Max. rated current		Type
	kA		A	kA		A	mA	
i550-C3.0/400-3	65	gG/gL, gRL	35	65	B, C	25	≥ 30	Typ B
i550-C4.0/400-3	65	gG/gL, gRL	35	65	B, C	25	≥ 30	Typ B
i550-C5.5/400-3	65	gG/gL, gRL	25	65	B, C	25	≥ 300	Typ B
i550-C7.5/400-3	65	gG/gL, gRL	40	65	B, C	40	≥ 30	Typ B
i550-C11/400-3	65	gG/gL, gRL	40	65	B, C	40	≥ 30	Typ B
i550-C15/400-3	65	gG/gL, gRL	90	65	B, C	90	≥ 300	Typ B
i550-C18/400-3	65	gG/gL, gRL	90	65	B, C	90	≥ 300	Typ B
i550-C22/400-3	65	gG/gL, gRL	90	65	B, C	90	≥ 300	Typ B
i550-C30/400-3	65	gG/gL, gRL	90	65	B, C	90	≥ 300	Typ B
i550-C37/400-3	22	gG/gL, gRL	125	35	B, C	125	≥ 300	Typ B
i550-C45/400-3	22	gG/gL, gRL	125	35	B, C	125	≥ 300	Typ B
i550-C55/400-3	22	gR	200	35	B, C	200	≥ 300	Typ B
i550-C75/400-3	22	gR	200	35	B, C	200	≥ 300	Typ B
i550-C90/400-3	22	gR	300	10	B, C	300	≥ 300	Typ B
i550-C110/400-3	22	gR	300	10	B, C	300	≥ 300	Typ B

Please note that from 37 kW onwards a mains choke must always be used.

Connection data

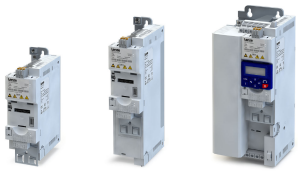
See "3-phase mains connection 480 V" ▸ Connection data 147

The connection data for the terminal X1 can be found under: ▸ Connection data 79



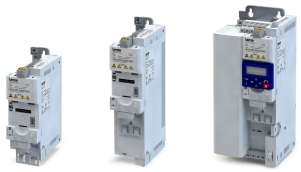
Brake resistors

Inverter	Brake resistor					
	Order code	Rated resistance	Rated power	Thermal capacity	Dimensions (H x W x D)	Weight
		Ω	W	kWs	mm	kg
i550-C5.5/400-3	ERBP047R200W	47	200	30	240 x 42 x 122	1.0
i550-C5.5/400-3	ERBS047R400W	47	400	60	400 x 114 x 105	2.3
i550-C5.5/400-3	ERBS047R800W	47	800	120	710 x 114 x 105	4.0
i550-C37/400-3	ERBG075D01K9	7.5	1900	285	302 x 486 x 236	9.5
i550-C45/400-3	ERBG075D01K9	7.5	1900	285	302 x 486 x 236	9.5
i550-C55/400-3	ERBG005R02K6	5	2600	390	302 x 486 x 326	11.0
i550-C75/400-3	ERBG005R02K6	5	2600	390	302 x 486 x 326	11.0
i550-C90/400-3	ERBG028D04K1	2.8	4100	615	302 x 486 x 426	12.8
i550-C110/400-3	ERBG028D04K1	2.8	4100	615	302 x 486 x 426	12.8
i550-C3.0/400-3	ERBM082R150W	82	150	22.5	238 x 80 x 59	0.70
i550-C3.0/400-3	ERBP082R200W	82	200	30	240 x 42 x 122	1.0
i550-C3.0/400-3	ERBS082R780WNQN000	82	780	117	666 x 124 x 122	3.6
i550-C4.0/400-3	ERBM047R135W	47	135	6.3	216 x 80 x 28	0.67
i550-C4.0/400-3	ERBS047R400W	47	400	60	400 x 114 x 105	2.3
i550-C4.0/400-3	ERBS047R800W	47	800	120	710 x 114 x 105	4.0
i550-C7.5/400-3	ERBP027R200W	27	200	30	240 x 42 x 122	1.0
i550-C7.5/400-3	ERBS027R600W	27	600	90	550 x 114 x 105	3.1
i550-C7.5/400-3	ERBS027R01K4	27	1400	210	1110 x 114 x 105	6.3
i550-C11/400-3	ERBS027R600W	27	600	90	550 x 114 x 105	3.1
i550-C11/400-3	ERBS027R01K2	27	1200	180	1020 x 114 x 105	5.6
i550-C11/400-3	ERBS027R01K4	27	1400	210	1110 x 114 x 105	6.3
i550-C15/400-3	ERBP018R300W	18	300	45	320 x 42 x 122	1.4
i550-C15/400-3	ERBS018R01K4	18	1400	210	1110 x 114 x 105	6.3
i550-C15/400-3	ERBG018R04K3	18	4300	645	302 x 486 x 426	13.5
i550-C18/400-3	ERBS015R800W	15	800	120	710 x 114 x 105	4.0
i550-C18/400-3	ERBS015R02K4	15	2400	360	1020 x 204 x 105	10
i550-C18/400-3	ERBG015R06K2	15	6200	930	302 x 486 x 526	17.0
i550-C22/400-3	ERBS015R800W	15	800	120	710 x 114 x 105	4.0
i550-C22/400-3	ERBS015R02K4	15	2400	360	1020 x 204 x 105	10
i550-C22/400-3	ERBG015R06K2	15	6200	930	302 x 486 x 526	17.0
i550-C30/400-3	ERBG075D01K9	7.5	1900	285	302 x 486 x 236	9.5



Mains chokes

Inverter	Netzdrossel					
	Order code	No. of phases	Rated current	Inductance	Dimensions (H x W x D)	Weight
			A	mH	mm	kg
i550-C3.0/400-3	EZAELN3008B372	3	8	3.68	85 x 120 x 140	1.9
i550-C4.0/400-3	EZAELN3010B292		10	2.94		2
i550-C5.5/400-3	EZAELN3016B182		16	1.84	95 x 120 x 140	2.7
i550-C7.5/400-3	EZAELN3020B152		20	1.47	95 x 155 x 165	3.8
i550-C11/400-3	EZAELN3025B122		25	1.18	110 x 155 x 170	5.8
i550-C15/400-3	EZAELN3030B981		30	0.98	111 x 155 x 170	5.85
i550-C18/400-3	EZAELN3040B741		40	0.74	102 x 185 x 195	6.8
i550-C22/400-3	EZAELN3050B591		50	0.59	112 x 185 x 210	8.35
i550-C30/400-3	EZAELN3063B471		63	0.47	122 x 185 x 210	9.65
i550-C37/400-3	EZAELN3080B371		80	0.37	125 x 210 x 240	12.5
i550-C45/400-3	EZAELN3090B331		90	0.33	130 x 267 x 205	10.95
i550-C55/400-3	EZAELN3125B241		125	0.24	160 x 291 x 215	17.1
i550-C75/400-3	EZAELN3160B191		160	0.19	189 x 291 x 215	22.1
i550-C90/400-3	EZAELN3180B171		180	0.17	184 x 316 x 235	25
i550-C110/400-3	EZAELN3200B151		200	0.15	160 x 352 x 265	



RFI filters / Mains filters

Basic information on RFI filters, mains filters and EMC: from 📖 223

EMC filters can be used both in the side structure and in the substructure.

Maximum motor cable lengths with residual current device (RCD)

Mains connection			3-phase, 400 V/480 V, Light Duty				
Inverter			i550-C3.0/400-3 i550-C4.0/400-3	i550-C5.5/400-3	i550-C7.5/400-3 i550-C11/400-3	i550-C15/400-3 i550-C18/400-3 i550-C22/400-3 i550-C30/400-3 i550-C37/400-3 i550-C45/400-3	i550-C55/400-3 i550-C75/400-3 i550-C90/400-3 i550-C110/400-3
Without RFI filter							
Without EMC category Thermal limitation	Max. motor cable length shielded	m	50	100	100	100	200
	Max. motor cable length unshielded	m	100	200	200	200	300
With integrated RFI filter							
Category C1	Max. motor cable length shielded	m	-	-	-	-	-
Category C2		m	20	20	20	20	20
	RCD (optional)	mA	30	300	300	300	300
RFI filter Low Leakage							
Category C1	Max. motor cable length shielded	m	-	-	-	-	-
	RCD (optional)	mA	-	-	-	-	-
RFI filter Short Distance							
Category C1	Max. motor cable length shielded	m	25	25	25	-	-
Category C2		m	50	50	50	-	-
	RCD (optional)	mA	30	30	30	-	-
RFI filter Long Distance							
Category C1	Max. motor cable length shielded	m	50	50	50	-	-
Category C2		m	100	100	100	-	-
	RCD (optional)	mA	300	300	300	-	-

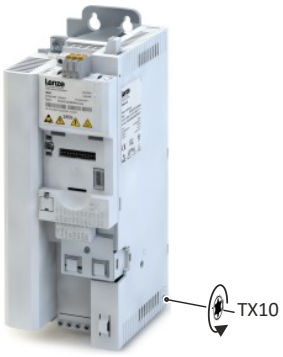
From i550-C18/400-3, long distance mains filters are used. Mains filters are a combination of mains choke and RFI filter.

Short distance filter

Inverter	Filter				Max. shielded motor cable length					
	Order code	Rated current	Dimensions (H x W x D)	Weight	C1		C2		C3	
		A	mm	kg	m	kHz	m	kHz		
i550-C3.0/400-3	I0FAE240F100S0001S	14	346 x 60 x 50	1.42	25	2	50	2	-	-
i550-C3.0/400-3	I0FAE240F100S0001S	14	346 x 60 x 50	1.42	25	4	50	4	-	-
i550-C4.0/400-3	I0FAE240F100S0001S	14	346 x 60 x 50	1.42	25	2	50	2	-	-
i550-C4.0/400-3	I0FAE240F100S0001S	14	346 x 60 x 50	1.42	25	4	50	4	-	-
i550-C5.5/400-3	I0FAE255F100S0001S	18.3	346 x 90 x 60	2.05	25	4	50	4	-	-
i550-C7.5/400-3	I0FAE311F100S0000S	29	371 x 120 x 60	2.35	25	4	50	4	-	-
i550-C11/400-3	I0FAE311F100S0000S	29	371 x 120 x 60	2.35	25	4	50	4	-	-

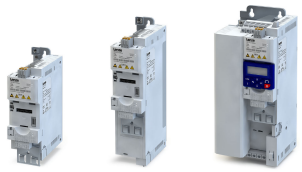
In order to meet the EMC requirements according to EN IEC 61800-3, the lower of the screws marked “IT” on the product must be removed when using the filters listed below.

Filters: I0FAE240F100S0001S
I0FAE255F100S0001S
I0FAE311F100S0000S



Long distance filter

Inverter	Filter				Max. shielded motor cable length					
	Order code	Rated current	Dimensions (H x W x D)	Weight	C1		C2		C3	
		A	mm	kg	m	kHz	m	kHz		
i550-C3.0/400-3	I0FAE240F100D0001S	14	346 x 60 x 50	1.42	50	4	50	4	-	-
i550-C4.0/400-3	I0FAE240F100D0001S	14	346 x 60 x 50	1.42	50	4	50	4	-	-
i550-C5.5/400-3	I0FAE255F100D0001S	18.3	346 x 90 x 60	1.65	50	4	100	4	-	-
i550-C7.5/400-3	I0FAE311F100D0000S	29	371 x 120 x 60	2.05	50	4	100	4	-	-
i550-C11/400-3	I0FAE311F100D0000S	29	371 x 120 x 60	2.05	50	4	100	4	-	-
i550-C15/400-3	I0FAE330F100D0001S	69	465 x 180 x 106	9.4	50	4	100	4	-	-
i550-C18/400-3	I0FAE330F100D0001S	69	465 x 180 x 106	9.4	50	4	100	4	-	-
i550-C22/400-3	I0FAE330F100D0001S	69	465 x 180 x 106	9.4	50	4	100	4	-	-
i550-C30/400-3	I0FAE330F100D0001S	69	465 x 180 x 106	9.4	50	4	100	4	-	-
i550-C37/400-3	I0FAE345F100D0001S	100	590 x 250 x 105	32	50	4	100	4	-	-
i550-C45/400-3	I0FAE345F100D0001S	100	590 x 250 x 105	32	50	2	100	2	-	-
i550-C45/400-3	I0FAE345F100D0001S	100	590 x 250 x 105	32	50	4	100	4	-	-
i550-C55/400-3	I0FAE355F100D0001S	120	700 x 250 x 105	36	50	4	100	4	-	-
i550-C75/400-3	I0FAE375F100D0001S	162	700 x 250 x 105	41.5	50	4	100	4	-	-
i550-C90/400-3	I0FAE411F100D0001S	234	855 x 250 x 130	63	-	-	100	4	-	-
i550-C110/400-3	I0FAE411F100D0001S	234	855 x 250 x 130	63	-	-	100	4	-	-



Ecodesign Directive

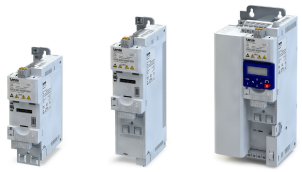
Product information acc. to REGULATION (EU) 2019/1781 (ANNEX I, Section 4)

Legend

Validity	The specifications also apply to power units with model identifier I5**D**□E□□□□ in combination with a control unit I5C...
Operating point (f; I)	f = relative motor stator frequency; I = relative torque-producing current
Power losses	The power losses at the operating points (f; I) and in the standby state refer to the rated apparent output power. The power losses for options (e.g. for diagnostics) and for accessories can be found in the additional product documentation on the Internet.

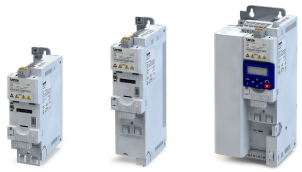
Performance losses										
0; 25	f; I	%	2.7	1.9	1.1	1.0	2.2	2.2	1.8	1.8
0; 50	f; I	%	2.7	1.9	1.3	1.1	2.2	2.2	1.8	1.8
0; 100	f; I	%	2.9	2.2	1.6	1.5	2.4	2.4	2.0	2.0
50; 25	f; I	%	2.7	2.0	1.2	1.0	2.2	2.3	1.8	1.8
50; 50	f; I	%	2.8	2.0	1.3	1.2	2.3	2.3	1.9	1.9
50; 100	f; I	%	3.1	2.3	1.8	1.7	2.6	2.6	2.2	2.2
90; 50	f; I	%	2.9	2.1	1.4	1.3	2.4	2.4	2.0	2.0
90; 100	f; I	%	3.3	2.6	2.0	1.9	2.9	2.8	2.5	2.4
In standby mode		%	0.9	0.6	0.4	0.3	0.9	0.9	0.6	0.6
Efficiency level			IE2	IE2	IE2	IE2	IE2	IE2	IE2	IE2
Manufacturer			Lenze SE · Hans-Lenze-Str. 1 · 31855 Aerzen · GERMANY							
Commercial register number			Hannover HRB 204803							
Model identifier of the product			I55AE125A	I55AE137A	I55AE175A	I55AE211A	I55AE125B	I55AE125D	I55AE137B	I55AE137D
Apparent output power		kVA	0.6	0.9	1.6	2.2	0.6	0.6	0.9	0.9
Indicative rated output power of the motor		kW	0.25	0.37	0.75	1.1	0.25	0.25	0.37	0.37
Rated output current		A	1.7	2.4	4.2	6	1.7	1.7	2.4	2.4
Maximum operating temperature		°C	45							
Rated input frequency		Hz	50							
Rated input voltage		V	120				230			
Switching frequency		kHz	4							
Rated apparent output power		kVA	0.697	0.977	1.71	2.29	0.697	0.697	0.977	0.977

Performance losses										
0; 25	f; I	%	1.6	1.8	1.1	1.1	0.9	1.1	0.8	1.0
0; 50	f; I	%	1.7	1.8	1.2	1.2	1.1	1.3	0.9	1.1
0; 100	f; I	%	1.9	2.1	1.5	1.6	1.4	1.6	1.2	1.4
50; 25	f; I	%	1.7	1.9	1.1	1.1	1.0	1.2	0.8	1.0
50; 50	f; I	%	1.7	1.9	1.3	1.3	1.1	1.4	1.0	1.2
50; 100	f; I	%	2.1	2.3	1.7	1.7	1.6	1.8	1.4	1.6
90; 50	f; I	%	1.8	2.0	1.3	1.4	1.2	1.4	1.1	1.3
90; 100	f; I	%	2.3	2.4	1.9	1.9	1.9	2.0	1.7	1.8
In standby mode		%	0.5	0.5	0.4	0.4	0.3	0.3	0.2	0.2
Efficiency level			IE2	IE2	IE2	IE2	IE2	IE2	IE2	IE2
Manufacturer			Lenze SE · Hans-Lenze-Str. 1 · 31855 Aerzen · GERMANY							
Commercial register number			Hannover HRB 204803							
Model identifier of the product			I55AE155B	I55AE155D	I55AE175B	I55AE175D	I55AE211B	I55AE211D	I55AE215B	I55AE215D
Apparent output power		kVA	1.2	1.2	1.6	1.6	2.2	2.2	2.6	2.6
Indicative rated output power of the motor		kW	0.55	0.55	0.75	0.75	1.1	1.1	1.5	1.5
Rated output current		A	3.2	3.2	4.2	4.2	6	6	7	7
Maximum operating temperature		°C	45							
Rated input frequency		Hz	50							
Rated input voltage		V	230							
Switching frequency		kHz	4							
Rated apparent output power		kVA	1.19	1.19	1.71	1.71	2.29	2.29	3.3	3.3



Performance losses										
0; 25	f; I	%	0.8	0.9	1.1	0.7	3.1	3.3	2.2	1.9
0; 50	f; I	%	1.0	1.1	1.3	1.0	3.1	3.4	2.3	2.0
0; 100	f; I	%	1.3	1.4	1.8	1.7	3.3	3.6	2.6	2.3
50; 25	f; I	%	0.9	1.0	1.2	0.8	3.1	3.4	2.2	1.9
50; 50	f; I	%	1.1	1.2	1.5	1.1	3.2	3.4	2.4	2.1
50; 100	f; I	%	1.6	1.6	2.2	1.9	3.5	3.7	2.8	2.5
90; 50	f; I	%	1.2	1.3	1.6	1.2	3.3	3.5	2.5	2.2
90; 100	f; I	%	1.9	1.9	2.5	2.3	3.7	3.9	2.9	2.8
In standby mode		%	0.1	0.1	0.1	0.1	0.6	0.5	0.4	0.3
Efficiency level			IE2	IE2	IE2	IE2	IE2	IE2	IE2	IE2
Manufacturer			Lenze SE · Hans-Lenze-Str. 1 · 31855 Aerzen · GERMANY							
Commercial register number			Hannover HRB 204803							
Model identifier of the product			I55AE222B	I55AE222D	I55AE240C	I55AE255C	I55AE137F	I55AE155F	I55AE175F	I55AE211F
Apparent output power		kVA	3.6	3.6	6.4	8.7	0.9	1.2	1.6	2.2
Indicative rated output power of the motor		kW	2.2	2.2	4	5.5	0.37	0.55	0.75	1.1
Rated output current		A	9.6	9.6	16.5	23	1.3	1.8	2.4	3.2
Maximum operating temperature		°C	45							
Rated input frequency		Hz	50							
Rated input voltage		V	230				400			
Switching frequency		kHz	4							
Rated apparent output power		kVA	4.44	4.44	7.38	9.95	0.977	1.19	1.71	2.29

Performance losses										
0; 25	f; I	%	1.2	1.1	1.4	1.2	1.0	0.7	0.5	0.8
0; 50	f; I	%	1.3	1.3	1.5	1.3	1.1	0.8	0.7	1.0
0; 100	f; I	%	1.6	1.6	1.9	1.7	1.6	1.2	1.0	1.5
50; 25	f; I	%	1.3	1.2	1.4	1.2	1.0	0.7	0.6	0.8
50; 50	f; I	%	1.4	1.3	1.6	1.4	1.2	0.9	0.7	1.0
50; 100	f; I	%	1.8	1.8	2.0	1.9	1.7	1.4	1.2	1.6
90; 50	f; I	%	1.5	1.5	1.6	1.5	1.2	0.9	0.8	1.1
90; 100	f; I	%	2.1	2.1	2.1	2.0	1.9	1.6	1.4	1.7
In standby mode		%	0.2	0.1	0.1	0.1	0.1	0.0	0.0	0.0
Efficiency level			IE2	IE2	IE2	IE2	IE2	IE2	IE2	IE2
Manufacturer			Lenze SE · Hans-Lenze-Str. 1 · 31855 Aerzen · GERMANY							
Commercial register number			Hannover HRB 204803							
Model identifier of the product			I55AE215F	I55AE222F	I55BE230F	I55BE240F	I55AE255F	I55BE275F	I55BE311F	I55BE315F
Apparent output power		kVA	2.6	3.8	4.9	6.4	8.7	11	16	21.5
Indicative rated output power of the motor		kW	1.5	2.2	3	4	5.5	7.5	11	15
Rated output current		A	3.9	5.6	7.3	9.5	13	16.5	23.5	32
Maximum operating temperature		°C	45							
Rated input frequency		Hz	50							
Rated input voltage		V	400							
Switching frequency		kHz	4							
Rated apparent output power		kVA	3.3	4.44	5.85	7.38	9.95	14.4	19.5	23.9



Performance losses										
0; 25	f; I	%	0.8	0.6	0.6	0.5	0.5	0.4	0.5	0.5
0; 50	f; I	%	1.0	0.8	0.7	0.7	0.6	0.6	0.6	0.7
0; 100	f; I	%	1.5	1.3	1.2	1.2	1.1	1.0	1.2	1.3
50; 25	f; I	%	0.8	0.6	0.6	0.5	0.5	0.4	0.5	0.5
50; 50	f; I	%	1.0	0.8	0.8	0.7	0.7	0.6	0.8	0.7
50; 100	f; I	%	1.7	1.4	1.4	1.3	1.3	1.2	1.5	1.5
90; 50	f; I	%	1.1	0.9	0.9	0.8	0.8	0.7	0.9	0.8
90; 100	f; I	%	1.7	1.5	1.5	1.6	1.6	1.5	1.9	1.7
In standby mode		%	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
Efficiency level			IE2	IE2	IE2	IE2	IE2	IE2	IE2	IE2
Manufacturer			Lenze SE · Hans-Lenze-Str. 1 · 31855 Aerzen · GERMANY							
Commercial register number			Hannover HRB 204803							
Model identifier of the product			I55BE318F	I55BE322F	I55BE330F	I55AE337F	I55AE345F	I55AE355F	I55AE375F	I55AE390F
Apparent output power		kVA	26.8	31.5	40.9	51	60	75	100	121
Indicative rated output power of the motor		kW	18.5	22	30	37	45	55	75	90
Rated output current		A	40	47	61	76	89	110	150	180
Maximum operating temperature		°C	45							
Rated input frequency		Hz	50							
Rated input voltage		V	400							
Switching frequency		kHz	4							
Rated apparent output power		kVA	28.3	38.2	47	56.2	68.4	92.8	111	135

Performance losses			
0; 25	f; I	%	0.3
0; 50	f; I	%	0.5
0; 100	f; I	%	0.9
50; 25	f; I	%	0.4
50; 50	f; I	%	0.5
50; 100	f; I	%	1.1
90; 50	f; I	%	0.6
90; 100	f; I	%	1.5
In standby mode		%	0.0
Efficiency level			IE2
Manufacturer			Lenze SE · Hans-Lenze-Str. 1 · 31855 Aerzen · GERMANY
Commercial register number			Hannover HRB 204803
Model identifier of the product			I55AE411F
Apparent output power		kVA	142
Indicative rated output power of the motor		kW	110
Rated output current		A	212
Maximum operating temperature		°C	45
Rated input frequency		Hz	50
Rated input voltage		V	400
Switching frequency		kHz	2
Rated apparent output power		kVA	162

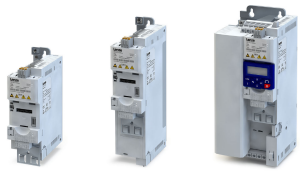
Dimensions

The specified installation clearances are minimum dimensions to ensure a sufficient air circulation for cooling purposes. They do not consider the bend radiuses of the connecting cables.

Several i5xx frequency inverters can be mounted directly next to each other, regardless of the device size. No installation clearance is required between the devices.

Installation clearances

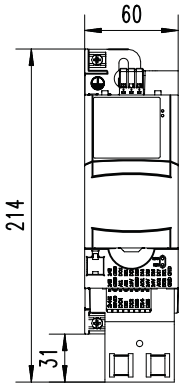
- Maintain the specified installation clearances above and below to the other installations.
- Several devices of the same series can be lined up directly, regardless of the device size. No installation clearance is required between the devices.

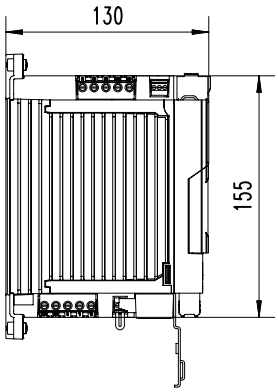


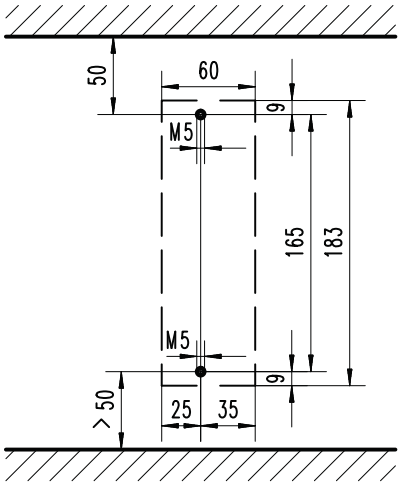
0.25 kW ... 0.37 kW

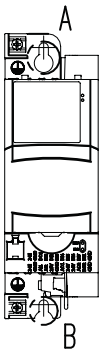
The dimensions in mm apply to:

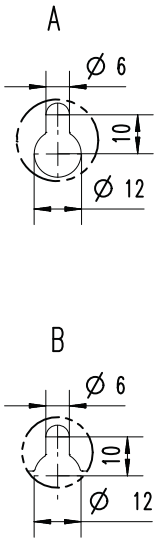
0.25 kW	i550-C0.25/230-1	i550-C0.25/230-2	
0.37 kW	i550-C0.37/230-1	i550-C0.37/230-2	i550-C0.37/400-3
Weight	0.8 kg	0.8 kg	0.8 kg









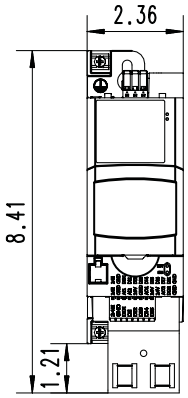


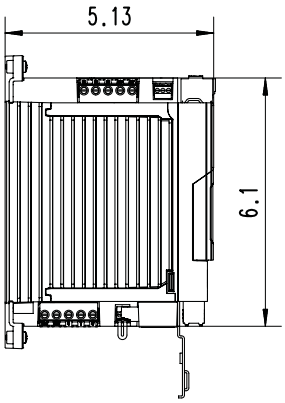
8800263

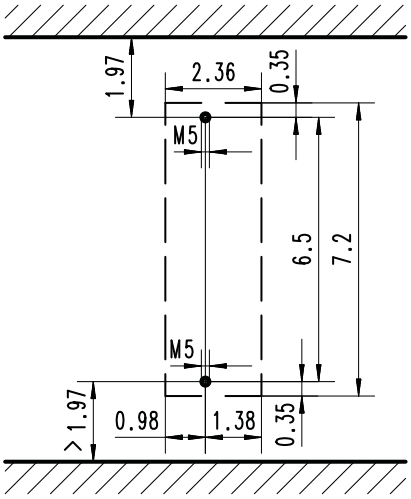
0.33 hp ... 0.5 hp

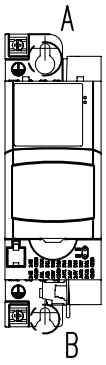
The dimensions in inch apply to:

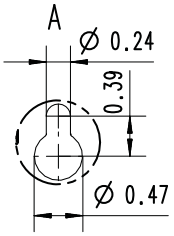
0.33 hp	i550-C0.25/230-1	i550-C0.25/230-2	
0.5 hp	i550-C0.37/230-1	i550-C0.37/230-2	i550-C0.37/400-3
Weight	1.8 lb	1.8 lb	1.8 lb

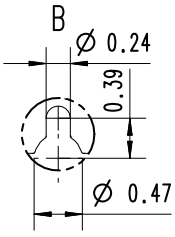




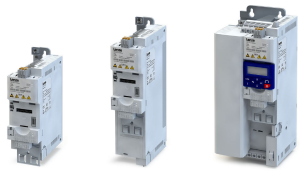








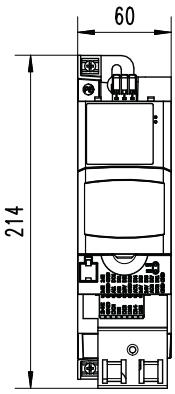
8800298

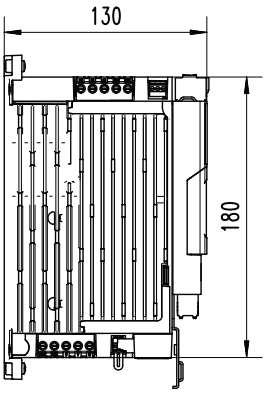


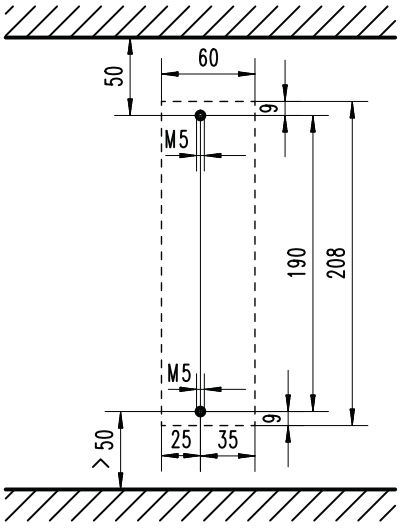
0.25 kW ... 0.75 kW

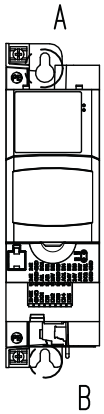
The dimensions in mm apply to:

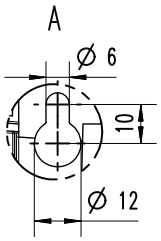
0.25 kW	i550-C0.25/120-1			
0.37 kW	i550-C0.37/120-1			
0.55 kW		i550-C0.55/230-1	i550-C0.55/230-2	i550-C0.55/400-3
0.75 kW		i550-C0.75/230-1	i550-C0.75/230-2	i550-C0.75/400-3
Weight	1 kg	1 kg	1 kg	1 kg

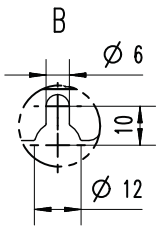










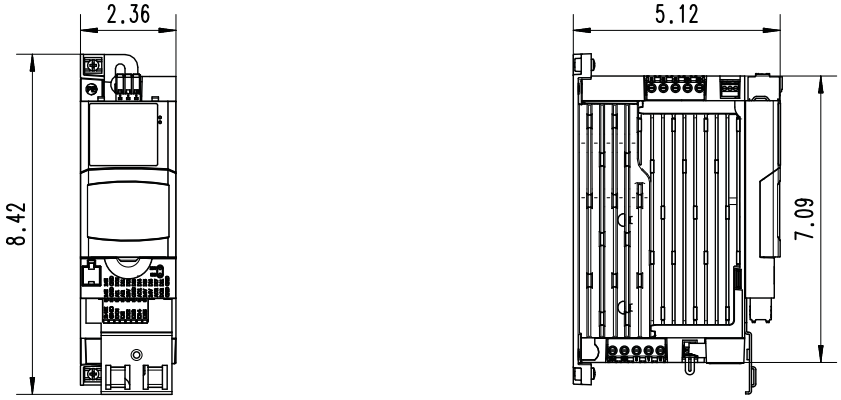


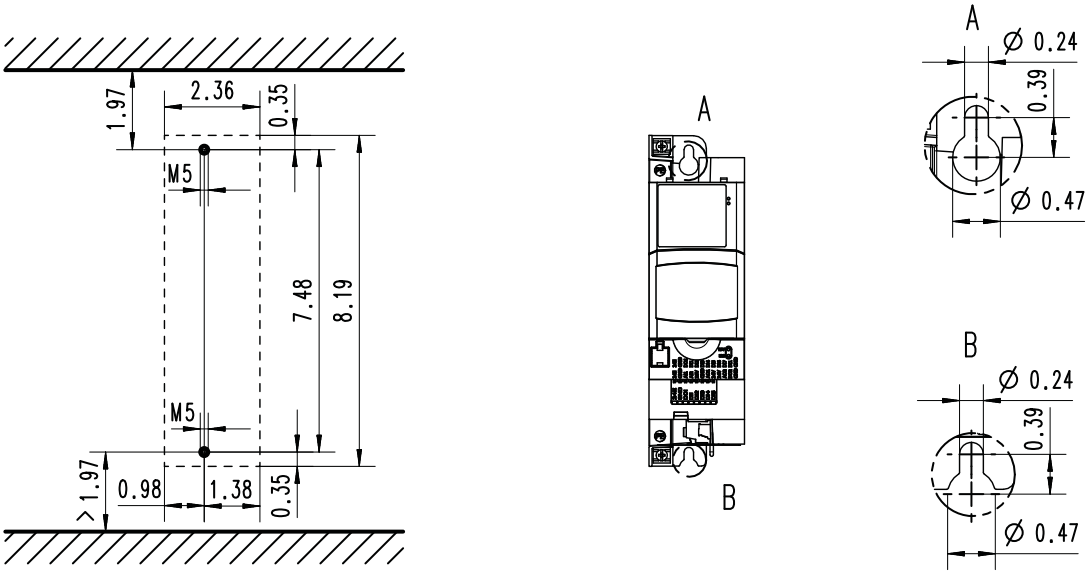
8800264

0.33 hp ... 1 hp

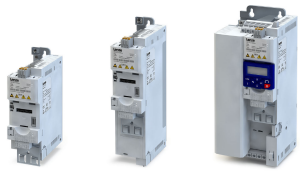
The dimensions in inch apply to:

0.33 hp	i550-C0.25/120-1			
0.5 hp	i550-C0.37/120-1			
0.75 hp		i550-C0.55/230-1	i550-C0.55/230-2	i550-C0.55/400-3
1 hp		i550-C0.75/230-1	i550-C0.75/230-2	i550-C0.75/400-3
Weight	2.2 lb	2.2 lb	2.2 lb	2.2 lb





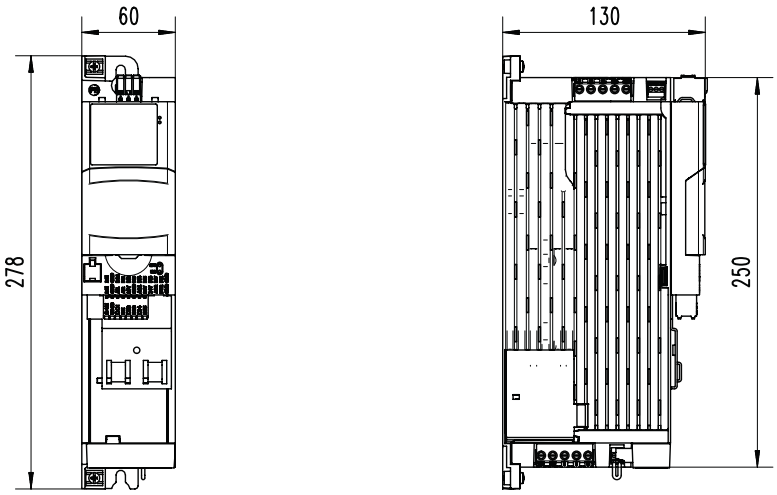
8800299

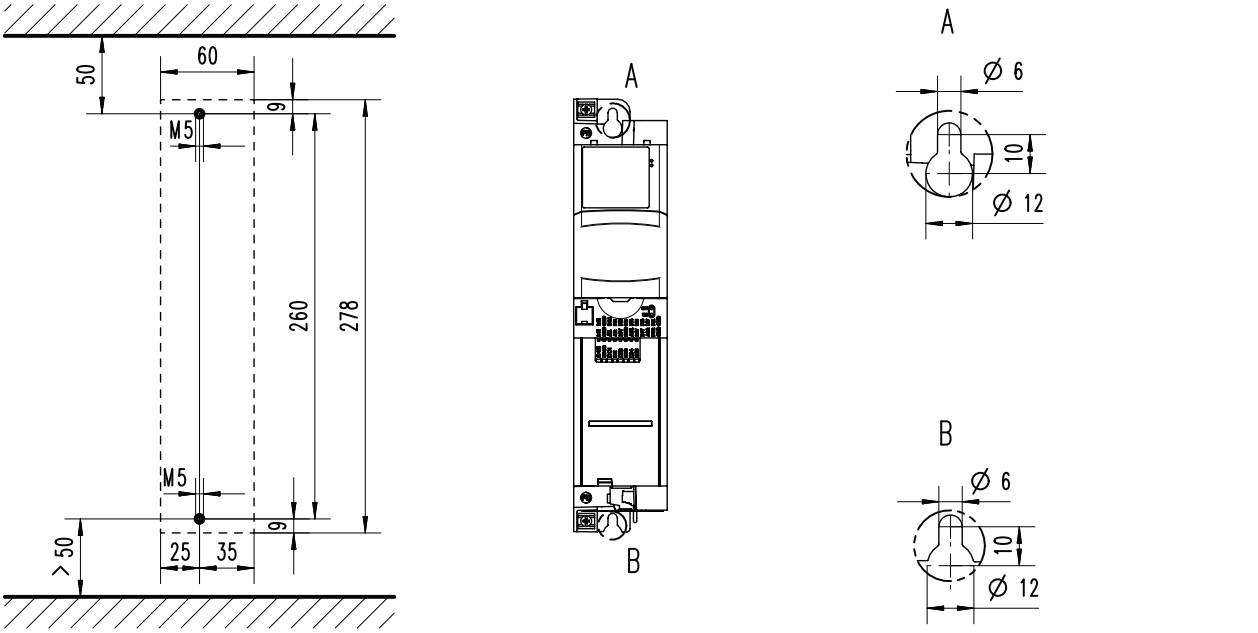


0.75 kW ... 4 kW

The dimensions in mm apply to:

0.75 kW	i550-C0.75/120-1				
1.1 kW	i550-C1.1/120-1	i550-C1.1/230-1	i550-C1.1/230-2	i550-C1.1/400-3	
1.5 kW		i550-C1.5/230-1	i550-C1.5/230-2	i550-C1.5/400-3	
2.2 kW		i550-C2.2/230-1	i550-C2.2/230-2	i550-C2.2/400-3	
3 kW					i550-C3.0/400-3
4 kW					i550-C4.0/400-3
Weight	1.35 kg	1.35 kg	1.35 kg	1.35 kg	1.35 kg



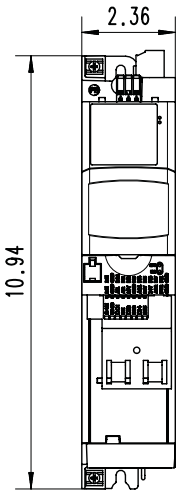


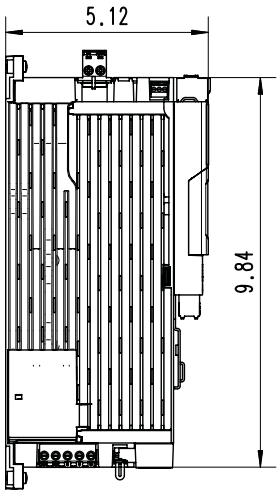
8800265

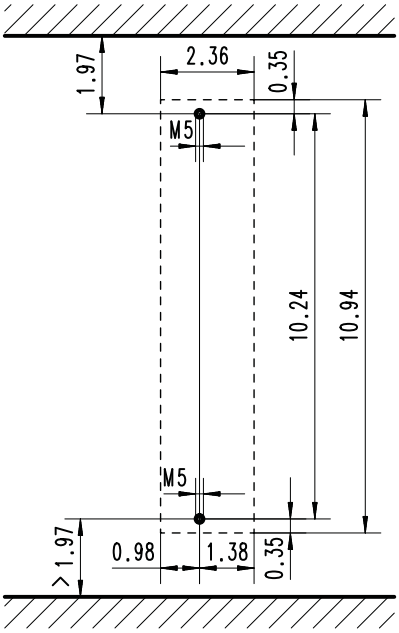
1 hp ... 5 hp

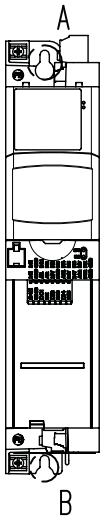
The dimensions in inch apply to:

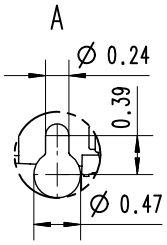
1 hp	i550-C0.75/120-1				
1.5 hp	i550-C1.1/120-1	i550-C1.1/230-1	i550-C1.1/230-2	i550-C1.1/400-3	
2 hp		i550-C1.5/230-1	i550-C1.5/230-2	i550-C1.5/400-3	
3 hp		i550-C2.2/230-1	i550-C2.2/230-2	i550-C2.2/400-3	
4 hp					i550-C3.0/400-3
5 hp					i550-C4.0/400-3
Weight	3 lb	3 lb	3 lb	3 lb	3 lb

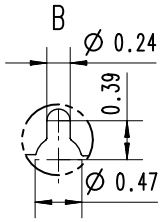




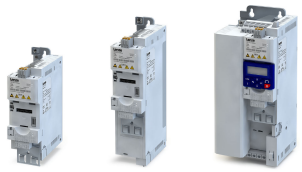








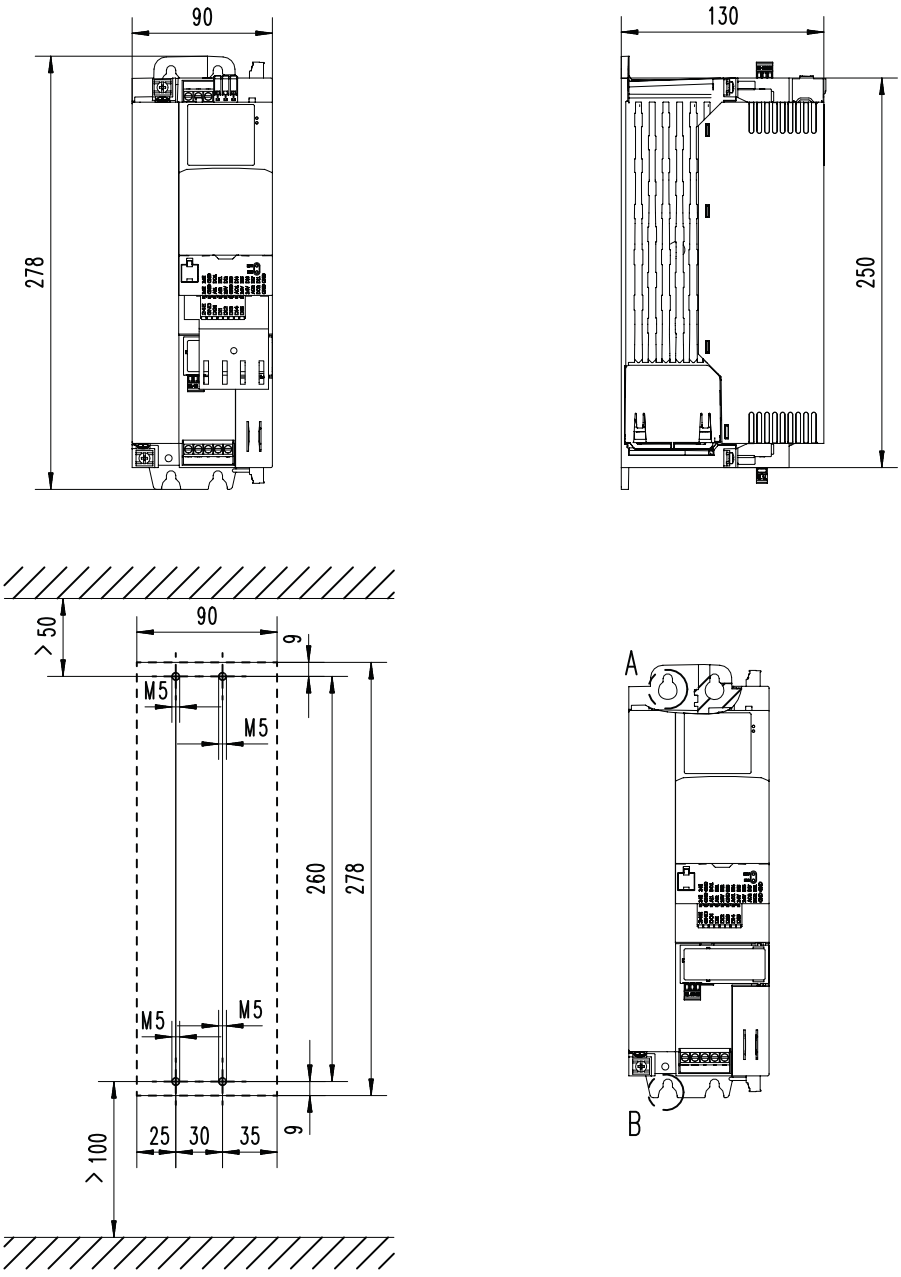
8800300



4 kW ... 5.5 kW

The dimensions in mm apply to:

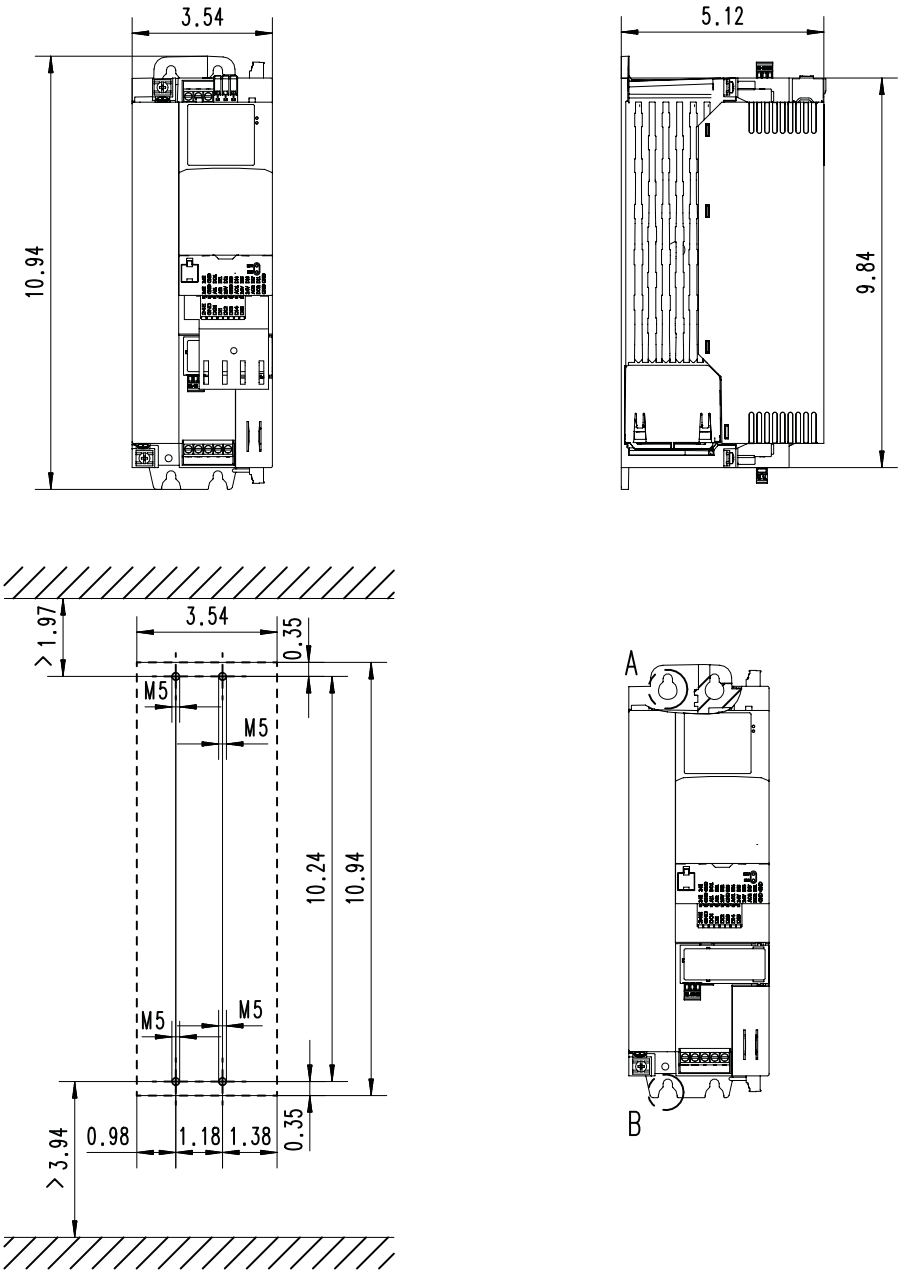
4 kW	i550-C4.0/230-3	
5.5 kW	i550-C5.5/230-3	i550-C5.5/400-3
Weight	2.1 kg	2.3 kg

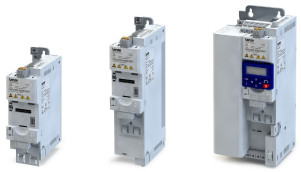


5 hp ... 7.5 hp

The dimensions in inch apply to:

5 hp	i550-C4.0/230-3	
7.5 hp	i550-C5.5/230-3	i550-C5.5/400-3
Weight	4.6 lb	5 lb

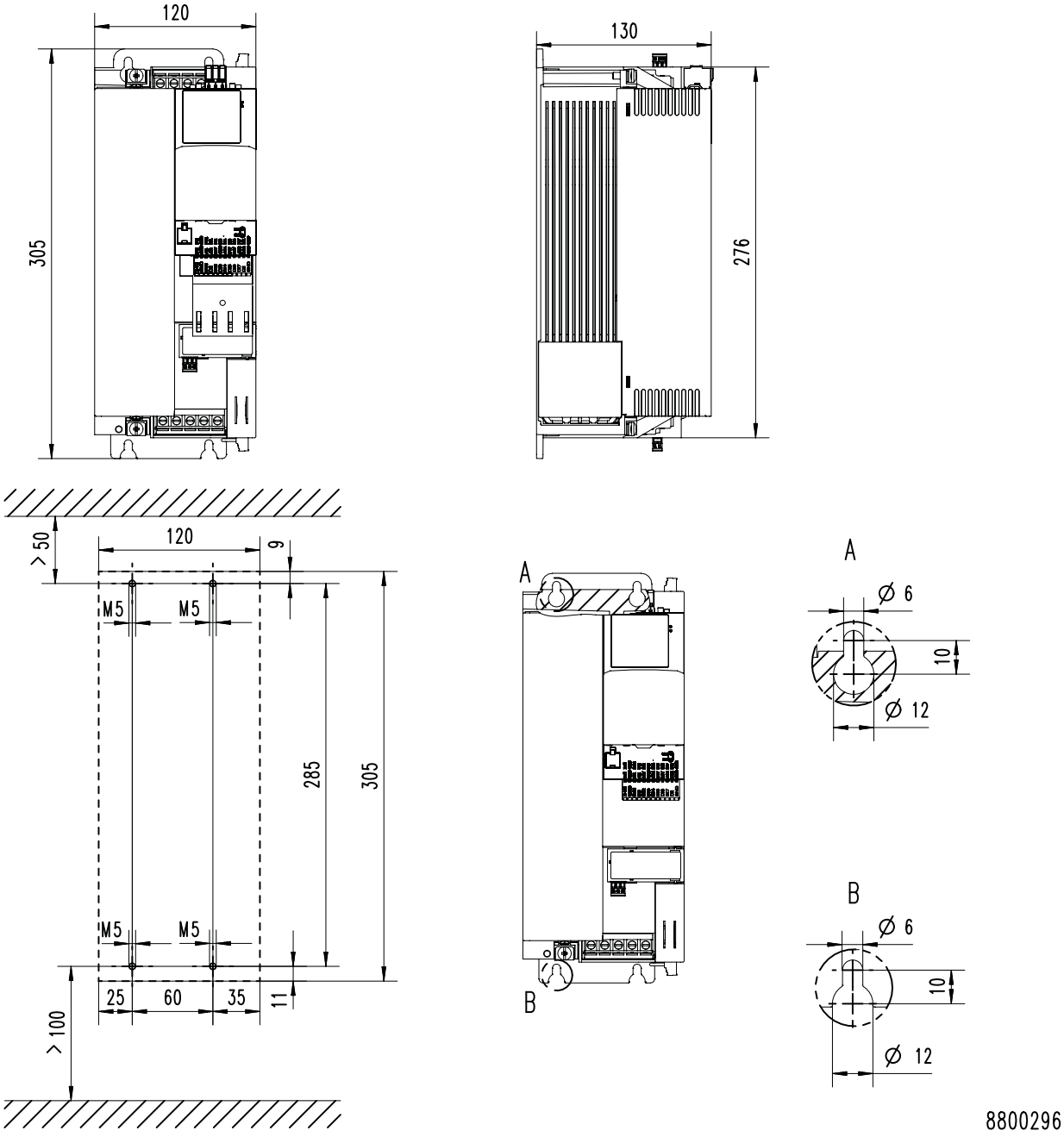




7.5 kW ... 11 kW

The dimensions in mm apply to:

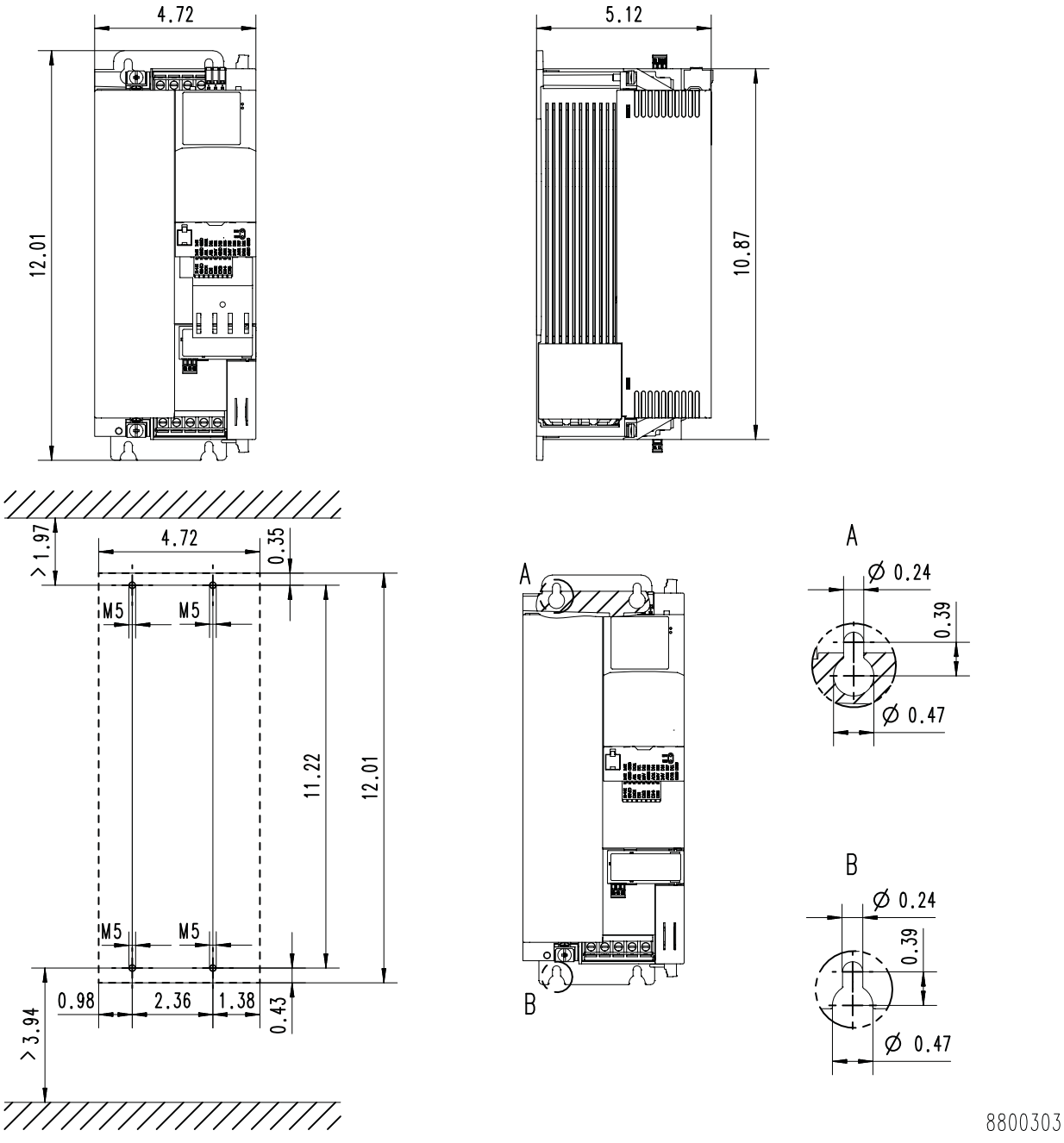
7.5 kW	i550-C7.5/400-3
11 kW	i550-C11/400-3
Weight	3.7 kg

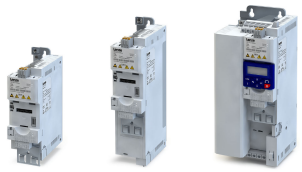


10 hp ... 15 hp

The dimensions in inch apply to:

10 hp	i550-C7.5/400-3
15 hp	i550-C11/400-3
Weight	8 lb

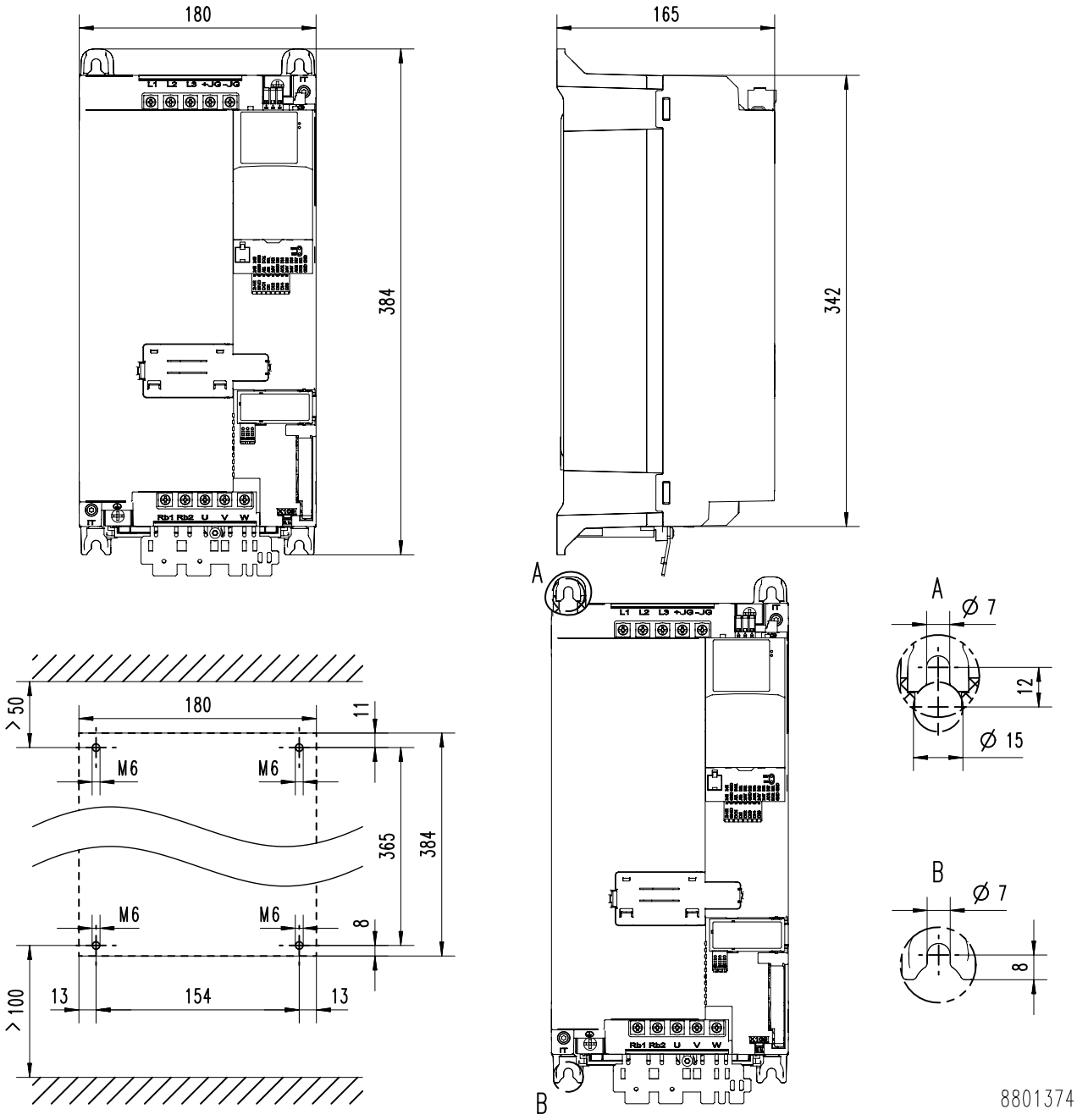




15 kW ... 30 kW

The dimensions in mm apply to:

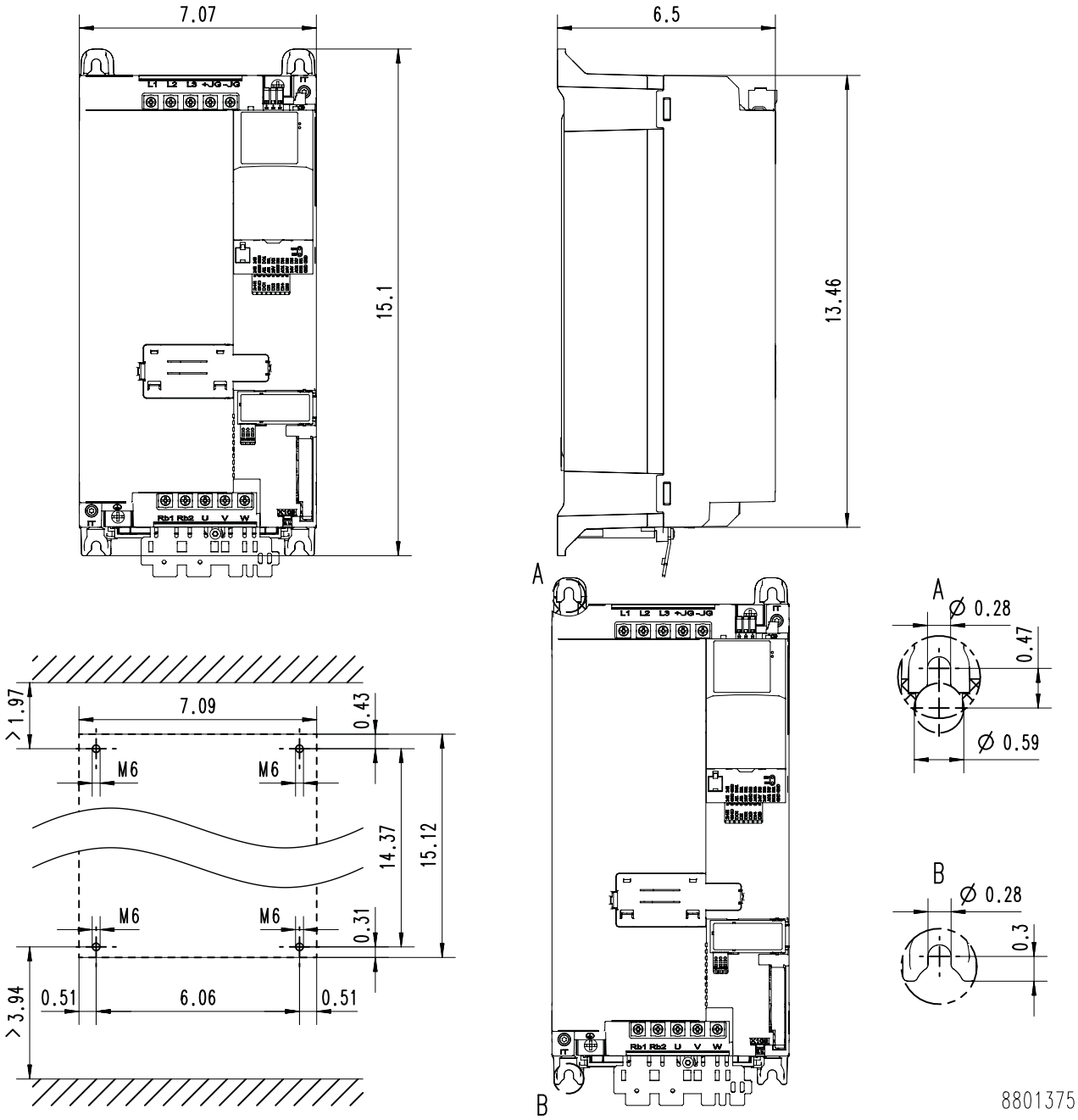
15 kW	i550-C15/400-3	i550-C15/400-3
18.5 kW	i550-C18/400-3	i550-C18/400-3
22 kW	i550-C22/400-3	i550-C22/400-3
30 kW	i550-C30/400-3	i550-C30/400-3
Weight	10.3 kg	8 kg

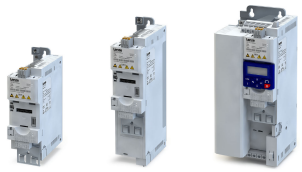


20 hp ... 40 hp

The dimensions in inch apply to:

20 hp	i550-C15/400-3	i550-C15/400-3
25 hp	i550-C18/400-3	i550-C18/400-3
30 hp	i550-C22/400-3	i550-C22/400-3
40 hp	i550-C30/400-3	i550-C30/400-3
Weight	23 lb	17.6 lb

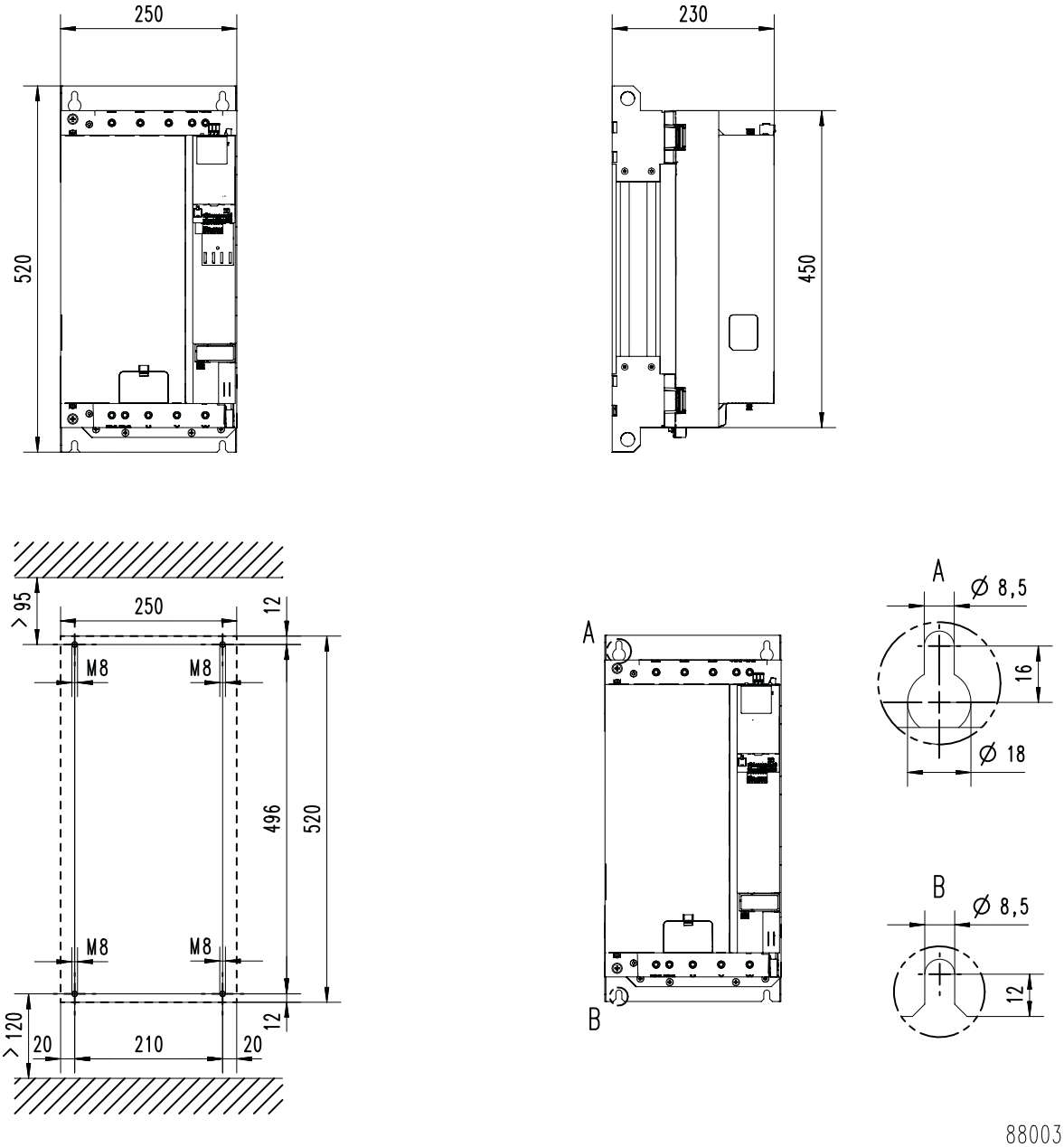




37 kW ... 45 kW

The dimensions in mm apply to:

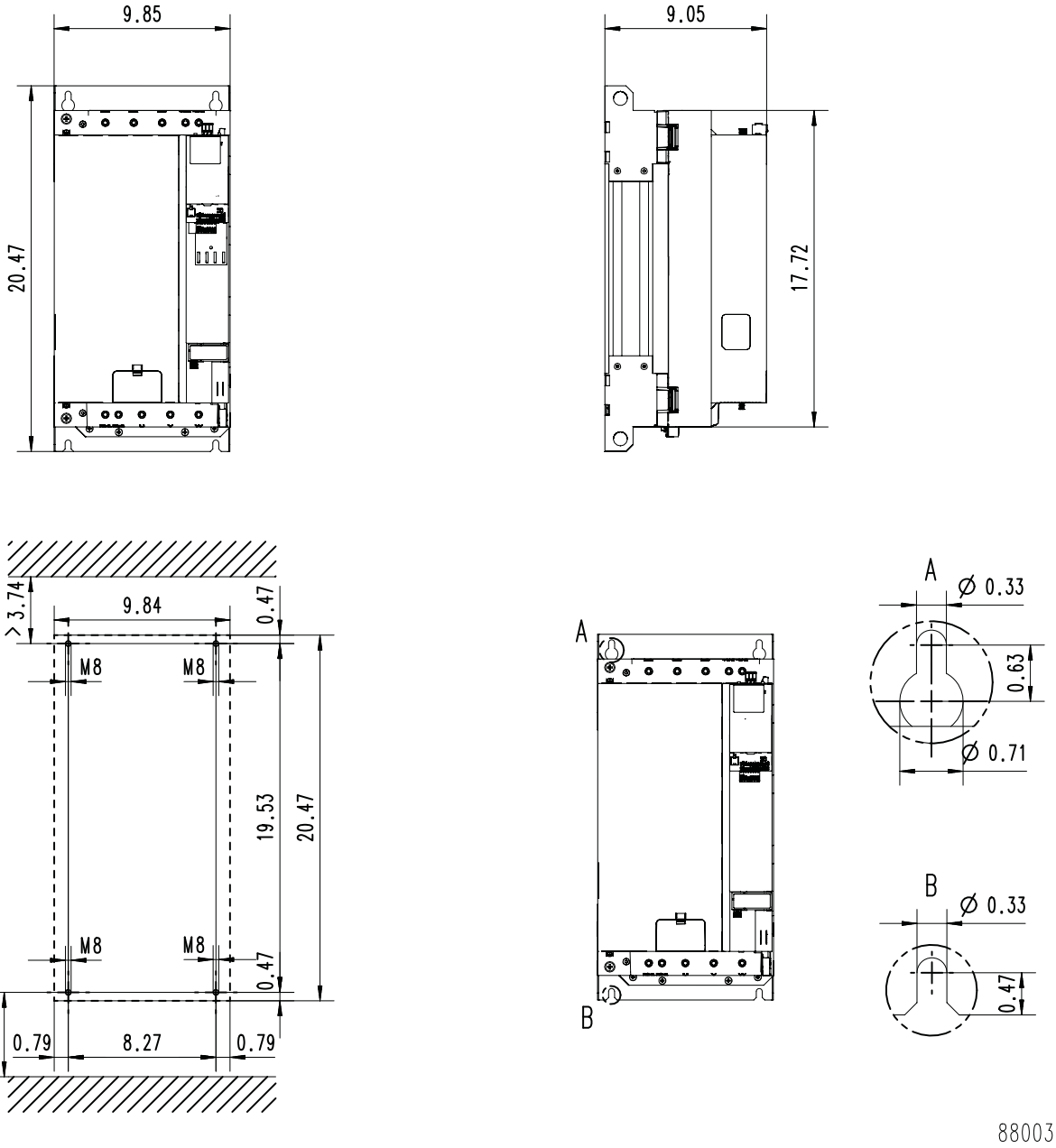
37 kW	i550-C37/400-3
45 kW	i550-C45/400-3
Weight	17.2 kg

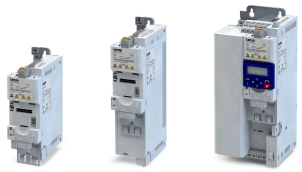


50 hp ... 60 hp

The dimensions in inch apply to:

50 hp	i550-C37/400-3
60 hp	i550-C45/400-3
Weight	38 lb

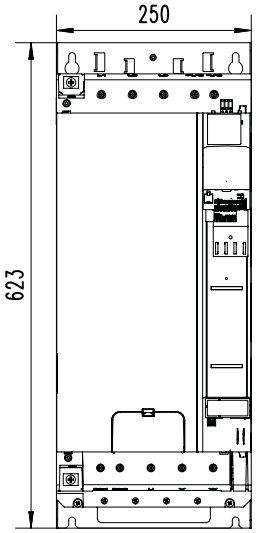


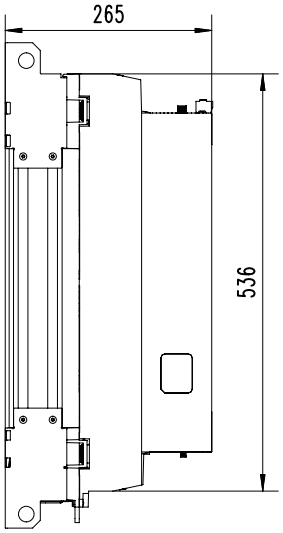


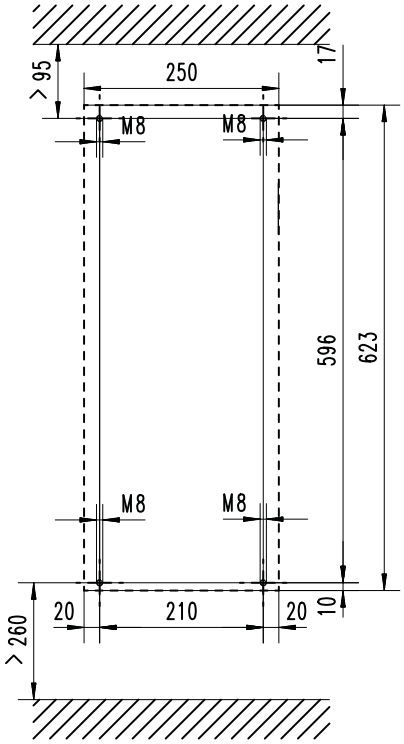
55 kW ... 75 kW

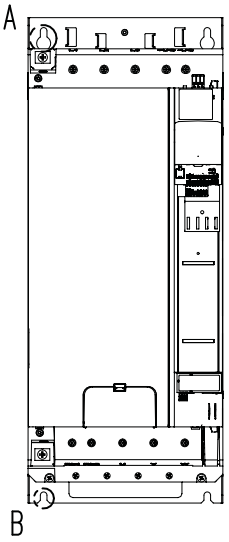
The dimensions in mm apply to:

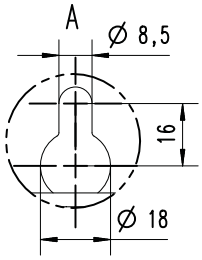
55 kW	i550-C55/400-3
75 kW	i550-C75/400-3
Weight	24 kg

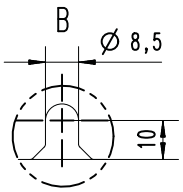










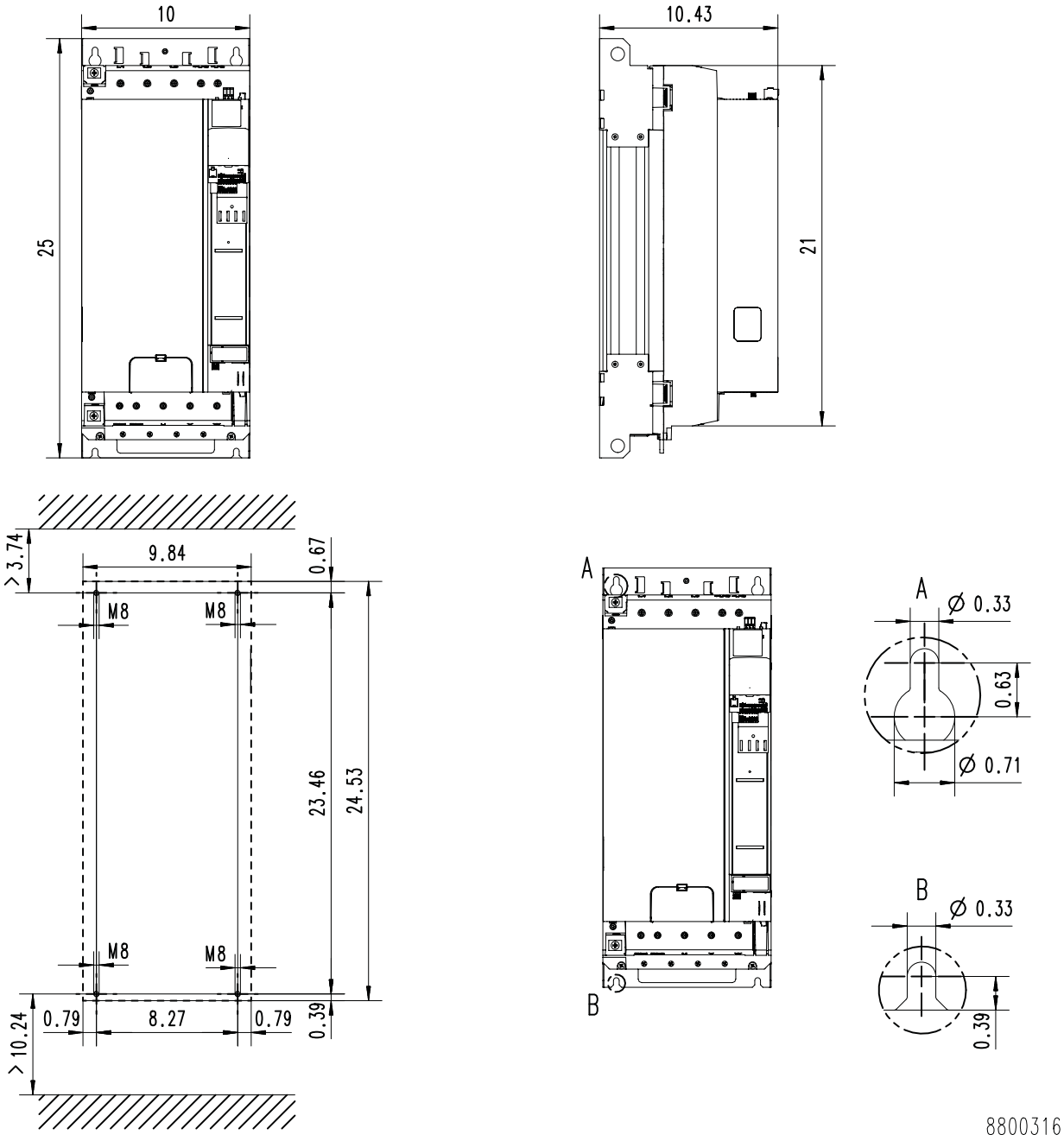


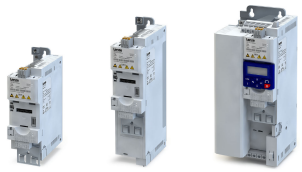
8800315

75 hp ... 100 hp

The dimensions in inch apply to:

75 hp	i550-C55/400-3
100 hp	i550-C75/400-3
Weight	53 lb

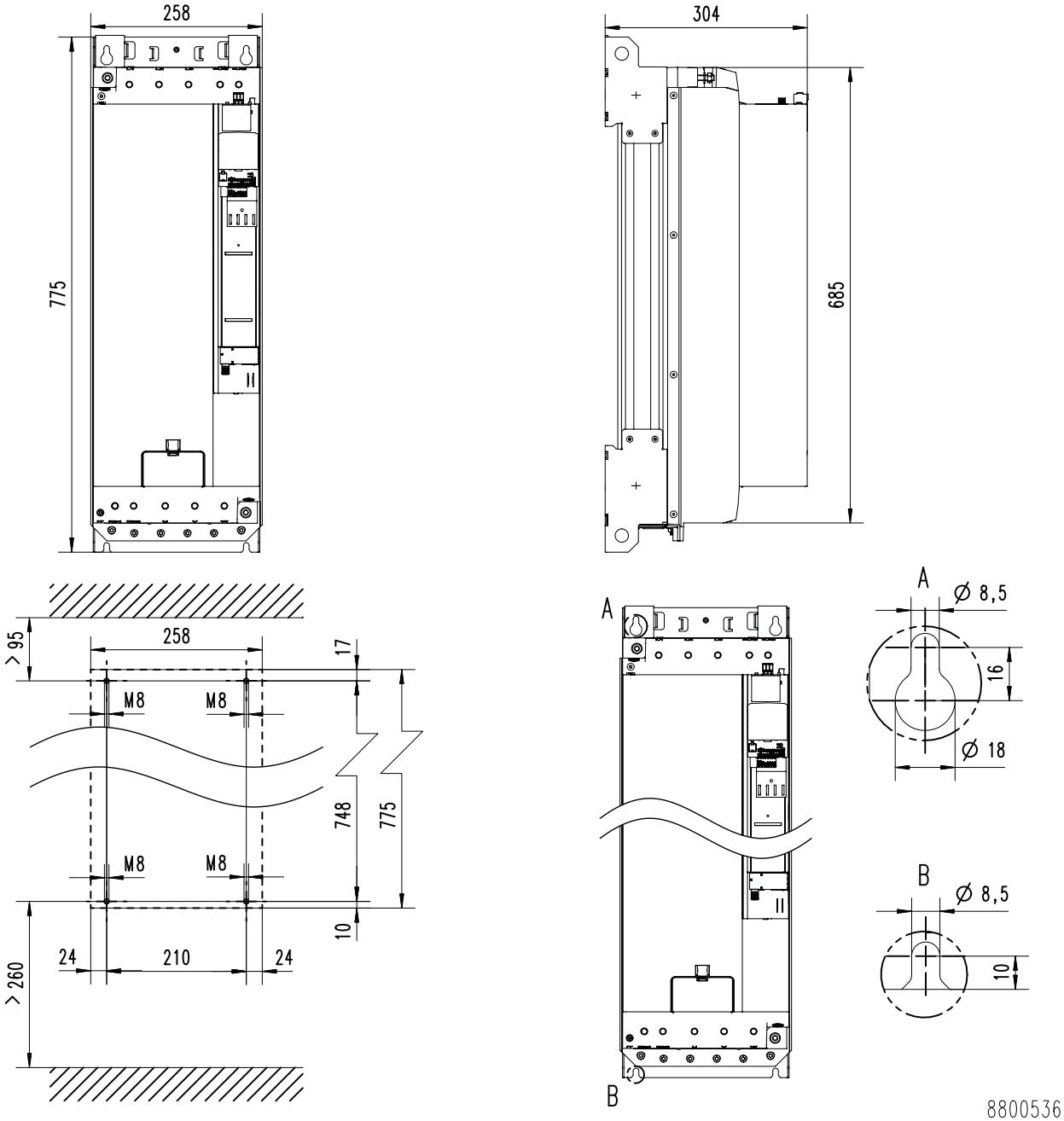




90 kW ... 110 kW

The dimensions in mm apply to:

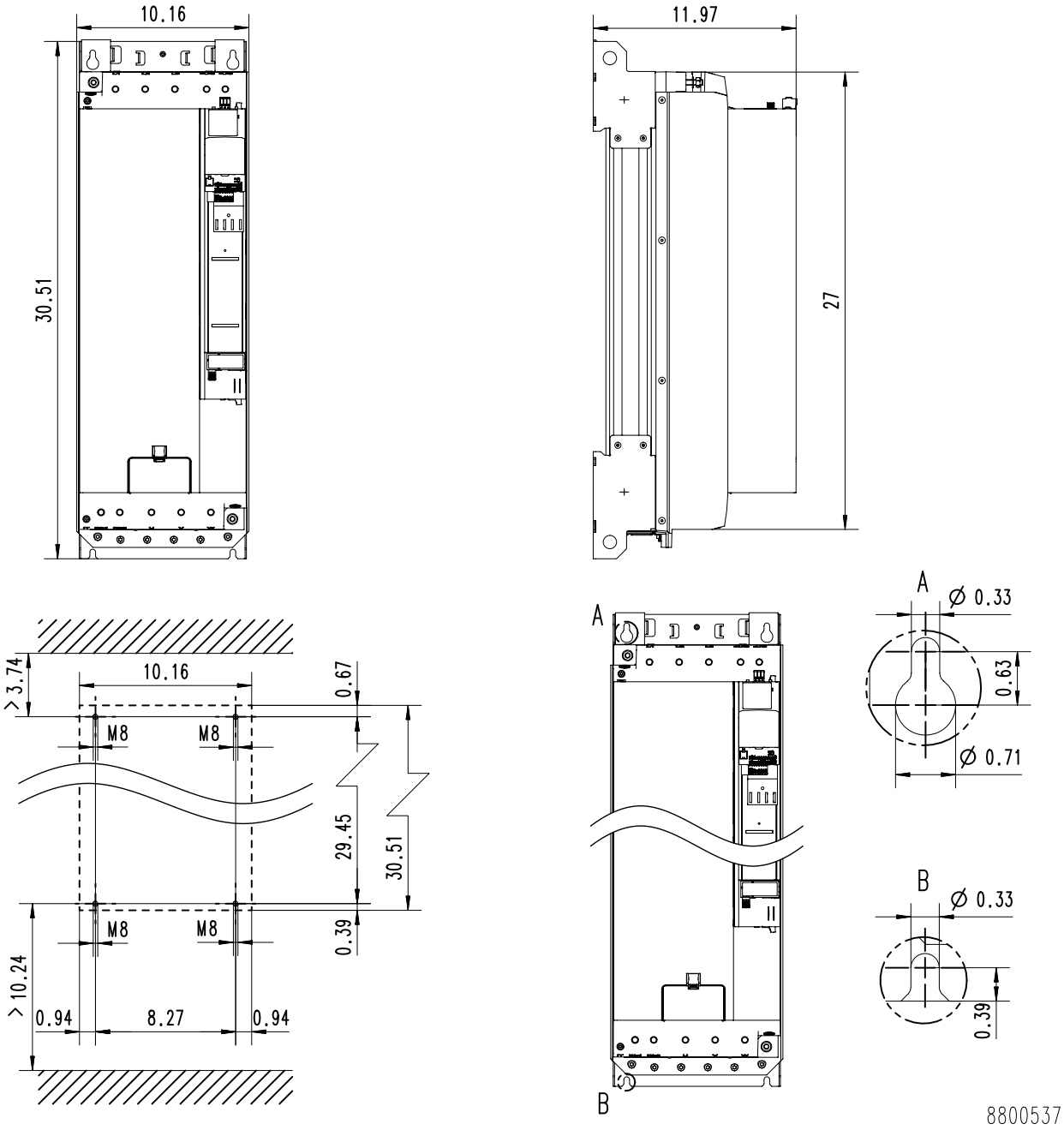
90 kW	i550-C90/400-3
110 kW	i550-C110/400-3
Weight	35.6 kg

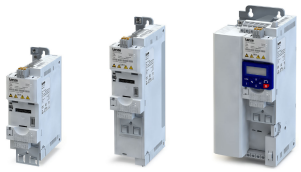


125 hp ... 150 hp

The dimensions in inch apply to:

125 hp	i550-C90/400-3
150 hp	i550-C110/400-3
Weight	78.5 lb





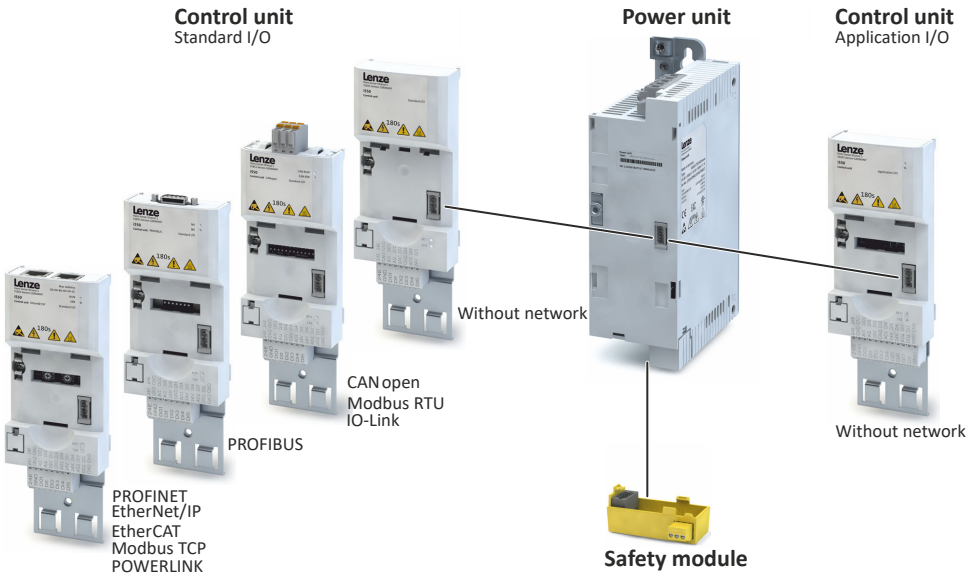
Product extensions

Overview

The inverters can easily be integrated into the machine. The scalable product extensions serve to flexibly match the required functions to your application.

The control unit with standard I/O can be extended with different networks.

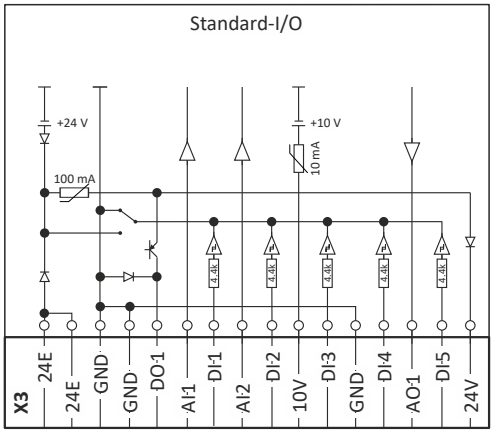
The control unit with application I/O provides additional inputs and outputs (I/Os). A network component is not available.



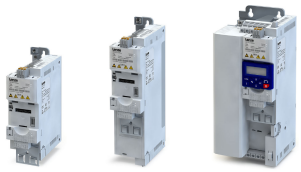
I/O extensions

Standard I/O

The standard I/O provides the inverter with analog and digital inputs and outputs and is designed for standard applications. The standard I/O is available with different networks.

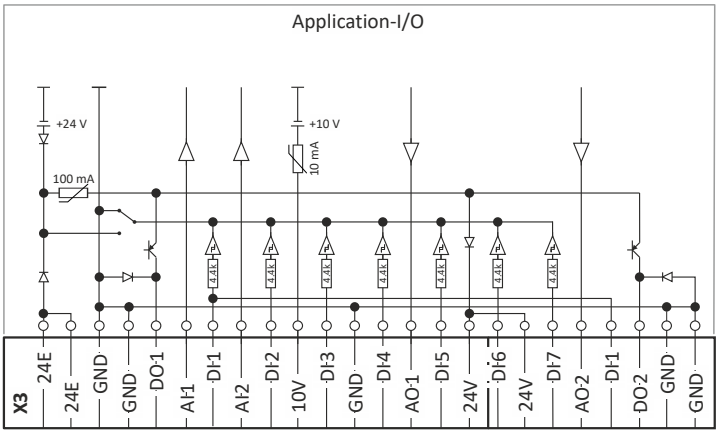


Control terminal X3		
Inputs/outputs	**Terminal**	**Description**
Digital inputs	DI1, DI2, DI3, DI4, DI5	DI3/DI4 can be optionally used as frequency or encoder input. HIGH active/LOW active switchable.
Digital outputs	DO1	
Analog inputs	AI1, AI2	Can be optionally used as voltage or current input.
Analog outputs	AO1	Can be optionally used as voltage or current output.
24-V input	24E	Mains-independent DC supply of the control electronics (incl. communication)
10-V output	10 V	Reference voltage or setpoint potentiometer
24-V output	24V	Primarily for supplying digital inputs or Basic Safety - STO; SELV/PELV
Reference potential	GND	
Connection system		Spring terminals, not pluggable

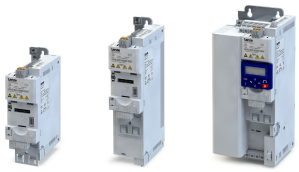


Application I/O

In addition to the standard I/O, the application I/O provides the inverter with more digital and analog inputs and is intended for individual applications. The combination with network components is not available.



Digital inputs	Terminal X3: DI1, DI2, DI3, DI4, DI5, DI6, DI7	DI3/DI4 can be optionally used as frequency or encoder input. HIGH active/LOW active switchable
Digital outputs	Terminal X3: DO1, DO2	
Analog inputs	Terminal X3: AI1, AI2	can be optionally used as voltage or current input.
Analog outputs	Terminal X3: AO1, AO2	Can be optionally used as voltage or current output.
24-V input	Terminal X3: 24E	Mains-independent DC supply of the control electronics (incl. communication)
10-V output	Terminal X3: 10V	Reference voltage for setpoint potentiometer
24-V output	Terminal X3: 24V	
Reference potential	Terminal X3: GND	
Connection system	Pluggable spring terminal	



Data of control connections

Digital inputs

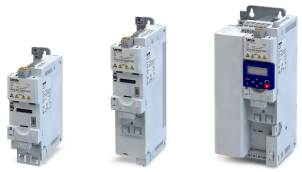
Switching type		PNP, NPN	Parameterisable
PNP switching level			
LOW	V	< +5	IEC 61131−2, type 1
HIGH	V	> +15	
NPN switching level			
LOW	V	> +15	
HIGH	V	< +5	
Input resistance	kΩ	4.6	
Cycle time	ms	1	
Electric strength of external voltage	V	± 30	

Frequency input			
Connection		X3/DI3, X3/DI4	
Frequency range	kHz	0 … 100	

Encoder input			
Type		Incremental HTL encoder	
Two-track connection		X3/DI3 X3/DI4	Track A Track B
Frequency range	kHz	0 … 100	

Digital outputs

Switching level			
LOW	V	< +5	IEC 61131−2, type 1
HIGH	V	> +15	
max. output current	mA	100	Total current for DO1 and 24V
Cycle time	ms	1	
Short-circuit strength		Unlimited period	
Electric strength of external voltage	V	± 30	
Polarity reversal protection		Integrated freewheeling diode for switching the inductive load	
Overload behaviour		Reduced voltage or periodic switch-off/on	
Reset or switch-on behaviour		Output is switched off	LOW



Analog inputs

Cycle time	ms	1	
Resolution of A/D converter	Bit	12	
Operation as voltage input			
Connection designation		X3/AI1, X3/AI2	
Input voltage DC	V	-10 … 10	
Input resistance	kΩ	70	
Accuracy	mV	± 50	Typical
Input voltage in case of open circuit	V	- 0.2 … 0.2	Display "0"
Electric strength of external voltage	V	± 24	
Operation as current input			
Connection designation		X3/AI1, X3/AI2	
Input current	mA	0 ... 20	
		4 … 20	open-circuit monitored
Accuracy	mA	± 0.1	Typical
Input current in case of open circuit	mA	< 0.1	Display "0"
Input resistance	Ω	< 250	
Electric strength of external voltage	V	± 24	

Analog outputs

Short-circuit strength		Unlimited period	
Electric strength of external voltage	V	+ 24V	
Operation as voltage output			
Resolution of D/A converter	Bit	12	
Output voltage DC	V	0 ... 10	
max. output current	mA	5	
min. load resistance	kΩ	≥ 2.2	
max. capacitive load	µF	1	
Accuracy	mV	± 100	Typical
Operation as current output			
Output current	mA	0 ... 20	
		4 … 20	open-circuit monitored
Accuracy	mA	± 0.3	Typical

10-V output

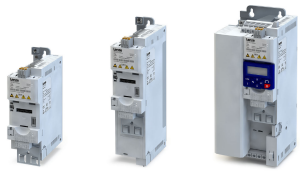
Use		Primarily for the supply of a potentiometer (1 ... 10 kΩ)	
Output voltage DC			
Typical	V	10	
Accuracy	mV	± 100	
Max. output current	mA	10	
Max. capacitive load	µF	1	
Short-circuit strength		Unlimited period	
Electric strength of external voltage	V	+ 24	

24-V input

Use		Input for mains-independent DC supply of the control electronics (incl. communication)	
Input voltage DC			
Typical	V	24	IEC 61131-2
Area	V	19.2 … 28.8	
Input power			
Typical	W	3.6	
Max.	W	6	Depending on the use and state of inputs and outputs.
Input current			
Typical	A	0.150	
Max.	A	1.0	When switching on for 50 ms
Capacity to be charged	µF	440	
Polarity reversal protection		When polarity is reversed: No function and no destruction	
Suppression of voltage pulses		Suppressor diode 30 V, bidirectional	
Power supply unit		SELV/PELV	Externally to create a mains-independent DC supply
Max. current	A	8.0	While looping-through

24-V output

Use		Primarily for supplying digital inputs or passive sensors at X1	SELV/PELV
Output voltage DC			
Typical	V	24	
Range	V	16 … 28	
max. output current	mA	100	Total current for DO... and 24V
Short-circuit strength		Unlimited period	
External-voltage protection	V	+ 30	
Overcurrent fusing		Automatically resettable	

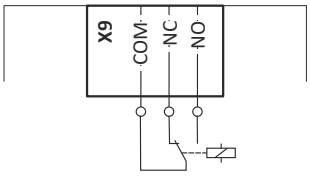


Further control connections

Relay output

Use a corresponding suppressor circuit in case of an inductive or capacitive load!

Connection			Terminal X9: COM	Common contact (Common)
			Terminal X9: NC	Normally closed contact
			Terminal X9: NO	Normally open contact
Minimum DC contact load				
	Voltage	V	10	A correct switching of the relay contacts needs both values to be exceeded simultaneously.
	Current	mA	10	
Switching voltage/switching current				
Maximum	AC 240 V	A	3	According to UL: General Purpose
	24 V DC	A	2	According to UL: Resistive
	240 V DC	A	0.16	



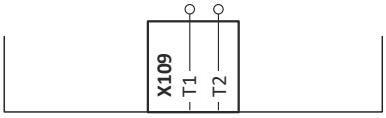
PTC input

The external PTC sensor must have the following **electrical insulation** incl. wiring:

At least one basic insulation to the power potential and at least one basic insulation to the control potential.

In the Lenze setting, motor temperature monitoring is activated! In the delivery status, there is a wire jumper between the terminals T1 and T2. Before connecting a thermal sensor, remove the wire jumper.

Use	Connection of PTC or thermal contact
Connection	Terminal X109: T1 Terminal X109: T2
Sensor types	PTC single sensor (DIN 44081) PTC triple sensor (DIN 44082) Thermal contact



Networks

CANopen

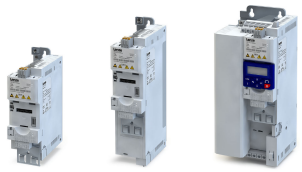
CANopen is an internationally approved communication protocol which is designed for commercial and industrial automation applications. High data transfer rates in connection with efficient data formatting provide for the coordination of motion control devices in multi-axis applications.

General information			
Version		Optionally Integrated in standard I/O	
DC supply of the control electronics and optional fieldbus		Internally via the inverter	Network-dependent
		Alternatively: External supply	Network-independent 24 V DC an X3/24E...GND

Bus-related information			
Name		CANopen CiA 301 V4.2.0	
Communication medium		CAN cable in accordance with ISO 11898-2	
Use		Connection of inverter to a CANopen network	
Connection system		Pluggable double spring terminal	
Status display		2 LEDs	
Connection designation		X216: CH, CL, CG	

Technical data			
Bus terminating resistor	Ω	120	Terminated on both sides
integrated bus terminating resistor		Yes	Activation via DIP switch
Network topology			
without repeater		Line	
with repeater		Line or tree	
Station			
Type		Slave	
Max. number without repeater		127	per bus segment, incl. host system
Address		1 ... 127	Adjustable via code or DIP switch
Baud rate	kbps	20, 50, 125, 250, 500, 800 or 1000	Adjustable via code or DIP switch
Max. bus length	m	2500, 1000, 500, 250, 100, 50 or 25	Total cable length depends on the baud rate
Max. cable length between two nodes		not limited, the max. bus length is decisive	
Process data			
Transmit PDOs		3 TPDOs with 1 … 8 bytes (adjustable)	
Receive PDOs		3 RPDOs with 1 … 8 bytes (adjustable)	
Transmission mode for TPDOs			
With change of data		Yes	
Time-controlled, multiple of	ms	10	
After reception		1 … 240 sync telegrams	
Parameter data			
SDO channels		Max. 2 servers	

Communication time			
Communication time depends on		Processing time in the inverter	Time between start of a request and arrival of response
		Telegram runtime (baud rate, telegram length)	
		Nesting depth of network	
		Bus load	



Processing time of process data			
Update cycle	ms	10	In inverter
Processing time	ms	0 ... 1	
Application task runtime of the technology application used (tolerance)	ms	1 ... x	

Other data
Note: There are no interdependencies between parameter data and process data.

Modbus RTU

Modbus is an internationally approved, asynchronous, serial communication protocol, designed for commercial and industrial automation applications.

General information			
Version		Optionally Integrated in standard I/O	
DC supply of the control electronics and optional fieldbus		Internally via the inverter	Network-dependent
		Alternatively: External supply	Network-independent 24 V DC an X3/24E...GND

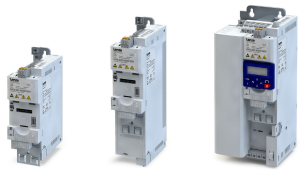
Bus-related information			
Name		Modbus RTU	
Communication medium		RS485 (EIA)	
Use		Connection of inverter to a Modbus network	
Connection system		Pluggable double spring terminal	
Status display		2 LEDs	
Connection designation		X216: TA, TB, COM	

Technical data			
Communication profile		Modbus RTU	
Bus terminating resistor	Ω	120	Terminated on both sides
Integrated bus terminating resistor		Yes	Activation via DIP switch
Network topology			
Without repeater		Line	
Station			
Type		Slave	
Max. number without repeater		32	Per bus segment, incl. host system
Max. number with repeater		90	
Address		1 ... 247	Adjustable via code or DIP switch
Transfer rate	kbps	4.8 … 115	Adjustable via code or DIP switch, alternatively automatic detection via DIP switch can be activated
Max. cable length	m	12 ... 600	Per bus segment, depending on the transfer rate and the cable type used
Max. cable length between two nodes		not limited, the max. bus length is decisive	
Data channel			
SDO channels		Max. 2 servers, with 1 … 8 bytes	Supported functions: Read Holding Registers Preset Single Register Preset Multiple Registers Read/Write 4 x registers

Communication time			
Communication time depends on		Processing time in the inverter	Time between start of a request and arrival of response
		Telegram runtime (baud rate, telegram length)	
		Nesting depth of network	
		Bus load	

Processing time of process data			
Update cycle	ms	1	In the inverter
Processing time	ms	0 ... 1	
Application task runtime of the technology application used (tolerance)	ms	1 ... x	

Other data
Note: There are no interdependencies between parameter data and process data.



IO-Link

IO-Link is the standardized IO technology (IEC 61131-9) for communication with sensors and actuators. Point-to-point communication is based on the 3-wire sensor and actuator connection without additional requirements concerning the cable material.

General information			
Version		Optionally Integrated in standard I/O	
DC supply of the control electronics and optional fieldbus		Internally via the inverter	Network-dependent
		Alternatively: External supply	Network-independent 24 V DC an X3/24E...GND

Bus-related information			
Name		IO-Link V 1.1	
Communication medium		Unshielded 3-wire standard cable	
Use		Connection of the inverter to an I/O-Link Master	
Connection system		Pluggable double spring terminal	
Status display		1 LED	
Connection designation		X316: L+ (24 V) C/Q (Switching and communication line) L- (0 V)	

Technical data			
Topology			
Master - slave		Tree (point to point)	
Station			
Type		Slave	
Master - slave		1:1	
Baud rate	kbps	230.4	COM3
Max. input current	mA	200	Port Class A (type A)
Max. cable length between IO-Link master and IO-Link slave (i550)	m	20	
Process data			
Input		12 Byte / 6 Byte	Can be defined by selecting the IODD (12 bytes or 6 bytes).
Output		12 Byte / 6 Byte	

Processing time of process data			
Cycle time	ms	2	

PROFIBUS

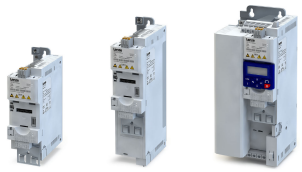
PROFIBUS is a common fieldbus for the connection of inverters to different control systems in plants.

General information			
Version		Optionally Integrated in standard I/O	
DC supply of the control electronics and optional fieldbus		Internally via the inverter	Network-dependent
		Alternatively: External supply	Network-independent 24 V DC an X3/24E...GND

Bus-related information			
Name		PROFIBUS-DP	
Communication medium		RS485	
Use		Connection of the inverter to a PROFIBUS-DP network	
Connection system		9-pole Sub-D socket	
Status display		2 LEDs	
Connection designation		X226: Pin 1 … 9	

Technical data			
Communication profile		PROFIBUS-DP-V0	DRIVECOM parameter data channel
		PROFIBUS-DP-V1	PROFIdrive parameter data channel
Bus terminating resistor	Ω	120	Terminated on both sides
integrated bus terminating resistor		No	
Network topology			
Without repeater		Line	
With repeater		-	
Station			
Type		Slave	
Max. Number without repeater		32	per bus segment, incl. host system
Max. Number with repeater		125	
Address		1 ... 127	Adjustable via code or DIP switch
Transfer rate	kbps	9.6 ... 12000	Automatic detection for cable type A (EN 50170)
Max. Bus length	m	1200	Per bus segment, depending on the transfer rate and the cable type used
Max. Cable length between two nodes		not limited, the max. bus length is decisive	
Process data			
PZD		1 ... 16 words (16 bits/word) per direction	Max. 32 bits (4 bytes) as a coherent PDO object
Transmission mode			
Data length, cyclic		1 ... 16 words, process data channel + 4 words of disconnectable parameter data channel	
Identification number		0x0E550	
User data			
Cyclic (DP-V0)		4 bytes	
Acyclic (DP-V1)		Max. 240 bytes	

Communication time			
Communication time depends on		Processing time in the inverter	Time between start of a request and arrival of response
		Telegram runtime (baud rate, telegram length)	
		Nesting depth of network	
		Bus load	



Processing time of process data			
Update cycle	ms	1	In the inverter
Processing time	ms	0 ... 1	
Application task runtime of the technology application used (tolerance)	ms	1 ... x	

Other data
Note: There are no interdependencies between parameter data and process data.

EtherCAT

EtherCAT® (Ethernet for Controller and Automation Technology) is an Ethernet-based fieldbus system which fulfils the application profile for industrial plant systems.

General information			
Version		Optionally Integrated in standard I/O	
DC supply of the control electronics and optional fieldbus		Internally via the inverter	Network-dependent
		Alternatively: External supply	Network-independent 24 V DC an X3/24E...GND

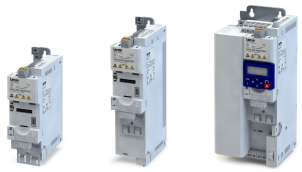
Bus-related information			
Name		EtherCAT	
Communication medium		Ethernet 100 Mbps, full duplex	
Use		Connection as EtherCAT slave	
Status display		2 LEDs (RUN, ERR)	
Connection designation		IN: X246 OUT: X247	

Technical data			
Communication profile		EtherCAT	
		CANopen over EtherCAT	
Safety over EtherCAT (FSoE)		No	
Vendor ID [hex]		0x3B	
Network topology		Line, tree ring	
Device			
Type		EtherCAT slave	
Max. number		65535	In the entire network
Address		Automatically assigned by the master	
Max. cable length	m	Not limited	The length between the devices is decisive.
Max. cable length between two devices	m	100	
Process data			
Transmit PDOs		0 ... 16 double words	Max. 64 bytes
Receive PDOs		0 ... 16 double words	
Cycle time	ms	Integer multiple of 1 ms	

Communication time			
Communication time depends on		Processing time in the inverter	Time between start of a request and arrival of response
		Telegram runtime (baud rate, telegram length)	
		Nesting depth of network	
		Bus load	

Processing time of process data			
Update cycle	ms	1	In the inverter
Processing time	ms	0 ... 1	
Application task runtime of the technology application used (tolerance)	ms	1 ... x	

Other data
Note: There are no interdependencies between parameter data and process data.



EtherNet/IP

EtherNet/IP is a common fieldbus for the connection of inverters to different control systems in plants.

General information			
Version		Optionally Integrated in standard I/O	
DC supply of the control electronics and optional fieldbus		Internally via the inverter	Network-dependent
		Alternatively: External supply	Network-independent 24 V DC an X3/24E...GND

Bus-related information			
Name		EtherNet/IP	
Communication medium		Ethernet 10 Mbps, 100 Mbps, half duplex, full duplex	
Use		Connection as EtherNet/IP adapter	
Status display		2 LEDs (CIP Module Status, CIP Network Status)	
Connection designation		X266, X267	

Technical data			
Communication profile		EtherNet/IP	
		AC Drive	
Bus terminating resistor		Not required	
integrated bus terminating resistor		No	
Network topology			
Without repeater		Line, tree, ring	
With repeater		-	
Device			
Type		Adapter (slave)	
Max. Number		254	Per subnetwork
Address		Station name	
Max. Cable length	m	-	Not limited The length between the TNs is decisive.
Max. cable length between two devices	m	100	
Process data			
Transmit PDOs		16 words	Max. 32 bits (4 bytes) as a coherent PDO object
Receive PDOs		16 words	
Cycle time	ms	> 4	
Switching method		Store-and-Forward Cut-Through	
Switch latency	µs	~ 125	At maximum telegram length
Other data		Additional TCP/IP channel	

Communication time			
Communication time depends on		Processing time in the inverter	Time between start of a request and arrival of response
		Telegram runtime (baud rate, telegram length)	
		Nesting depth of network	
		Bus load	

Processing time of process data			
Update cycle	ms	1	In the inverter
Processing time	ms	0 ... 1	
Application task runtime of the technology application used (tolerance)	ms	1 ... x	

Other data
Note: There are no interdependencies between parameter data and process data.

Modbus TCP

Modbus is an internationally approved Ethernet-based communication protocol, designed for commercial and industrial automation applications.

General information			
Version		Optionally Integrated in standard I/O	
DC supply of the control electronics and optional fieldbus		Internally via the inverter	Network-dependent
		Alternatively: External supply	Network-independent 24 V DC an X3/24E...GND

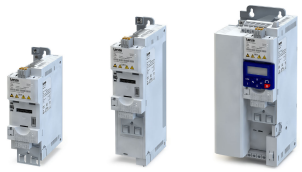
Bus-related information			
Name		Modbus TCP	
Communication medium		Ethernet 10 Mbps, 100 Mbps, half duplex, full duplex	
Use		Connection as Modbus TCP slave	
Status display		2 LEDs	
Connection designation		Port 1: X276 Port 2 X277	

Technical data			
Communication profile		Modbus/TCP	
Bus terminating resistor		Not required	
integrated bus terminating resistor		No	
Network topology			
Without repeater		Line, tree, ring	
With repeater		-	
Device			
Type		Adapter (slave)	
Max. Number		254	Per subnetwork
Address		Station name	
Max. Cable length	m	-	Not limited. The length between the devices is decisive.
Max. cable length between two devices	m	100	
Process data			
Transmit PDOs		256 bytes	
Receive PDOs		256 bytes	
Cycle time	ms	> 4	
Switching method		-	
Switch latency	µs	~ 125	At maximum telegram length
Other data		Additional TCP/IP channel	

Communication time			
Communication time depends on		Processing time in the inverter	Time between start of a request and arrival of response
		Telegram runtime (baud rate, telegram length)	
		Nesting depth of network	
		Bus load	

Processing time of process data			
Update cycle	ms	1	In the inverter
Processing time	ms	0 ... 1	
Application task runtime of the technology application used (tolerance)	ms	1 ... x	

Other data
Note: There are no interdependencies between parameter data and process data.



POWERLINK

Ethernet POWERLINK is a common fieldbus for the connection of inverters to different control systems in plants.

General information			
Version		Optionally Integrated in standard I/O	
DC supply of the control electronics and optional fieldbus		Internally via the inverter	Network-dependent
		Alternatively: External supply	Network-independent 24 V DC an X3/24E...GND

Bus-related information			
Name		Ethernet POWERLINK	
Communication medium		Ethernet 100 Mbps, half duplex	
Use		Connection of the inverter to a POWERLINK network	
Connection system		RJ45	
Status display		2 LEDs	
Connection designation		IN: X286 OUT: X287	

Technical data			
Communication profile		POWERLINK	
		AC Drive	
Bus terminating resistor		Not required	
integrated bus terminating resistor		No	
Network topology			
Without repeater		Tree, star and line	
With repeater		-	
Station			
Type		Adapter (controlled node, CN)	
Max. Number		240	
Address		Station name	
Max. Cable length	m	-	Not limited The length between the nodes is decisive.
Max. Cable length between two nodes	m	100	
Process data			
Transmit PDOs		4 words	Max. 16 bits (2 bytes) as a coherent PDO object
Receive PDOs		2 words	
Cycle time	ms	Multiple of 0.4 ms and 0.5 ms	
Other data		Additional TCP/IP channel	

Communication time			
Communication time depends on		Processing time in the inverter	Time between start of a request and arrival of response
		Telegram runtime (baud rate, telegram length)	
		Nesting depth of network	
		Bus load	

Processing time of process data			
Update cycle	ms	1	In the inverter
Processing time	ms	0 ... 1	
Application task runtime of the technology application used (tolerance)	ms	1 ... x	

Other data
Note: There are no interdependencies between parameter data and process data.

PROFINET

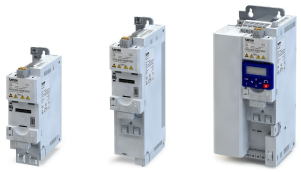
PROFINET is a common fieldbus for the connection of inverters to different control systems in plants.

General information			
Version		Optionally Integrated in standard I/O	
DC supply of the control electronics and optional fieldbus		Internally via the inverter	Network-dependent
		Alternatively: External supply	Network-independent 24 V DC an X3/24E...GND

Bus-related information			
Name		PROFINET RT	
Communication medium		Ethernet 100 Mbps, full duplex	
Use		Integration as PROFINET IO-Device	
Status display		2 LEDs (Ready, Error)	
Connection designation		X256, X257	

Technical data			
Communication profile		PROFINET	
Bus terminating resistor		Not required	
Integrated bus terminating resistor		Yes	
Network topology			
Without repeater		Line, tree, ring	
With repeater		-	
Device			
Type		IO device with real time (RT) communication properties Conformance Class B	
Max. Number		255	Per subnetwork
Address		Station name	
Max. Cable length	m	Not limited	The length between the devices is decisive.
Max. cable length between two devices	m	100	
Process data	Byte	4, 8, 12, 16, 20, 24, 28, 32, ..., 64	
Cycle time	ms	1, 2, 4, 8, 16	
Switching method		Cut-through	
Other data		Additional TCP/IP channel	

Other data
Note: There are no interdependencies between parameter data and process data.



Functional safety

General information and basics

The functional safety describes the necessary measures that need to be taken by means of electrical or electronic equipment to prevent or eliminate dangers due to functional errors.

Protective devices prevent any human access to dangerous areas during normal operation. However, persons may have to be in the danger areas in certain operating modes. The machine operator is protected by internal drive and control measures in these operating modes.

Integrated safety

Integrated safety provides the conditions in the controls and drives to implement protective functions. Planning and installation expenditure is reduced. Using integrated safety increases machine functionality and availability. Integrated safety can be used for the protection of persons working on machines in accordance with the Machinery Directive.

Integrated safety provides safe inputs. If the STO safety function is requested, the safety system immediately brings about the torque-free state according to EN 61800-5-2.

Standards

Safety regulations are confirmed by laws and other governmental guidelines and measures and the prevailing opinion among experts, e.g. by technical regulations.

The regulations and rules to be applied must be observed in accordance with the application.

Risk assessment

This documentation can only accentuate the need for a risk assessment. The user of the integrated safety system must read up on standards and the legal situation.

Before a machine can be put into circulation, the manufacturer of the machine has to conduct a risk assessment according to the 2006/42/EC: Machinery Directive [UKCA: S.I. 2008/1597 - The Supply of Machinery (Safety) Regulations 2008] to determine the hazards associated with the use of the machine.

The Machinery Directive refers to three basic principles for the highest possible level of safety:

- Hazard elimination / minimisation by the construction itself.
- Taking the protective measures required against hazards that cannot be removed.
- Existing residual hazards must be documented and the user must be informed of them.

Detailed information on the risk assessment is provided in the DIN EN ISO 12100:2013-08: Safety of machinery − General principles for design − Risk assessment and risk reduction . The result of the risk assessment determines the category for safety-related control systems according to EN ISO 13849-1. Safety-oriented parts of the machine control must be compliant.

Mission time

The mission time of the used components must be complied with.

In case of a defect or when the mission time of a component has expired, the complete component must be replaced. Continued operation is not permitted!

The mission time for the safety functions cannot be reset by a special proof test.

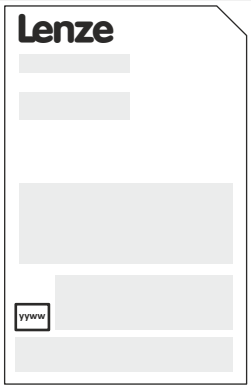
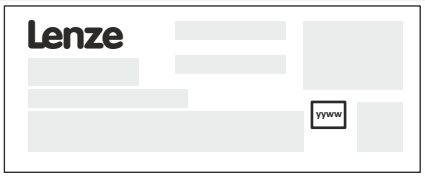
The specified mission time starts at the date of manufacture.

Mission time ▸ Technical data 🕮 215

i550-Cabinet

- If you have mounted the safety module yourself, you must observe the manufacturing date of the safety module and the manufacturing date of the device.
- If you have a completely mounted device, you only have to observe the manufacturing date of the device.

The manufacturing date can be found on the nameplate of the respective component:

Manufacturing date of the device	Manufacturing date of the safety module
	
yyww = year of manufacture and week of manufacture (1841 = CW 41 2018)	

Identification of the components

Safety components and the respective terminals are yellow.

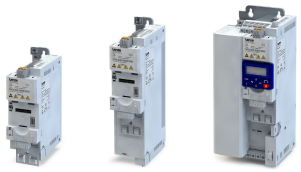
Restart

⚠ DANGER!

The drive can automatically restart if the request of the safety function is deactivated.

Possible consequence: Death or severe injuries

▶ You must provide external measures according to EN ISO 13849-1 which ensure that the drive only restarts after a confirmation.



Safe inputs

The components used must comply with the risk reduction required for the application.

Active sensors
Active sensors are units with 2-channel semiconductor outputs (OSSD outputs).

Test pulses for monitoring the outputs and lines are permissible.

P/M-switching sensors switch the positive and negative cable or the signal and ground cable of a sensor signal.

Please note the following:

- The maximum permissible connection capacity of the outputs.
- Active sensors are connected directly to the terminal strip, see section "Active sensor connection".
- Monitoring for short circuits must be carried out by the active sensor.

The outputs have to switch simultaneously (equivalently). Safety functions will be activated if only one channel is switched. Active triggering of only one channel points to faulty sensors or impermissible wiring.

Examples of active sensors:

- Lightgrid
- Laser scanner
- Control systems

Passive sensors
Passive sensors are 2-channel switching elements with contacts.

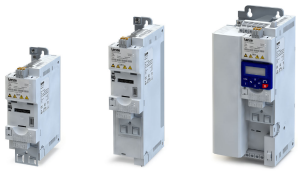
Please note the following:

- The switches must be wired according to the closed-circuit principle.
- Passive sensors are connected to the terminal strip via a safety switching device, see section “Passive sensor connection”.
- An external safety component must monitor the connecting cables and the function of the sensors if complete exclusion of faults cannot be guaranteed.

The contacts must switch at the same time (equivalent). Safety functions will be activated if only one channel is switched. Switching of only one channel points to faulty sensors or impermissible wiring.

Examples of passive sensors:

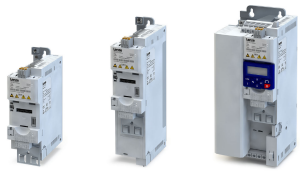
- Door contact switch
- Emergency stop control units



Safety functions

Supported safety functions for "Basic Safety - STO"

- Safe torque off (STO) 📖 212



Safe torque off (STO)

This function corresponds to a "Stop 0" according to EN 60204.

The motor cannot generate torque and movements of the drive.

⚠ DANGER!

With the "Safe torque off" (STO) function, no "emergency switching off" in terms with EN 60204-1 can be executed without additional measures. There is no electrical isolation between the motor and inverter and no service switch or maintenance switch!

Possible consequence: Death or severe injuries

- ▸ "Emergency switching off" requires electrical isolation, e. g. by a central mains contactor.

⚠ DANGER!

The power supply is not safely disconnected.

Possible consequence: Death or serious injury due to electrical voltage

- ▸ Turn off the power supply.

⚠ DANGER!

Automatic restart if the request of the safety function is deactivated.

Possible consequence: Death or severe injuries

- ▸ You must provide external measures according to EN ISO 13849-1 which ensure that the drive only restarts after a confirmation.

Functional description

How to safely disconnect the drive:

1. A safety sensor requests the safety function.
2. The transmission of the pulse width modulation is safely switched off by the safety unit. The power drivers do not generate a rotating field anymore.
3. The inverter switches to the STO active device status (status word 0x6041, Bit15 = 0).

The motor is safely switched to torqueless operation (STO).

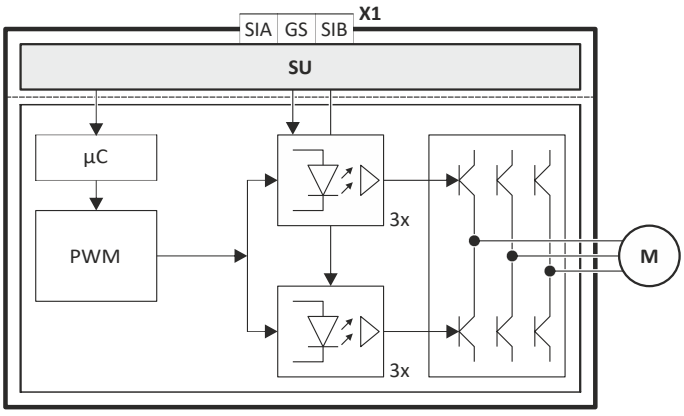


Fig. 8: Functional principle: Basic Safety - STO

X1	Control terminals of the safety unit	PWM	Pulse width modulation
SU	Hardware interface	M	Motor
µC	Microcontroller		

Function chart

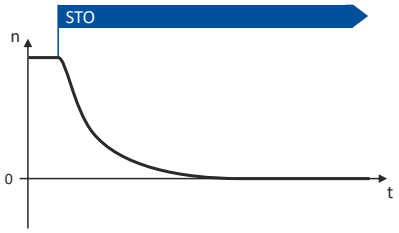


Fig. 9: Safety function STO

Functional sequence and error response have no adjustable parameters.

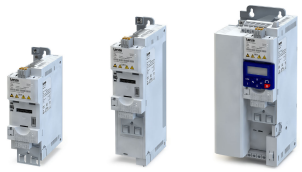
When assessing risk, also take into account overtravel distances.

Truth table

Safe input / channel		Inverter	Inverter status word 0x282A:004		CiA status word
SIA	SIB	Device state	Bit 10	Bit 11	Object 0x6041, bit 15
LOW	LOW	STO active	1	1	0
LOW	HIGH	Impermissible state, drive disabled	1	0	0
HIGH	LOW		1	0	0
HIGH	HIGH	Drive enabled	0	0	1

If the GS connection is interrupted, or in case of a short circuit/cross-circuit of GS to SIA/SIB, STO is active.

If SIA = LOW and SIB = LOW, the internal "Safe torque off (STO) active [55]" status signal in the inverter is set to TRUE. You can use this status signal to control a "non-safe output" (e.g. the relay).



Acceptance

The machine manufacturer must check and prove the operability of the safety functions used.

- The machine manufacturer must authorise a person with expertise and knowledge of the safety functions to carry out the test.
- The test result of every safety function must be documented and signed by the inspector.

A complete test comprises the following:

- Documenting the plant including the safety functions:
  - Creating an overview screen of the plant.
  - Describing the plant.
  - Describing the safety equipment.
  - Documenting the safety functions used.
  - Checking the function of the safety functions used.
- Preparing the test report:
  - Documenting the functional test.
  - Checking the parameters.
  - Signing the test report.
- Preparing the appendix with test records:
  - Protocols for the plant
  - External recording

The tester must repeat the test after each change and record the results in the test report.

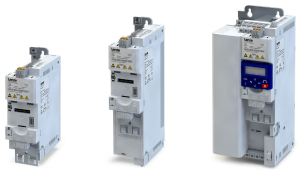
Periodic inspections

After installation and after every modification, the user must check and validate the safety function.

The user must document these tests.

The correct sequence of the safety−oriented functions must be checked in periodic inspections. The risk analysis or applicable regulations determine the time distances between the tests.

The inspection interval should not exceed one year.



Technical data

Safety-related characteristics Basic Safety - STO

The data applies to products delivered **after** 1st September 2016.

Safety-related characteristics according to EN 61508, Part 1-7 and EN 62061

Specification	Value	Comment
Safety Integrity Level	SIL 3	
PFH [1/h]	1.71 E−09	1.71 % of SIL 3
PFD_{avg} (T)	1.49 E−04	14.9 % of SIL 3 after T = 20 years
Proof test interval	20 years	Mission time

Safety-related characteristics according to EN ISO 13849-1

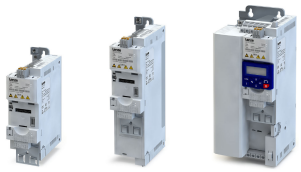
Specification	Value	Comment
Performance Level	e	
Category	4	
$MTTF_d$	High	3200 years
Mean diagnostic coverage DC_{av}	High	99 %

Basics of the safety-related characteristics

Basics	Value	Comment
Source of failure rates	SN 29500	When no values from the component manufacturers were available.
Average max. ambient temperature	40 °C	

Further data and information

Electrical installation ▸ Functional safety 🕮 76

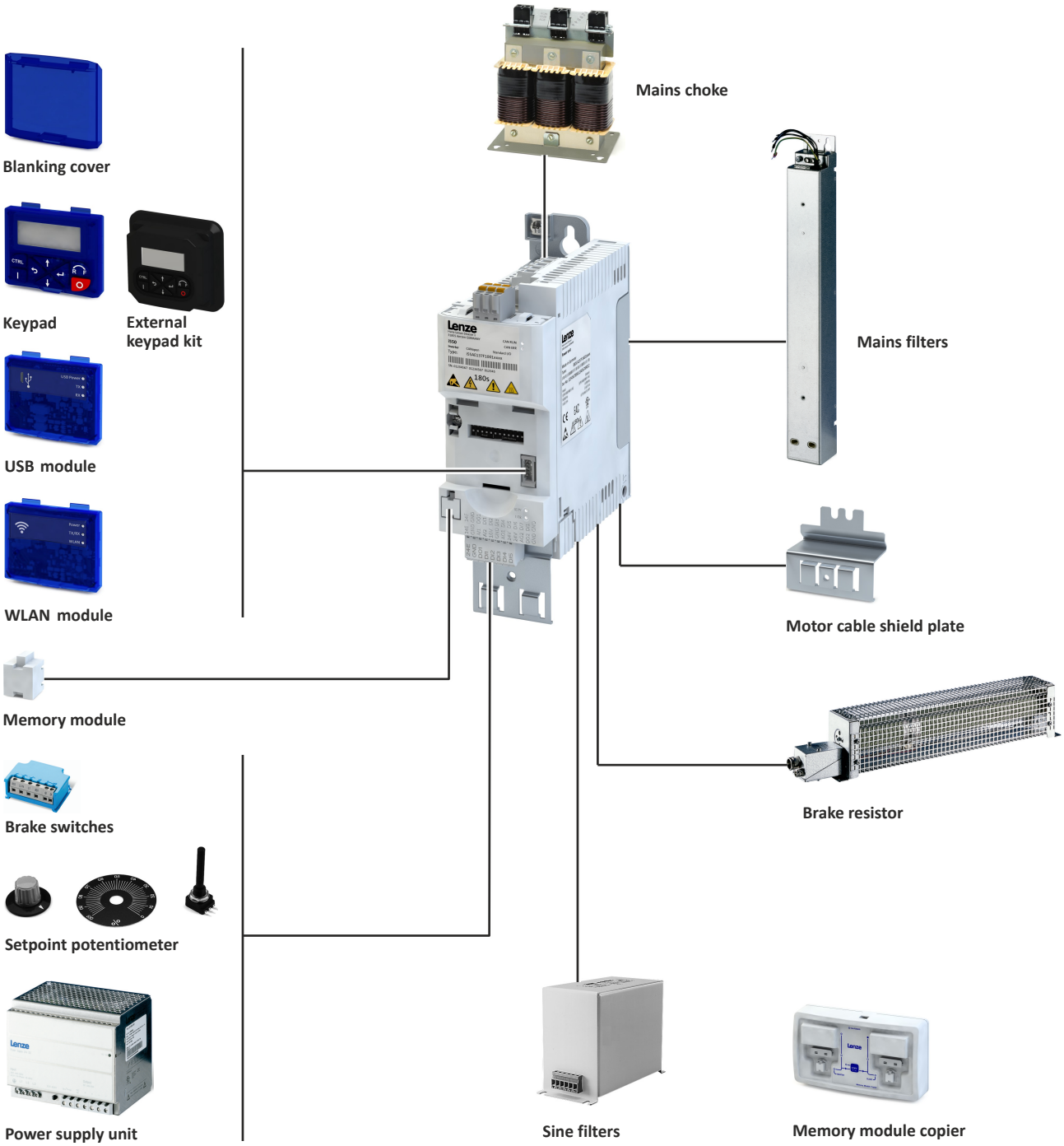


Accessories

Overview

A package of accessories optimally matched to the inverter is available for your applications.

Moreover, the pluggable modules make commissioning and diagnostics easier.



Further accessories: DIN rail, terminal strips and latching terminals for the shield sheet of the control unit.

Operation and diagnostics

Keypad

Parameter setting and diagnostics

Thanks to the intuitive operating structure, the navigation keys allow a quick and easy access to the most important parameters, either to configure functions or to query current values. Parameters and actual values are indicated on the easy-to-read display.

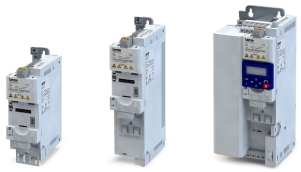
Keypad	
Order code	**Type**
I5MADK0000000S	LCD display Display in German/English

External keypad

Installation in user interface

The external keypad kit facilitates installation of a I5MADK000000S keypad in an IP65 housing for mounting to the control cabinet wall.

External keypad kit	
Order code	**Type**
I5MADR0000000S I5MADR0000001S I5MADR0000002S	without connecting cable with connecting cable 3 m with connecting cable 5 m
The I5MADK000000S keypad is not part of the delivery.	



USB module

Interface to the PC

Connect the inverter via a USB 2.0 connection cable to a PC on which the Lenze "EASY Starter" engineering tool is installed. Configure the inverter with the "EASY Starter" using graphical user interfaces. You can create diagnostics with trend functions or observe parameter values.

Parameterising without supplying the inverter with voltage: in many cases, the USB interface of the PC is sufficient for the voltage supply if you connect the inverter directly to the PC without a hub.

USB module	
Order code	**Version**
I5MADU0000000S	Parameterization without voltage supply of the inverter is possible. USB 2.0 connecting cable required

Connecting cable		
Order code	**Length**	**Type**
EWL0085/S	3 m	USB 2.0-connecting cable (A-plug to micro B-plug)
EWL0086/S	5 m	

Inverters with network option EtherCAT, PROFINET or EtherNET/IP must be supplied with an additional voltage for setting parameters if a connection cable longer than 3 m is used.

Please observe the following for USB modules labelled as "PRE-SERIES": Inverters with network option EtherCAT, PROFINET or EtherNET/IP must always be supplied with an additional voltage for setting parameters.

WLAN module

Communicate wirelessly with the inverter, via a PC using the Lenze Engineering Tool "EASY Starter" or the Lenze "SMART Keypad App" for Android and iOS smartphones.

⚠WARNING!

- This product contains FCC ID: QOQWF121/IC: 5123A-BGTWF121
- To comply with FCC and Industry Canada RF radiation exposure limits for general population, the transmitter with its antenna must be installed such that a minimum separation distance of 20 cm is maintained between the radiator (antenna) and all persons at all times.
- This product must not be collocated or operated in conjunction with any other antenna or transmitter.
- -
- Le produit contient un module transmetteur certifié FCC ID: QOQWF121/IC: 5123A-BGTWF121
- Afin de se conformer aux réglementations de la FCC et d'Industry Canada relatives aux limites d'exposition aux rayonnements RF pour le grand public, le transmetteur et son antenne doivent être installés de sorte qu'une distance minimale de 20 cm soit constamment maintenue entre le radiateur (antenne) et toute personne.
- Le produit ne doit pas être utilisé en combinaison avec d'autres antennes ou transmetteurs.

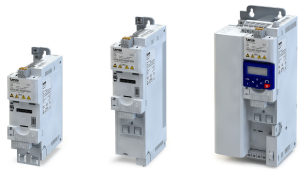
The module can be used if the certification is recognized in a country according to one of these standards.

Conformity and approvals		
CE	RED	EN 301489-1 V2.1.1:2016
		EN 301489-17 V3.1.1:2016
		EN 300328 V2.1.1:2016
FCC	Part 15.107/15.109 ICES-003	

Additional conformities and approvals:

- IC
- CMIIT

LED status displays			
LED 1	**LED 2**	**LED 3**	**Meaning**
Power (green)	**TX/RX (yellow)**	**WLAN (green)**	
Supply voltage status	**Communication status**	**WLAN status**	
OFF	OFF	OFF	No voltage
ON	ON	ON	Self-test (approx. 1 s)
ON	OFF	OFF	Ready for operation No active WLAN connection
ON	Flashing	ON	Communication active
ON	OFF	Blinking	Client Mode Waiting for connection
Blinking	OFF	OFF	Trouble



Connection data (default setting)	
IP address	192.168.178.1
SSID	<Product type>_<10-digit identifier>
Password	password

WLAN module	
Order code	**Type**
I5MADW0000000S	Range in open space: 100 m, conditions on site may restrict the range.

Blanking cover

Protection and optics

The blanking cover protects the terminals and provides for uniform optics if no other module is plugged on.

Blanking cover		
Order code	**Type**	**VPE**
		Piece
I5ZAA0000M	Protection against dust Uniform optics	4

Control and display elements

Potentiometer

For the external selection of an analog setpoint.

The setpoint selection (e.g. motor speed) can be manually set via the external potentiometer. The potentiometer is connected to the analog input terminals of the inverter.

The position is displayed on the scale via the rotary knob.

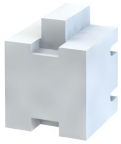
The components have to be ordered separately.

Potentiometer		
Order code	**Name**	**Type**
ERPD0010K0001W	Potentiometer	10 kΩ/1 W
ERZ0001	Rotary knob	Diameter 36 mm
ERZ0002	Scale	Scale 0 ... 100 %, Diameter 62 mm

Memory modules

For standard set-up, Lenze offers its customers multipacked, unwritten memory modules (EPM). In combination with the EPM copier, the EPMs can be duplicated at any location.

A memory module is included in the scope of supply of the inverter.



Memory module		
Order code	**Type**	**VPE**
		Piece
I0MAPA0000000M	Easily pluggable Duplicate data set with memory module copier	12

Memory module copier

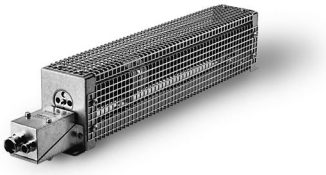
For duplicating data on memory modules for a faster standard set-up.

The memory module copier is a copying system for all memory modules from Lenze. With the help of simple optical user guidance, the data of a module is copied quickly and reliably to another memory module.

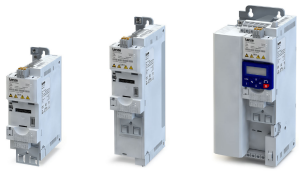
Memory module copiers	
Order code	**Type**
EZAEDE1001	Data set copier for memory modules

Brake resistors

- To decelerate greater moments of inertia or with a longer operation in generator mode an external brake resistor is required.
- The brake resistor absorbs the produced brake energy and converts it into heat.



The matching assignment of these accessories is specified in the technical data of the devices.



Mains chokes

- Mains chokes reduce the feedback effects of the inverter on the supplying mains by their high inductive resistance reducing high-frequency interference.
- The effective mains current is reduced which saves energy.
- Mains chokes can be used without restrictions in conjunction with RFI filters.
- Please note that the use of a mains choke reduces the mains voltage at the input of the inverter by4 % (typical voltage drop across the mains choke in the rated point).

Inverters above a certain power must always be operated on mains chokes. The inverters for which this is the case are specified in the technical data of the devices.

The matching assignment of these accessories is specified in the technical data of the devices.

RFI filters / Mains filters

RFI and mains filters are used to ensure compliance with the EMC requirements of EN IEC 61800-3. This standard defines the EMC requirements for electrical drive system in various categories.

- RFI filters are capacitive accessory components. RFI filters reduce conducted noise emissions. RFI filters are also called EMC filters.
- Mains filters are a combination of mains choke and RFI filter. Mains filters reduce the conducted noise emission.

Definition of the environments
(EN IEC 61800-3)

First environment
The first environment comprises residential buildings or locations that are directly connected to a low-voltage system for supplying residential areas.

Second environment
The second environment comprises facilities or locations that are not directly connected to a low-voltage system for supplying residential areas.

Category C1
Category C1 defines the requirements for drive systems that are intended for the use in the first environment at a rated voltage lower than 1000 V.

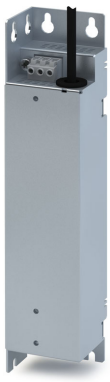
The limit values of the EN IEC 61800-3 comply with EN 55011 class B.

Category C2
Category C2 defines the requirements for permanently installed fixed drive systems that are intended for the use in the first environment at a rated voltage lower than 1000 V. Installation and commissioning may only be carried out by specialist personnel with EMC knowledge.

The limit values of the EN IEC 61800-3 comply with EN 55011 class A group 1.

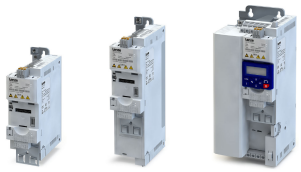
Category C3
Category C3 defines the requirements for drive systems that are exclusively intended for the use in the second environment at a rated voltage lower than 1000 V.

The limit values of the EN IEC 61800-3 comply with EN 55011 class A group 2.



When working with stricter line-bound noise emission requirements which cannot be met using the radio interference suppression measures integrated in the inverter, external filters can be used. The filters can be installed below or next to the inverter.

If necessary, the internal filters have to be deactivated when external filters are used. For this purpose, remove the IT screws of the inverters.



Comparison of integrated and external RFI filters

RFI filter	Filter types			
	Integrated in the inverter	External		
		Low Leakage	Short Distance	Long Distance
Use	In standard applications	In mobile systems	With short cable length	At switching frequencies 4 kHz and 8 kHz.
Optimization	Easy use	For low leakage current	For low leakage current	For long motor cable
Reduces noise emissions	Cable-guided and radiated	Cable-guided	Cable-guided	Cable-guided

The matching assignment of these accessories is specified in the technical data of the devices.

Sine filter

A sinusoidal filter in the motor cable limits the rate of voltage rise and the capacitive charge/discharge currents between the conductors that occur during inverter operation.

Only use a sinusoidal filter with standard asynchronous motors 0 to 550 V.

Operation only with V/f or square-law V/f characteristic control.

Set the switching frequency permanently to the specified value.

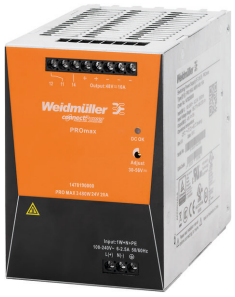
Limit the output frequency of the inverter to the given value.

The matching assignment of these accessories is specified in the technical data of the devices.

Power supply units

For the external supply of the control electronics of the inverter.

The parameterization and diagnostics can be executed when the mains input at the inverter is deenergized.



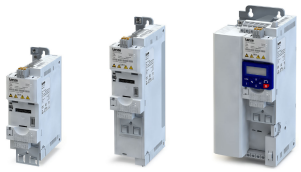
Order code			EZVA024				
			005BB000000	010BB000000	005FB000000	010FB000000	020FB000000
Mains connection			1 AC 230/240 V		2 oder 3 AC 400/480 V		
Netzspannungsbereich		V	85 ... 277		360 ... 575		
Rated current		A	1	1.5	0.3	0.4	0.85
Rated output voltage		V	24				
Ausgangsspannungsbereich		V	22.5 ... 29.5				
Rated output current		A	5	10	5	10	20
Degree of protection			IP20				
Abmessungen (H x B x T)		mm	130 x 40 x 125	130 x 60 x 125	130 x 40 x 125	130 x 60 x 125	130 x 70 x 150
Weight		kg	0.86	1.05	0.78	1.32	1.6

Brake switches

For switching an electromechanical brake.

The brake switch consists of a rectifier and an electronic circuit breaker. It is mounted on the control cabinet plate. Control is performed using a digital output on the inverter.

Brake switches		Half-wave rectifiers	Bridge rectifiers
Order code		E82ZWBRE	E82ZWBRB
Input voltage	V	AC 320 - 550	AC 180 - 317
Output voltage	V	DC 180 (with AC 400) DC 225 (with AC 500)	DC 205 (with AC 230)
Max. brake current	A	0.61	0.54



Mounting

Shield mounting kit

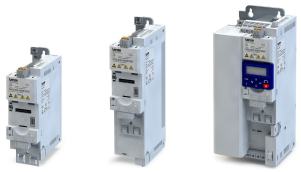
Motor cable

If the shielding of the motor cable is centrally connected to an earthing busbar in the control cabinet, no shielding is required.

For a direct connection of the shielding of the motor cable to the inverter, the optionally available accessories can be used consisting of shield sheet and fixing clips or wire clamps.

From 15 kW, the shield sheet is integrated.

Inverter	Shield mounting			
	Order code	Packaging unit	Order code	Packaging unit
		Piece		Piece
i550-C0.25/120-1 i550-C0.37/120-1 i550-C0.75/120-1 i550-C1.1/120-1	EZAMBHXM018/M	5x motor shield plate 5x fixing clip 5x terminal clamp (cable diameter 4 ... 15 mm)	EZAMBHXM018/S	1x motor shield plate 1x fixing clip 1x terminal clamp (cable diameter 4 ... 15 mm)
i550-C0.25/230-1 i550-C0.25/230-2 i550-C0.37/230-1 i550-C0.37/230-2 i550-C0.55/230-1 i550-C0.55/230-2 i550-C0.75/230-1 i550-C0.75/230-2 i550-C1.1/230-1 i550-C1.1/230-2 i550-C1.5/230-1 i550-C1.5/230-2 i550-C2.2/230-1 i550-C2.2/230-2	EZAMBHXM018/M	5x motor shield plate 5x fixing clip 5x terminal clamp (cable diameter 4 ... 15 mm)	EZAMBHXM018/S	1x motor shield plate 1x fixing clip 1x terminal clamp (cable diameter 4 ... 15 mm)
i550-C4.0/230-3 i550-C5.5/230-3	EZAMBHXM015/M	5x motor shield plate 5x fixing clip 5x terminal clamp (cable diameter 4 ... 15 mm) 5x screw M4x12	EZAMBHXM015/S	1x motor shield plate 1x fixing clip 1x terminal clamp (cable diameter 4 ... 15 mm) 1x screw M4x12
i550-C0.37/400-3 i550-C0.55/400-3 i550-C0.75/400-3 i550-C1.1/400-3 i550-C1.5/400-3 i550-C2.2/400-3 i550-C3.0/400-3 i550-C4.0/400-3	EZAMBHXM018/M	5x motor shield plate 5x fixing clip 5x terminal clamp (cable diameter 4 ... 15 mm)	EZAMBHXM018/S	1x motor shield plate 1x fixing clip 1x terminal clamp (cable diameter 4 ... 15 mm)
i550-C5.5/400-3	EZAMBHXM015/M	5x motor shield plate 5x fixing clip 5x terminal clamp (cable diameter 4 ... 15 mm) 5x screw M4x12	EZAMBHXM015/S	1x motor shield plate 1x fixing clip 1x terminal clamp (cable diameter 4 ... 15 mm) 1x screw M4x12
i550-C7.5/400-3 i550-C11/400-3	For type I55**A**E...: EZAMBHXM**0**16/M For type I55**B**E...: EZAMBHXM**B**16/M	5x motor shield plate 5x fixing clip 5x terminal clamp (cable diameter 10 ... 20 mm) 5x screw M4x12	For type I55**A**E...: EZAMBHXM**0**16/S For type I55**B**E...: EZAMBHXM**B**16/S	1x motor shield plate 1x fixing clip 1x terminal clamp (cable diameter 10 ... 20 mm) 1x screw M4x12
i550-C15/400-3 i550-C18.5/400-3 i550-C22/400-3	EZAMBHXM003/M	10x terminal clamp (cable diameter 10 ... 20 mm)	EZAMBHXM004/M	10x terminal clamp (cable diameter 15 ... 28 mm)
i550-C30/400-3 i550-C37/400-3 i550-C45/400-3	EZAMBHXM004/M	10x terminal clamp (cable diameter 15 ... 28 mm)	EZAMBHXM005/M	10x terminal clamp (cable diameter 20 ... 37 mm)
i550-C55/400-3 i550-C75/400-3	EZAMBHXM004/M	10x terminal clamp (cable diameter 15 ... 28 mm)	EZAMBHXM005/M	10x terminal clamp (cable diameter 20 ... 37 mm)
i550-C90/400-3 i550-C110/400-3	-	-	-	-



Shield mounting of the control cables

In case of the control unit, the shield sheet for control cables is integrated.

Usually, the shields can be fixed with standard plastic cable ties.

Optionally, fixing clips are suitable for the shield connections of the control cables of inverters 0.25 kW ... 0.75 kW.

Shield mounting kit	
Order code	**VPE**
	Piece
EZAMBHXM007/M	20x fixing clip

Terminal strips

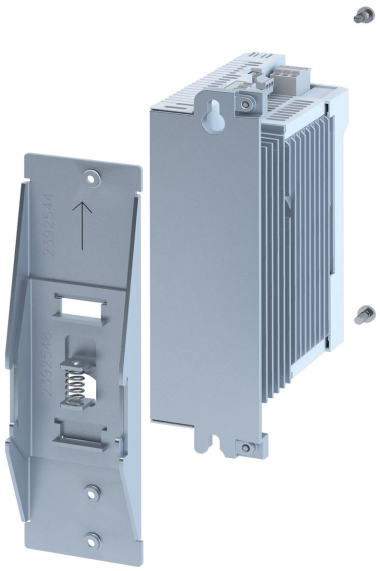
For connecting the inverter, the connections are equipped with pluggable terminal strips. Pluggable terminal strips are available separately for service purposes or if cable harnesses need to be physically separated.

Inverter	Terminal strips Mains connection X100		Terminal strips Motor connection X105	
	Order code	**VPE**	**Order code**	**VPE**
		Piece		**Piece**
i550-C0.25/230-1	EZAEVE032/M	10	EZAEVE039/M	5
i550-C0.37/230-1				
i550-C0.55/230-1				
i550-C0.75/230-1				
i550-C1.1/230-1	EZAEVE033/M			
i550-C1.5/230-1				
i550-C2.2/230-1				
i550-C0.25/230-2	EZAEVE034/M	10		
i550-C0.37/230-2				
i550-C0.55/230-2				
i550-C0.75/230-2				
i550-C1.1/230-2	EZAEVE035/M			
i550-C1.5/230-2				
i550-C2.2/230-2				
i550-C0.37/400-3	EZAEVE037/M	5		
i550-C0.55/400-3				
i550-C0.75/400-3				
i550-C1.1/400-3				
i550-C1.5/400-3				
i550-C2.2/400-3				
i550-C3.0/400-3				
i550-C4.0/400-3				

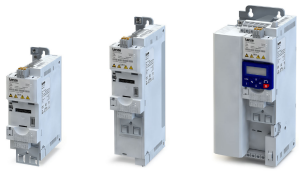
Terminal strips	Order code	VPE	Terminal strips	Order code	VPE
		Piece			**Piece**
Safety (STO) X1	EZAEVE029/M	10	Standard I/O X3	EZAEVE040/M	5
Relay X9	EZAEVE030/M	10	Application-I/O X3	EZAEVE041/M	5
Motor PTC X109	EZAEVE031/M	10	CANopen / Modbus X216	EZAEVE042/M	10

DIN rail

In accordance with EN 60175, the inverter can be mounted onto a DIN rail 35 mm x 7.5 mm.
For this purpose, a mounting set is available.



Mounting set	Can be used for inverters
Order code	Order code
I5ZAB0DR1S	I5xAE125x, I5xAE137x, I5xAE155x, I5xAE175x
I5ZAB0DR2S	I55AE175Ax, I5xAE211x, I5xAE215x, I5xAE222x, I5xxE230x, I5xxE240x, I5xxE255x

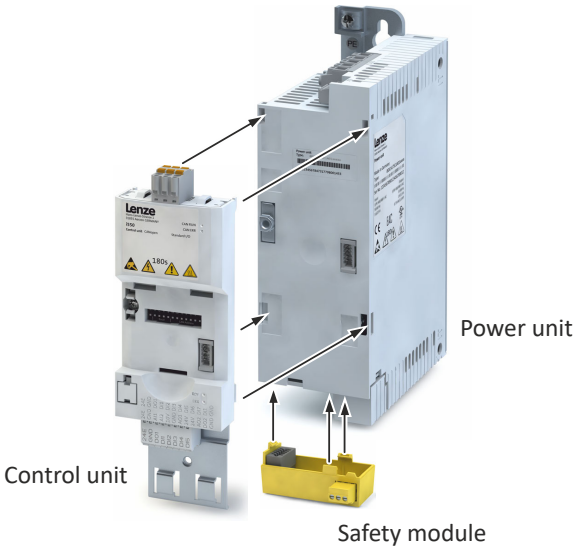


Purchase order

Notes on ordering

There are two ways to order an inverter.

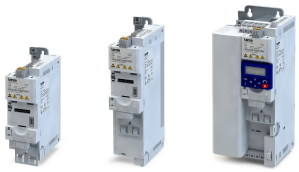
As a complete inverter or as single components consisting of power unit, control unit and safety module.

Complete inverter	Inverter consisting of components
	

»EASY Product Finder«

The »EASY Product Finder« helps you to configure your required product in next to no time. In addition, you can retrieve all important technical details such as data sheets, CAD data, and EPLAN data.

The link and the QR code lead directly to the "EASY Product Finder": EASY Product Finder



Order code

Delivery as complete inverter

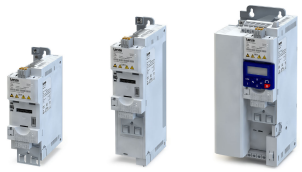
If always the same inverter is used in the machine the inverter can be ordered "out of the box".

Order data: Order code of the complete device.

Order example

Description of the component	Order code
Complete inverter	I55AE222F1AV10002S
3-phase mains connection 400 V	
Power 2.2 kW (i550-C2.2/400-3)	
Safety engineering: STO safety function	
Default setting of parameters: EU region (50-Hz systems)	
Standard I/O with CANopen	

Purchase order
Order code



i550 inverter

Complete inverter			
Power		Inverter	Order code
kW	hp		
1-phase mains connection 120 V, EMC filter not integrated			
0.25	0.33	i550-C0.25/120-1	I55AE125A1
0.37	0.5	i550-C0.37/120-1	I55AE137A1
0.75	1	i550-C0.75/120-1	I55AE175A1
1.1	1.5	i550-C1.1/120-1	I55AE211A1
1-phase mains connection 230 V, EMC filter integrated			
0.25	0.33	i550-C0.25/230-1	I55AE125B1
0.37	0.5	i550-C0.37/230-1	I55AE137B1
0.55	0.75	i550-C0.55/230-1	I55AE155B1
0.75	1	i550-C0.75/230-1	I55AE175B1
1.1	1.5	i550-C1.1/230-1	I55AE211B1
1.5	2	i550-C1.5/230-1	I55AE215B1
2.2	3	i550-C2.2/230-1	I55AE222B1
1/3-phase mains connection 230/240 V, EMC filter not integrated			
0.25	0.33	i550-C0.25/230-2	I55AE125D1
0.37	0.5	i550-C0.37/230-2	I55AE137D1
0.55	0.75	i550-C0.55/230-2	I55AE155D1
0.75	1	i550-C0.75/230-2	I55AE175D1
1.1	1.5	i550-C1.1/230-2	I55AE211D1
1.5	2	i550-C1.5/230-2	I55AE215D1
2.2	3	i550-C2.2/230-2	I55AE222D1
3-phase mains connection 230/240 V, EMC filter not integrated			
4.0	5	i550-C4.0/230-3	I55AE240C1
5.5	7.5	i550-C5.5/230-3	I55AE255C1
3-phase mains connection 400/480 V, EMC filter integrated			
0.37	0.5	i550-C0.37/400-3	I55AE137F1
0.55	0.75	i550-C0.55/400-3	I55AE155F1
0.75	1	i550-C0.75/400-3	I55AE175F1
1.1	1.5	i550-C1.1/400-3	I55AE211F1
1.5	2	i550-C1.5/400-3	I55AE215F1
2.2	3	i550-C2.2/400-3	I55AE222F1
3	4	i550-C3.0/400-3	I55BE230F1
4	5	i550-C4.0/400-3	I55BE240F1
5.5	7.5	i550-C5.5/400-3	I55AE255F1
7.5	10	i550-C7.5/400-3	I55BE275F1
11	15	i550-C11/400-3	I55BE311F1
15	20	i550-C15/400-3	I55BE315F1
18.5	25	i550-C18/400-3	I55BE318F1
22	30	i550-C22/400-3	I55BE322F1
30	40	i550-C30/400-3	I55BE330F1
37	50	i550-C37/400-3	I55AE337F1
45	60	i550-C45/400-3	I55AE345F1
55	74	i550-C55/400-3	I55AE355F1
75	100	i550-C75/400-3	I55AE375F1
90	120	i550-C90/400-3	I55AE390F1
110	150	i550-C110/400-3	I55AE411F1

Continuation ...

Complete inverter				
Power		**Inverter**	**Order code**	
kW	**hp**			
Continuation ...				
Safety engineering				
Without safety engineering				0
Safety function STO				A
Not relevant				V
EMC filter				
not integrated		i550-Cxxx/120-1 i550-Cxxx/230-2 i550-Cxxx/230-3		0
Integrated		i550-Cxxx/230-1 i550-Cxxx/400-3		1
Delivery status				
Default parameter setting: Region EU (50-Hz networks)				0
Default parameter setting: Region US (60-Hz networks)				1
Control unit				
Standard I/O without network				000S
Application I/O without network				001S
Standard I/O with CANopen				002S
Standard I/O with Modbus RTU				003S
Standard I/O with Modbus TCP				07WS
Standard I/O with PROFIBUS				004S
Standard I/O with EtherCAT				00KS
Standard I/O with PROFINET				07LS
Standard I/O with EtherNet/IP				07MS
Standard I/O with POWERLINK				012S
Standard I/O with IO-Link				016S

Delivery of individual components

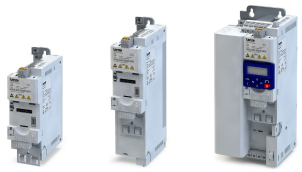
If different product versions are required in the machine, the various components can be ordered individually. Depending on the application, the components can be plugged together easily an without any further tools.

Order data: Order codes of the individual components.

Order example

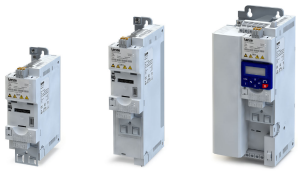
Description of components	Order code
Power unit	
3-phase mains connection 400/480 V	I5DAE222F10V10000S
Power 2.2 kW (i550-C2.2/400-3)	
Safety module	I5MASAV000000S
Safety function STO	
Control unit	
Standard I/O with CANopen	I5CA5C02000VA0000S
Default setting of parameters: EU region (50-Hz systems)	

Purchase order
Order code

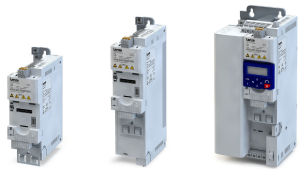


Power unit			
Power		Inverter	Order code
kW	hp		
1-phase mains connection 120 V, EMC filter not integrated			
0.25	0.33	i550-C0.25/120-1	I5DAE125A10V00000S
0.37	0.5	i550-C0.37/120-1	I5DAE137A10V00000S
0.75	1	i550-C0.75/120-1	I5DAE175A10V00000S
1.1	1.5	i550-C1.1/120-1	I5DAE211A10V00000S
1-phase mains connection 230 V, EMC filter integrated			
0.25	0.33	i550-C0.25/230-1	I5DAE125B10V10000S
0.37	0.5	i550-C0.37/230-1	I5DAE137B10V10000S
0.55	0.75	i550-C0.55/230-1	I5DAE155B10V10000S
0.75	1	i550-C0.75/230-1	I5DAE175B10V10000S
1.1	1.5	i550-C1.1/230-1	I5DAE211B10V10000S
1.5	2	i550-C1.5/230-1	I5DAE215B10V10000S
2.2	3	i550-C2.2/230-1	I5DAE222B10V10000S
1/3-phase mains connection 230/240 V, EMC filter not integrated			
0.25	0.33	i550-C0.25/230-2	I5DAE125D10V00000S
0.37	0.5	i550-C0.37/230-2	I5DAE137D10V00000S
0.55	0.75	i550-C0.55/230-2	I5DAE155D10V00000S
0.75	1	i550-C0.75/230-2	I5DAE175D10V00000S
1.1	1.5	i550-C1.1/230-2	I5DAE211D10V00000S
1.5	2	i550-C1.5/230-2	I5DAE215D10V00000S
2.2	3	i550-C2.2/230-2	I5DAE222D10V00000S
3-phase mains connection 230/240 V, EMC filter not integrated			
4.0	5	i550-C4.0/230-3	I5DAE240C10V00000S
5.5	7.5	i550-C5.5/230-3	I5DAE255C10V00000S
3-phase mains connection 400/480 V, EMC filter integrated			
0.37	0.5	i550-C0.37/400-3	I5DAE137F10V10000S
0.55	0.75	i550-C0.55/400-3	I5DAE155F10V10000S
0.75	1	i550-C0.75/400-3	I5DAE175F10V10000S
1.1	1.5	i550-C1.1/400-3	I5DAE211F10V10000S
1.5	2	i550-C1.5/400-3	I5DAE215F10V10000S
2.2	3	i550-C2.2/400-3	I5DAE222F10V10000S
3	4	i550-C3.0/400-3	I5DBE230F10V10000S
4	5	i550-C4.0/400-3	I5DBE240F10V10000S
5.5	7.5	i550-C5.5/400-3	I5DAE255F10V10000S
7.5	10	i550-C7.5/400-3	I5DBE275F10V10000S
11	15	i550-C11/400-3	I5DBE311F10V10000S
15	20	i550-C15/400-3	I5DBE315F10V10000S
18.5	25	i550-C18/400-3	I5DBE318F10V10000S
22	30	i550-C22/400-3	I5DBE322F10V10000S
30	40	i550-C30/400-3	I5DBE330F10V10000S
37	50	i550-C37/400-3	I5DAE337F10V10000S
45	60	i550-C45/400-3	I5DAE345F10V10000S
55	74	i550-C55/400-3	I5DAE355F10V10000S
75	100	i550-C75/400-3	I5DAE375F10V10000S
90	120	i550-C90/400-3	I5DAE390F10V10000S
110	150	i550-C110/400-3	I5DAE411F10V10000S

Safety module	Order code
Safety function STO	I5MASAV000000S



Control unit	Order code	
	Delivery status Default parameter setting: Region EU (50-Hz networks)	**Delivery status Default parameter setting: Region US (60-Hz networks)**
Standard I/O without network	I5CA5002000VA0000S	I5CA5002000VA1000S
Application I/O without network	I5CA5003000VA0000S	I5CA5003000VA1000S
Standard I/O with CANopen	I5CA5C02000VA0000S	I5CA5C02000VA1000S
Standard I/O with Modbus RTU	I5CA5W02000VA0000S	I5CA5W02000VA1000S
Standard I/O with Modbus TCP	I5CA5V02000VA0070S	I5CA5V02000VA1070S
Standard I/O with PROFIBUS	I5CA5P02000VA0000S	I5CA5P02000VA1000S
Standard I/O with EtherCAT	I5CA5T02000VA0000S	I5CA5T02000VA1000S
Standard I/O with PROFINET	I5CA5R02000VA0070S	I5CA5R02000VA1070S
Standard I/O with EtherNet/IP	i5CA5G02000VA0070S	I5CA5G02000VA1070S
Standard I/O with POWERLINK	I5CA5N02000VA0000S	I5CA5N02000VA1000S
Standard I/O with IO-Link	I5CA5K02000VA0000S	I5CA5K02000VA1000S



Environmental notes and recycling

Lenze has been certified to the worldwide environmental management standard for many years (DIN EN ISO 14001). As part of our environmental policy and the associated climate responsibility, please note the following information on hazardous ingredients and the recycling of Lenze products and their packaging:

CE

Lenze products are partly subject to the EU Directive on the restriction of certain hazardous substances in electrical and electronic equipment 2011/65/EU: RoHS Directive [UKCA: S.I. 2012/3032 - The Restriction of the Use of Certain Hazardous Substances in Electrical and Electronic Equipment Regulations 2012] . This is documented accordingly in the EU declaration of conformity and with the CE mark.

Lenze products are not subject to EU Directive 2012/19/EU: Directive on waste electrical and electronic equipment (WEEE) [UKCA: S.I. 2013/3113 - The Waste Electrical and Electronic Equipment Regulations 2013] , but some contain batteries/rechargeable batteries in accordance with EU Directive 2006/66/EC: Battery Directive [UKCA: S.I. 2009/890 - The Waste Batteries and Accumulators Regulations 2009] . The disposal route, which is separate from household waste, is indicated by corresponding labels with the "crossed-out trash can".
Any batteries/rechargeable batteries included are designed to last the life of the product and do not need to be replaced or otherwise removed by the end user.

21 PAP

Lenze products are usually sold with cardboard or plastic packaging. This packaging complies with EU Directive 94/62/EC: Directive on packaging and packaging waste [UKCA: S.I. 1997/648 - The Producer Responsibility Obligations (Packaging Waste) Regulations 1997] .
The required disposal route is indicated by material-specific labels with the "recycling triangle".
Example: "21 - other cardboard"

REACH

Lenze products are subject to REGULATION (EC) No 1907/2006: REACH Regulation [UKCA: S.I. 2008/2852 - The REACH Enforcement Regulations 2008] . When used as intended, exposure of substances to humans, animals and the environment is excluded.

Lenze products are industrial electrical and electronic products and are disposed of professionally. Both the mechanical and electrical components such as electric motors, gearboxes or inverters contain valuable raw materials that can be recycled and reused. Proper recycling and thus maintaining the highest possible level of recyclability is therefore important and sensible from an economic and ecological point of view.

- Coordinate professional disposal with your waste disposal company.
- Separate mechanical and electrical components, packaging, hazardous waste (e.g. gear oils) and batteries/rechargeable batteries wherever possible.
- Dispose of the separated waste in an environmentally sound and proper manner (no household waste or municipal bulky waste).

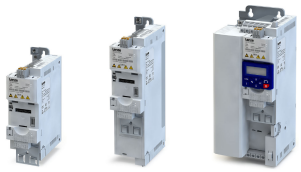
What?	Material	Disposal instructions
Pallets	Wood	Return to manufacturers, freight forwarders or reusable materials collection system
Packaging material	Paper, cardboard, pasteboard, plastics	Collect and dispose of separately
Products		
Electronic devices	Metal, plastics, circuit boards, heatsinks	As electronic waste give to professional disposer for recycling
Gearbox	Oil	Drain oil and dispose of separately
	Casting, steel, aluminium	Dispose as metal scrap
Motors	Casting, copper, rotors, magnets, potting compound	As engine scrap give to professional disposer for recycling
Dry-cell batteries/rechargeable batteries		As used batteries give to professional disposer for recycling

Further information on Lenze's environmental and climate responsibility and on the topic of energy efficiency can be found on the Internet:

www.Lenze.com → search word: "Sustainability"

Appendix

Declarations of Conformity



Lenze

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EU-Konformitätserklärung

EU Declaration of Conformity

LENZE SE, Hans-Lenze-Strasse 1, 31855 Aerzen GERMANY

erklärt in alleiniger Verantwortung die Übereinstimmung der Produkte

declares under sole responsibility compliance of the products

I55AExxxx1xxxxxxx &
I5MASAxxxxxxxx (Safety Module) (x=0-9/A-Z)

mit der

with the

Maschinenrichtlinie
2006/42/EG Anhang VIII und IX

Machinery Directive
2006/42/EC Annex VIII and IX

Angewandte harmonisierte Normen:

Applied harmonized standards:

Sicherer Halt	Stopp Kategorie 0	**EN 60204-1**	**:2018**	Stop category 0	Safe torque off
	Kategorie 4 Performance Level (PL): PL e	**EN ISO 13849-1**	**:2015**	Category 4 Performance Level (PL): PL e	
		EN 61508 1-7	**:2010**		
Sicherheitsfunktionen siehe Betriebsanleitung.	SIL 3	**EN 62061** **+AC +A1 +A2**	**:2005** **:2010 :2013 :2015**	SIL 3	For safety functions see manual.
		EN 61800-5-2	**:2017**		
		EN 61800-5-1 +A1	**:2007 :2017**		

Konformitätsbewertung

CE 0035

Benannte Stelle

Zertifikate

Gültigkeit

Conformity assessment

notified body

TÜV Rheinland Industrie Service GmbH
Am Grauen Stein
51105 Köln / Germany

Certificates 01/205/5455.01/19

Date of expiry 2024-5

EMV- Richtlinie
2014/30/EU

EMC Directive
2014/30/EU

Angewandte harmonisierte Normen:

Applied harmonized standards:

EN 61800-3:2004 + A1:2012
EN 61800-3:2018

RoHS- Richtline
2011/65/EU

RoHS Directive
2011/65/EU

Angewandte harmonisierte Normen:

Applied harmonized standards:

EN IEC 63000:2018

Die Sicherheitshinweise der Betriebanleitung sind zu beachten.

The safety instructions of the manual are to be considered.

Die Produkte sind bestimmt zum Einbau in Maschinen. Die Inbetriebnahme ist solange untersagt bis festgestellt wurde, dass die Maschine, in welche diese Produkte eingebaut werden sollen, den Bestimmungen der o.g. EU-Richtlinie entsprechen.

These products are intended for installation in machines. Operation is prohibited until it has been determined that the machines in which these products are to be installed, conforms to the above mentioned EU Directive.

Ort / Datum
Place / date

Aerzen 16.10.2020

Geschäftsführer
Managing Director

Dipl.-Ing. Frank Maier

Dokumentationsverantwortlicher
Responsible for documentation

i.V. T. Wedemeyer
i.V. T. Wedemeyer

2458986.00

UK Declaration of Conformity

Manufacturer

LENZE SE, Hans-Lenze-Strasse 1, 31855 Aerzen GERMANY

Authorised representative

LENZE Ltd., 6, Abbey Court Fraser Road Priory, Business Park, MK44 3WH Bedford

declares under sole responsibility compliance of the products

I55AExxxx1xxxxxxxx &
I5MASAxxxxxxxx (Safety Module) (x=0-9/A-Z)

with the

The Supply of Machinery (Safety) Regulations 2008				**S.I. 2008 No. 1597**
Applied designated standards:				
Safe torque off	**EN 60204-1**	**:2018**		
For safety functions see manual.	**EN ISO 13849-1**	**:2015**	Category 4 Performance Level: PL e	
	EN 61508 1-7	**:2010**		SIL 3
	EN 62061 **+AC +A1 +A2**	**:2005** **:2010 :2013 :2015**		SIL 3
	EN 61800-5-2	**:2007 + 2017**		
	EN 61800-5-1 + A1	**:2007 :2017**		

Conformity assessment

UK CA	**Approved Body**	TUV Rheinland UK Ltd 1011 Stratford Road Solihull, B90 4BN Approved Body No. 2571
	Certificates	01/205U/5455.00/21
	Date of expiry	2024-05

The Electromagnetic Compatibility Regulations 2016 **S.I. 2016 No. 1091**

Applied designated standards:

EN 61800-3:2004 + A1:2012
EN IEC 61800-3:2018

The Ecodesign for Energy-Related Products and Energy Information Regulations 2021

Applied designated standards:

EN 61800-9-2:2017

The Restriction of the Use of Certain Hazardous Substances in Electrical and Electronic Equipment Regulations 2012
S.I. 2012 No. 3032

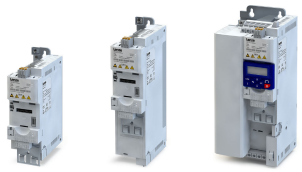
Applied designated standards:

EN IEC 63000:2018

The safety instructions of the manual are to be considered.

These products are intended for installation in machines. Operation is prohibited until it has been determined that the machines in which these products are to be installed, conforms to the above mentioned Regulations.

Place / date	Chief Technology Officer	Responsible for documentation
Aerzen 08.12.2021		
	Dipl.-Ing. Frank Maier	*i.V. Torsten Wedemeyer*



Good to know

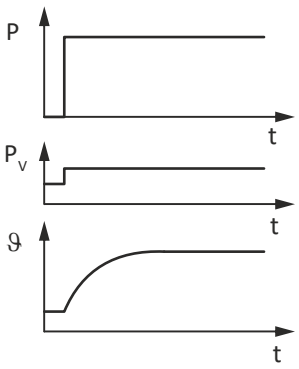
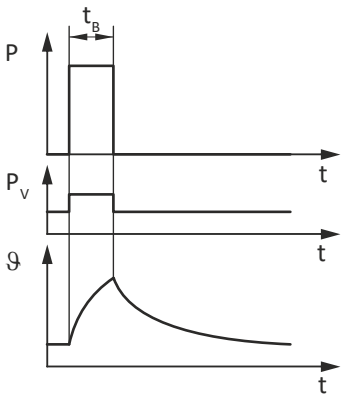
Operating modes of the motor

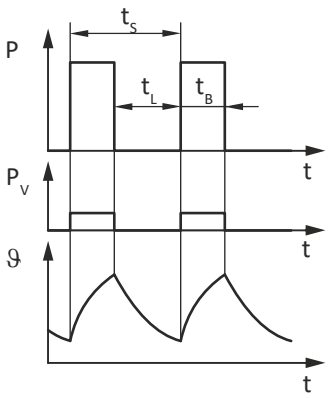
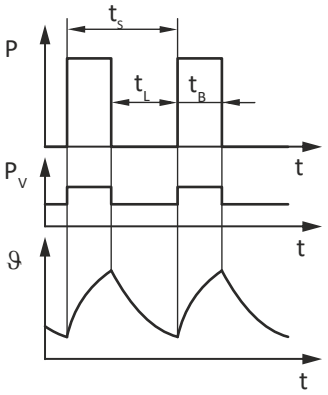
Operating modes S1 ... S10 as specified by EN 60034-1 describe the basic stress of an electrical machine.

In continuous operation a motor reaches its permissible temperature limit if it outputs the rated power dimensioned for continuous operation. However, if the motor is only subjected to load for a short time, the power output by the motor may be greater without the motor reaching its permissible temperature limit. This behaviour is referred to as overload capacity.

Depending on the duration of the load and the resulting temperature rise, the required motor can be selected reduced by the overload capacity.

The most important operating modes

Continuous operation S1	Short-time operation S2
	
Operation with a constant load until the motor reaches the thermal steady state. The motor may be actuated continuously with its rated power.	Operation with constant load; however, the motor does not reach the thermal steady state. During the following standstill, the motor winding cools down to the ambient temperature again. The increase in power depends on the load duration.

Intermittent operation S3	Non-intermittent periodic operation S6
	
Sequence of identical duty cycles comprising operation with a constant load and subsequent standstill. Start-up and braking processes do not have an impact on the winding temperature. The steady-state is not reached. The guide values apply to a cycle duration of 10 minutes. The power increase depends on the cycle duration and on the load period/downtime ratio.	Sequence of identical duty cycles comprising operation with a constant load and subsequent no-load operation. The motor cools down during the no-load phase. Start-up and braking processes do not have an impact on the winding temperature. The steady-state is not reached. The guide values apply to a cycle duration of 10 minutes. The power increase depends on the cycle duration and on the load period/idle time ratio.

P	Power	P_V	Power loss
t	Time	t_B	Load period
t_L	Idle time	t_S	Cycle duration
ϑ	Temperature		

Motor control types

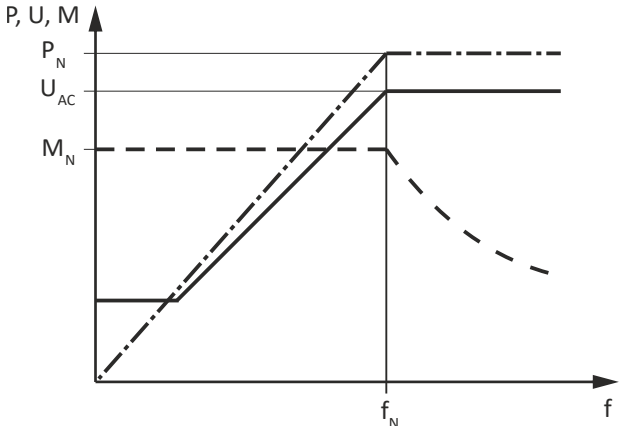
The inverter provides various motor control types.

Linear V/f characteristic control

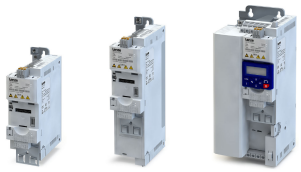
The output voltage is increased proportionately to the output frequency.

In case of low output frequencies, the motor voltage can be increased to ensure a minimum current for the breakaway torque. In the field weakening range, the output voltage of the inverter is constant (mains voltage) and the frequency can be further increased depending on the load. The maximum torque of the motor is reduced proportionately to the square of the frequency increase, the maximum output power of the motor being constant.

Application areas are for instance: Single drives with constant load.



P	Power	P_N	Rated power
V	Voltage	U_{AC}	Mains voltage
M	Torque	M_N	Rated torque
f	Frequency	f_N	Rated frequency



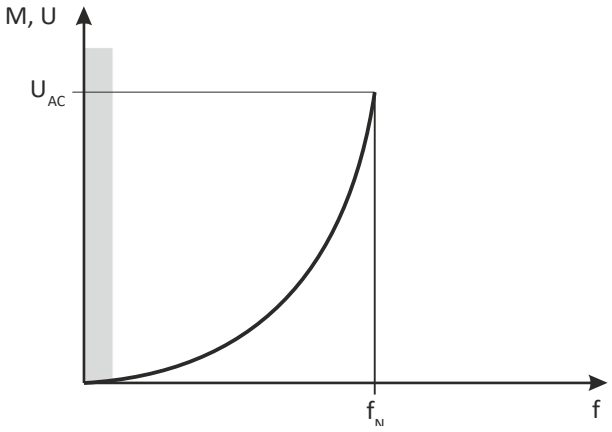
Square-law V/f characteristic control

The output voltage is increased squarely to the output frequency.

In case of low output frequencies, the motor voltage can be increased to ensure a minimum current for the breakaway torque. In the field weakening range, the output voltage of the inverter is constant (mains voltage) and the frequency can be further increased depending on the load. The maximum torque of the motor is reduced squarely to the frequency increase, the maximum output power of the motor being constant.

Application areas are for instance:

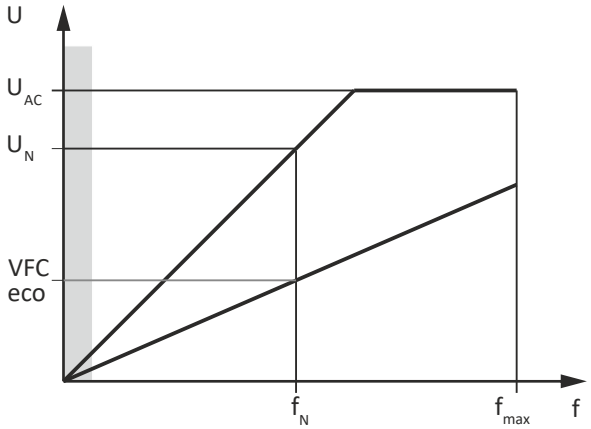
- Pumps
- Fans
- Ventilators



V	Voltage	U_{AC}	Mains voltage
f	Frequency	f_N	Rated frequency
M	Torque		

VFCeco

The VFCeco mode has a special effect in the partial load operational range. Usually, three-phase AC motors are supplied there with a higher magnetising current than required by the operating conditions. The VFCeco mode reduces the losses in the partial load operational range so that savings up to 30 % are possible.



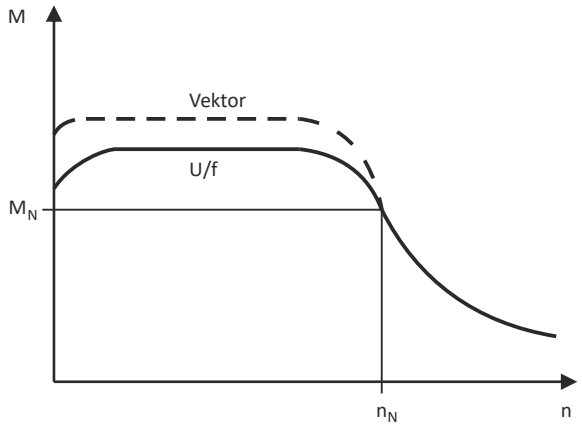
V	Voltage	f	Frequency
U_{AC}	Mains voltage	f_N	Rated frequency
U_N	Rated voltage	f_{max}	Max. frequency

Sensorless vector control (SLVC)

In vector control, an inverted voltage model is used for calculation. The parameters are detected via a parameter identification. The inverter determines the angle between current and voltage. This imposes a current on the motor”.

Compared to the V/f characteristic control, the vector control serves to achieve improved drive characteristics thanks to:

- higher torque throughout the entire speed range
- higher speed accuracy and higher concentricity factor
- higher efficiency



M	Torque	M_N	Rated torque
n	Speed	n_N	Rated speed

Application areas are for instance:

- Single drives with changing loads
- Single drives with high starting duty
- Sensorless speed control of three-phase AC motors

Switching frequencies

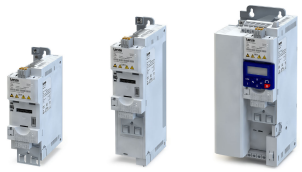
On an inverter, the term "switching frequency" is understood to mean the frequency with which the input and outputs of the output module (inverter) are switched. On an inverter, the switching frequency can generally be set to values between 2 and 16 kHz, whereby the selection is based on the respective power output.

As switching the modules cause heat losses, the inverter can provide higher output currents at low switching frequencies than at high frequencies. Additionally, it is distinguished between the operation at a permanently set switching frequency and a variably set switching frequency. Here, the switching frequency is automatically reduced as a function of the device utilization.

At a higher switching frequency, the noise generation is less.

Options for the switching frequency:

- 2 kHz
- 4 kHz
- 8 kHz
- 12 kHz
- 16 kHz
- variable (automatic adaptation)



Enclosures

The protection class indicates the suitability of a product for specific ambient conditions with regard to humidity as well as the protection against contact and the ingress of foreign particles. The protection classes are classified in the EN 60034-5/ EN IEC 60529.

The first code number after the code letters IP indicates the protection against the ingress of foreign particles and dust. The second code number refers to the protection against the ingress of humidity.

Code number 1	Degree of protection	Code number 2	Degree of protection
0	No protection	0	No protection
1	Protection against the ingress of foreign particles d > 50 mm. No protection in case of deliberate access.	1	Protection against vertically dripping water (dripping water).
2	Protection against medium-sized foreign particles, d > 12 mm, keeping away fingers or the like.	2	Protection against diagonally falling water (dripping water), 15 ° compared to normal service position.
3	Protection against small foreign particles d > 2.5 mm. Keeping away tools, wires or the like.	3	Protection against spraying water, up to 60 ° from vertical.
4	Protection against granular foreign particles, d > 1 mm, keeping away tools, wire or the like.	4	Protection against spraying water from all directions.
5	Protection against dust deposits (dust-protected), complete protection against contact.	5	Protection against water jets from all directions.
6	Protection against the ingress of dust (dust-proof), complete protection against contact.	6	Protection against choppy seas or heavy water jets (flood protection).

Glossary

Definitions in functional safety

Abbreviation	Meaning
AIE	Acknowledge In Error, error acknowledgement
AIS	Acknowledge In Stop, restart acknowledgement
OFF state	Triggered signal status of the safety sensors
CCF	Common Cause Error (also β-value)
EC_FS	Error Class Fail Safe
EC_SS1	Error Class Safe Stop 1
EC_SS2	Error Class Safe Stop 2
EC_STO	Error Class Safe Torque Off Stop 0
ON state	Signal status of the safety sensors in normal operation
FIT	Failure In Time, 1 FIT = 10-9 Error/h
FMEA	Failure Mode and Effect Analysis
FSoE	FailSafe over EtherCAT
GSDML	Device description file with PROFINET-specific data to integrate the configuring software of a PROFINET controller.
HFT	Hardware Failure Tolerance
Cat.	Category according to EN ISO 13849-1
nBD	Speed value Base-Drive, internally determined actual speed from standard application
nSD	Safe-Drive speed value, internally determined actual speed from the safety application
n_safe	Actual speed determined from validation of nBD and nSD. Enters the further processing of the speed-dependent safety functions.
OSSD	Output Signal Switching Device, tested signal output
pBD	Base-Drive position value, internally determined actual position from standard application
pSD	Safe-Drive position value, internally determined actual position from the safety application
p_safe	Actual position determined from validation of pBD and pSD. Enters the further processing of the position-dependent safety functions.
PELV	Protective Extra Low Voltage
PL	Performance Level according to EN ISO 13849-1
PM	Plus−Minus − switched signal paths
PP	Plus−Plus − switched signal paths
PS	PROFIsafe
PWM	Pulse Width Modulation
SCS	Safe Creeping Speed
SD−In	Safe Digital Input
SD−Out	Safe Digital Output
SELV	Safety Extra Low Voltage
SFF	Safe Failure Fraction
SIL	Safety Integrity Level according to EN IEC 61508

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