

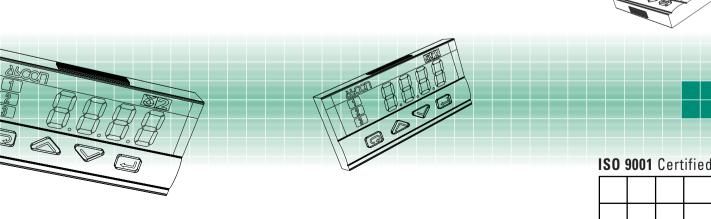
# Controller Indicator Transmitter 1/32 DIN - 48 x 24 mm gamma**due**® series C1 line

## Small, easy and comprehensive

Easy configuration and simple operating method. The smallest line of the gammadue® series concentrates the functionality of the temperature controller-indicator-transmitter without loosing the typical characteristics of more complex devices like: autotune, IP65 front panel protection, serial communications,

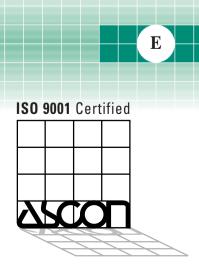
analogue retransmission output, custom linearisation, and transmitter power supply.





#### **ASCON** spa

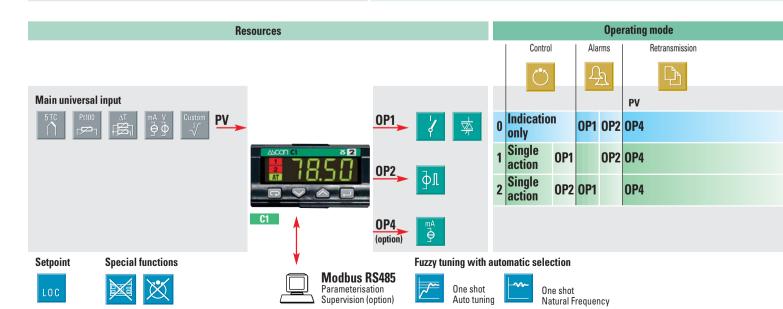
Via Falzarego, 9/11 - 20021 Bollate - (Milano) Italy - Tel. +39 02 333 371 - Fax +39 02 350 4243 http://www.ascon.it e-mail: sales@ascon.it







Your needs	Our solutions
Restricted space and reduction of the instrumentation overall dimensions	1/32 DIN - 48 x 24 Size
Easy replacement and quick start-up	Configuration by simple to use codes
Correct tuning for any condition	Automatic selection between two different methods
Conversion and retransmission of low level signals	Transmitter with isolated and analogue output
Contactless temperature measurements	Indicator with infrared input ability
Alarm signalling	Absolute and deviation alarms
Interfacing with other devices	Serial communications at 9600 baud Modbus/Jbus protocol, analogue retransmission output
Quick learning	Every model has the same operating method
Ergonomic compatibility with other devices	Two colours: beige or darkgrey front panels
Environmental protection	IP65 front panel protection (indoor, dust and water protection)
Easy to use	Ergonomic keypad, clear and comprehensive display
Noise immunity	Electromagnetic compatibility
Universal input signals, linear as well as non-linear	Configurable input (TC, RTD, mA, Volt and $\Delta T$ , infrared sensor, custom linearisation)
Reliability and safety	CE compatibility, ASCON is ISO 9001 certified, 3 years warranty
Technical support	Technical application assistance from ASCON sales and after sales service



#### **Technical data**

	D						
Features at env. 25°C	Description						
	From keypa	d or ser	ial		the type		
	communications, the user selects: - the associated functions and the						
Total	corresponding outputs						
configurability						of control algo	
,	<ul> <li>the type of output and the safe conditions</li> <li>the type and functionality of the alarms</li> <li>the values of all the control parameters</li> </ul>						
			A/D conv	erter w	ith 50000	points	
	Common			Update measurement time: 0.2s			
	Sampling t			pling time: 0.5s			
Input shift: ±60 digits Input filter: 130s (OFF							
						Between 100240Vac	
	Accuracy		0.23 % ±1di				error is minimal
PV input	Resistance						Line: 20Ω max. (3 wire)
(for signal	thermomete		Pt100Ω at	t 0°C	2 or 3 w	rire	Thermal drift
ranges	(for ∆T: R1+	R2	(IEC 751) °C/°F sele	otoblo	connec	tion	0.35°C/10°C env. T.
see table 1)	must be <32	20Ω)	C/ FSEIG	clable			<0.35°C/10 $\Omega$ line resist.
			L,J,T,K,S		Interna	l cold	Line: 150Ω max.
	Thermocou	ple	(IEC 584)		junction		Thermal drift
			°C/°F sele	ctable	comper	nsation	$<2\mu$ V/°C env. T. $<5\mu$ V/10Ω line resist.
			0/420m <i>A</i>	with	F		(ομν/ 1022 IIII ο 10313 c.
	DC input		$2.5\Omega$ ext.			ering units, decimal point,	
	(current)		Rj > 10MΩ	2		nge -9999999	Input drift:
	DC input		0/1050r	nV		nge -9999999	< 0.1%/20°C env. T.
	(voltage)		Rj >10MΩ			ts minimum	
					AL1 ala	rm	AL2 alarm
	Indicator w	ith 2 ala	rms		OP1- relay or triac		OP2 - SSR drive
Operating					0P2 - S	SR drive	OP1 - relay or triac
modes					Control	output	AL2 alarm
	1 PID loop or ON/OFF with 1 alarm		arm		elay or triac	OP2 - SSR drive	
						SR drive	OP1 - relay or triac
	Algorithm PID with overshoo			ot contr	ol or ON/OFF		
	Proport. band (P) 0.5999.9%						
	Integral tim	e (I)	0.1100.	0 min	OFF = 0		
Control mode	Integral tim Derivative t	e (I)	0.1100.l	0 min	0FF = 0		PID algorithm
Control mode	Integral tim Derivative t Cycle time	e (I) time (D)	0.1100.0 0.0110.0 1200 s	0 min 00 min	OFF = 0		PID algorithm
Control mode	Integral tim Derivative t Cycle time Overshoot	e (I) time (D)	0.1100.0 0.0110.0 1200 s 0.011.00	0 min 00 min 0	OFF = 0		PID algorithm
Control mode	Integral tim Derivative t Cycle time Overshoot of High limit	e (I) time (D)	0.1100.0 0.0110.0 1200 s 0.011.00 100.010	0 min 00 min 0 0	0FF = 0		-
Control mode	Integral tim Derivative t Cycle time Overshoot of High limit Hysteresis	e (I) ime (D) control	0.1100.0 0.0110.0 1200 s 0.011.00 100.010 0.110.0	0 min 00 min 0 0 0.0%			PID algorithm  ON/OFF algorithm
Control mode  OP1 output	Integral tim Derivative t Cycle time Overshoot of High limit Hysteresis SPST relay	e (I) ime (D) control	0.1100.0 0.0110.0 1200 s 0.011.00 100.010 0.110.0 V250V (for	0 min 00 min 0 0 1.0% % resistiv			-
OP1 output	Integral tim Derivative t Cycle time Overshoot of High limit Hysteresis SPST relay Triac, 2A/25	e (I) ime (D) control N.O., 2A	0.1100.0 0.0110.0 1200 s 0.011.00 100.010 0.110.00 \/250V (for	O min O min O O O O O O O O O O O O O O O O O O O	e load)	х.	-
	Integral tim Derivative t Cycle time Overshoot of High limit Hysteresis SPST relay Triac, 2A/25 SSR drive n	e (I) ime (D) control N.O., 2A 60Vac fo	0.1100.0 0.0110.0 1200 s 0.011.00 100.010 0.110.0 V/250V (for r contactor ted: 5Vdc, =	O min O min O O O O O O O O O O O O O O O O O O O	e load)	х.	-
OP1 output OP2 output AL1 alarm (indicator with	Integral tim Derivative t Cycle time Overshoot of High limit Hysteresis SPST relay Triac, 2A/25	e (I) control  N.O., 2A oVac fo ot isolat 0.110.	0.1100.0 0.0110.0 1200 s 0.011.00 100.010 0.110.0 V/250V (for r contactor ted: 5Vdc, =	0 min 00 min 0 0.0% % resistiv r coil ± 10%, 3	e load) 30mA ma		-
OP1 output OP2 output AL1 alarm	Integral tim Derivative t Cycle time Overshoot of High limit Hysteresis SPST relay Triac, 2A/25 SSR drive n Hysteresis	e (I) control  N.O., 2A oVac fo ot isolat 0.110.	0.1100.0 0.0110.0 1200 s 0.011.00 100.010 0.110.0 V/250V (for r contactor ted: 5Vdc, =	0 min 00 min 0 0.0% % resistiv r coil ± 10%, 3	e load) 30mA ma		-
OP1 output OP2 output AL1 alarm (indicator with	Integral tim Derivative t Cycle time Overshoot of High limit Hysteresis SPST relay Triac, 2A/25 SSR drive n Hysteresis Active high	e (I) control N.O., 2A 60Vac fo lot isolat 0.110.	0.1100.0 0.0110.0 1200 s 0.011.0 100.010 0.110.0 \(\frac{7}{250V}\) (for r contactor ted: 5Vdc, = 0% range	0 min 00 min 0 0.0% % resistiv r coil ± 10%, 3	e load) 30mA ma	e range	ON/OFF algorithm
OP1 output OP2 output AL1 alarm (indicator with 2 alarms)	Integral tim Derivative t Cycle time Overshoot of High limit Hysteresis SPST relay Triac, 2A/25 SSR drive n Hysteresis Active high Active low	e (I) control N.O., 2A 60Vac fo lot isolat 0.110.	0.1100.0 0.0110.0 1200 s 0.011.00 100.010 0.110.0 V250V (for r contactor ted: 5Vdc, = 0% range Absolute	0 min 00 min 0.0% % resistiv r coil £ 10%, 3	e load) 80mA ma	e range	ON/OFF algorithm
OP1 output OP2 output AL1 alarm (indicator with	Integral tim Derivative t Cycle time Overshoot of High limit Hysteresis SPST relay Triac, 2A/25 SSR drive n Hysteresis Active high Active low	e (I) iime (D) control N.O., 2A iioVac fo iot isolat 0.110. Active	0.1100.0 0.0110.0 1200 s 0.011.0 100.010 0.110.0 V/250V (for r contactor ted: 5Vdc, = 0% range Absolute 0% range high	0 min 00 min 0 0.0% % resistiv r coil ± 10%, 3	e load) 80mA ma	e range  Deviation three  Band thresho	ON/OFF algorithm  eshold ± range old 0range
OP1 output OP2 output AL1 alarm (indicator with 2 alarms)	Integral tim Derivative t Cycle time Overshoot of High limit Hysteresis SPST relay Triac, 2A/25 SSR drive n Hysteresis I Active high Active low Hysteresis (	e (I) ime (D) control  N.O., 2A 60Vac fo oot isolat 0.110.  Active	0.1100.0 0.0110.0 1200 s 0.011.00 100.010 0.110.0 V/250V (for r contactor ted: 5Vdc, = 0% range Absolute 0% range high	0 min 00 min 00 min 00 0.0% % resistiv r coil ± 10%, 3	e load) 80mA ma old, whol	e range  Deviation three  Band thresho	ON/OFF algorithm  eshold ± range
OP1 output OP2 output AL1 alarm (indicator with 2 alarms)	Integral tim Derivative to Cycle time Overshoot of High limit Hysteresis SPST relay Triac, 2A/25 SSR drive n Hysteresis Active high Active low Hysteresis of	e (I) ime (D) control  N.O., 2A 50Vac fo oot isolat 0.110.  Active Active	0.1100.0 0.0110.0 1200 s 0.011.0 100.010 0.110.0 v/250V (for r contactor ted: 5Vdc, = 0% range Absolute 0% range high low	0 min 00 min 00 min 00 0.0% % resistiv r coil ± 10%, 3	e load) 80mA ma old, whol	e range  Deviation thre Band thresho Absolute thre	ON/OFF algorithm  eshold ± range old 0range eshold, whole range
OP1 output OP2 output AL1 alarm (indicator with 2 alarms) AL2 alarm	Integral tim Derivative t Cycle time Overshoot of High limit Hysteresis SPST relay Triac, 2A/25 SSR drive n Hysteresis I Active high Active low Hysteresis of Action Up and dow	e (I) ime (D) control  N.O., 2A 50Vac fo oot isolat 0.110.  Active Active	0.1100.0 0.0110.0 1200 s 0.011.0 100.010 0.110.0 v/250V (for r contactor ted: 5Vdc, = 0% range Absolute 0% range high low	0 min 00 min 00 min 00 0.0% % resistiv r coil ± 10%, 3	e load)  30mA ma  old, whol  1 type  r break  0.1.	Deviation three Band threshot Absolute three999.9 digit/mi	ON/OFF algorithm  eshold ± range old 0range eshold, whole range on (OFF = 0)
OP1 output OP2 output AL1 alarm (indicator with 2 alarms)	Integral tim Derivative t Cycle time Overshoot of High limit Hysteresis SPST relay Triac, 2A/25 SSR drive n Hysteresis of Active high Active low Hysteresis of Action Up and dow Low limit	e (I) ime (D) control  N.O., 2A 50Vac fo oot isolat 0.110.  Active Active	0.1100.0 0.0110.0 1200 s 0.011.0 100.010 0.110.0 v/250V (for r contactor ted: 5Vdc, = 0% range Absolute 0% range high low	0 min 00 min 00 min 00 0.0% % resistiv r coil ± 10%, 3	e load)  30mA ma  old, whol  1 type  r break  0.1.  Froi	Deviation three Band thresho Absolute three999.9 digit/mi	ON/OFF algorithm  eshold ± range old 0range eshold, whole range on (OFF = 0) high limit
OP1 output OP2 output AL1 alarm (indicator with 2 alarms) AL2 alarm	Integral tim Derivative t Cycle time Overshoot of High limit Hysteresis SPST relay Triac, 2A/25 SSR drive n Hysteresis of Active high Active low Hysteresis of Action Up and dow Low limit High limit	e (I) ime (D) control N.O., 2A 60Vac fo iot isolat 0.110. Active Active Special	0.1100.0 0.0110.1 1200 s 0.011.0 100.010 0.110.0 V250V (for r contactor ted: 5Vdc, s 0% range Absolute 0% range high low	O min	e load)  30mA ma  old, whol  1 type  r break  0.1.  Froi	Deviation through Band threshold Absolute thre	ON/OFF algorithm  eshold ± range old 0range eshold, whole range on (OFF = 0) high limit
OP1 output OP2 output AL1 alarm (indicator with 2 alarms)  AL2 alarm  Setpoint  OP4 (option)	Integral tim Derivative t Cycle time Overshoot of High limit Hysteresis SPST relay Triac, 2A/25 SSR drive n Hysteresis of Active high Active low Hysteresis of Action Up and dow Low limit High limit Galvanically	e (I) ime (D) control  N.O., 2A ioVac fo iot isolat 0.110.  Active Active Specia n ramps	0.1100.0 0.0110.0 1200 s 0.011.0 100.010 0.110.0 V250V (for r contactor ted: 5Vdc, s 0% range Absolute 0% range high low I function	O min	e load)  30mA ma  old, whol  r type  r break  0.1.  Froi	Deviation three Band thresho Absolute three999.9 digit/mi	ON/OFF algorithm  eshold ± range old 0range eshold, whole range on (OFF = 0) high limit
OP1 output OP2 output AL1 alarm (indicator with 2 alarms)  AL2 alarm  Setpoint  OP4 (option) PV retransmis-	Integral tim Derivative t Cycle time Overshoot of High limit Hysteresis SPST relay Triac, 2A/25 SSR drive n Hysteresis of Active high Active low Hysteresis of Action Up and dow Low limit High limit Galvanically Resolution:	e (I) ime (D) control  N.O., 2A 60Vac fo iot isolat 0.110.  Active Active Specia n ramps y isolate 12bit (0.	0.1100.0 0.0110.0 1200 s 0.011.0 100.010 0.110.0 V250V (for r contactor ted: 5Vdc, s 0% range Absolute 0% range high low I function	O min	e load)  30mA ma  old, whol  r break  0.1.  From  From  Curi	Deviation thre Band thresho Absolute thre 999.9 digit/mi n low range to	ON/OFF algorithm  eshold ± range old 0range eshold, whole range on (OFF = 0) high limit igh range
OP1 output OP2 output AL1 alarm (indicator with 2 alarms)  AL2 alarm  Setpoint  OP4 (option) PV retransmission output	Integral tim Derivative to Cycle time Overshoot of High limit Hysteresis SPST relay Triac, 2A/25 SSR drive n Hysteresis Active high Active low Hysteresis of	e (I) ime (D) control  N.O., 2A 60Vac fo oot isolat 0.110.  Active Active Special n ramps y isolate 12bit (0.)	0.1100.0 0.0110.1 1200 s 0.011.00 100.010 0.110.0 V250V (for r contactor ted: 5Vdc, = 0% range Absolute 0% range high low I function	O min	e load)  80mA ma  old, whol  r break  0.1.  Fror  Fror  Curr  0/4.	e range  Deviation thre Band thresho Absolute thre999.9 digit/mi n low range to n low limit to h rent output:20mA 750Ω/15	ON/OFF algorithm  eshold ± range old 0range eshold, whole range on (OFF = 0) high limit igh range
OP1 output OP2 output AL1 alarm (indicator with 2 alarms)  AL2 alarm  Setpoint  OP4 (option) PV retransmission output One-shot	Integral tim Derivative to Cycle time Overshoot of High limit Hysteresis SPST relay Triac, 2A/25 SSR drive n Hysteresis Active high Active low Hysteresis of Action Up and dow Low limit High limit Galvanically Resolution: Accuracy: O Depending	e (I) ime (D) control  N.O., 2A 60Vac fo oot isolat 0.110.  Active Active Special n ramps y isolate 12bit (0. 0.1% on the p	0.1100.0 0.0110.0 1200 s 0.011.00 100.010 0.110.0 V250V (for r contactor ted: 5Vdc, s 0% range Absolute 0% range high low I function	O min	e load) 80mA ma old, whol type r break 0.1. Froi Cur 0/4. Ste	e range  Deviation thre Band thresho Absolute thre 999.9 digit/mi n low range to n low limit to h rent output:20mA 750Ω/1!	eshold ± range old 0range eshold, whole range on (OFF = 0) high limit igh range
OP1 output OP2 output AL1 alarm (indicator with 2 alarms)  AL2 alarm  Setpoint  OP4 (option) PV retransmission output One-shot Fuzzy-Tuning	Integral tim Derivative to Cycle time Overshoot of High limit Hysteresis SPST relay Triac, 2A/25 SSR drive n Hysteresis Active high Active low Hysteresis of Active low Hysteresis of Company of the control Depending the control	e (I) ime (D) control  N.O., 2A 60Vac fo oot isolat 0.110.  Active Active Special n ramps  y isolate 12bit (0. 0.1% on the per applie	0.1100.0 0.0110.0 1200 s 0.011.00 100.010 0.110.0 V250V (for r contactor ted: 5Vdc, = 0% range Absolute 0% range high low I function	O min O mesistiv	e load)  80mA ma  old, whol  r break  0.1.  From  Curr  0/4.  Stel  d Nat	e range  Deviation thre Band thresho Absolute thre 999.9 digit/mi n low range to n low limit to h rent output:20mA 750Ω/1! o response ural frequency	eshold ± range old 0range eshold, whole range on (OFF = 0) high limit igh range
OP1 output OP2 output AL1 alarm (indicator with 2 alarms)  AL2 alarm  Setpoint  OP4 (option) PV retransmission output One-shot Fuzzy-Tuning Ser. comm.s (opt.)	Integral tim Derivative to Cycle time Overshoot of High limit Hysteresis SPST relay Triac, 2A/25 SSR drive n Hysteresis Active high Active low Hysteresis of Action Up and dow Low limit High limit Galvanically Resolution: Accuracy: O Depending the controll RS 485 isola	e (I) ime (D) control  N.O., 2A 60Vac fo oot isolate 0.110.  Active Active Special n ramps y isolate 12bit (0. 0.1% on the per applie ated, Mo	0.1100.0 0.0110.0 1200 s 0.011.00 100.010 0.110.0 V250V (for r contactor ted: 5Vdc, s 0% range Absolute 0% range high low I function  d: 500Vac/ 025%)  rocess cores the best	O min O mesistiv	e load)  BOMA ma  old, whole  r break  0.1.  From  Curr  0/4.  Stel  d Nat	e range  Deviation thre Band thresho Absolute thre 999.9 digit/mi n low range to n low limit to h rent output:20mA 750Ω/1! o response ural frequency	eshold ± range old 0range eshold, whole range on (OFF = 0) high limit igh range
OP1 output OP2 output AL1 alarm (indicator with 2 alarms)  AL2 alarm  Setpoint  OP4 (option) PV retransmission output One-shot Fuzzy-Tuning	Integral tim Derivative to Cycle time Overshoot of High limit Hysteresis SPST relay Triac, 2A/25 SSR drive n Hysteresis Active high Active low Hysteresis of Active low Hysteresis of Company of the control Depending the control	e (I) ime (D) control  N.O., 2A 60Vac fo oot isolate 0.110.  Active Active Special n ramps y isolate 12bit (0. 0.1% on the per applie ated, Mo	0.1100.0 0.0110.0 1200 s 0.011.00 100.010 0.110.0 V250V (for r contactor ted: 5Vdc, s 0% range Absolute 0% range high low I function  d: 500Vac/ 025%)  rocess cores the best	O min O mesistiv	e load)  BOMA ma  old, whole  r break  0.1.  From  Curr  0/4.  Stel  d Nat	e range  Deviation thre Band thresho Absolute thre 999.9 digit/mi n low range to n low limit to h rent output:20mA 750Ω/1! o response ural frequency	eshold ± range old 0range eshold, whole range on (OFF = 0) high limit igh range

Input type	Scale range
	-99.9300.0 °C
RTD	-99.9572.0 °F
Pt100Ω at 0°C	-200600 °C
	-3281112 °F
T/C type L	0600 °C
Fe-Const.	321112 °F
T/C type J	0600 °C
Fe-Cu 45% Ni	321112 °F
T/C type T	-200400 °C
Cu - CuNi	-328752 °F
T/C type K	01200 °C
Chromel Alumel	322192 °F
T/C type S	01600 °C
Pt10%Rh-Pt	322912 °F
0/420 mA	Configurable engineering units
0/1050 mV	mA, mV, V, bar, psi, Rh, ph
mV Custom scale	On request

Table 1: PV input

#### **Fuzzy Tuning**

Two methods of tuning are available:

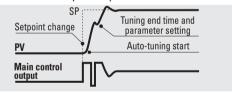
- Auto-Tuning "one shot"
- Natural frequency "one shot"

The **Fuzzy-Tuning** automatically selects one of the two methods which assure the best result for each condition.

The **Auto-Tuning** method works best on the step response basis.

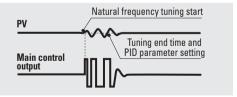
When activated, if a deviation exists between the Setpoint and process variable larger than 5% of scale range, the controller modifies the output value. Then, in a short time, it calculates the PID parameters and the new algorithm is operational immediately.

The main advantages of this method are fast calculation and quick implementation.



The **Natural frequency** method works best when the process variable is very near to the Setpoint. When activated, it causes a process oscillation around the Setpoint value.

The main advantage of this method is a reduced disturbance to the process.

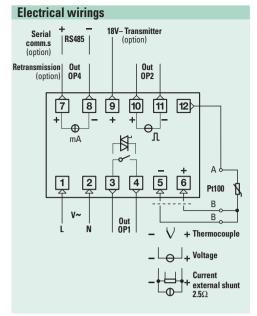


#### **Special functions**

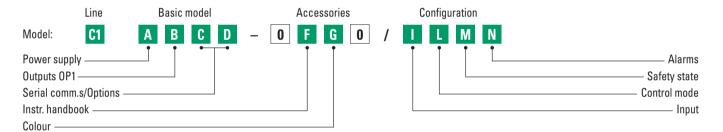
- Keypad lock/unlock function, to avoid incorrect operator actions
- Outputs lock/unlock function, at any moment it is possible to stop the control action, but not the process variable display, without switching-off the power supply.

### **Technical data**

Features at env. 25°C	Description	
	Measure input	Detection of out of range, short circuit or sensor break with automatic activation of the safety strategies and alerts on display
Operational safety	Control output	Safety value: 0100% (user enabled/disabled)
	Parameters	automatic activation of the safety strategies and alerts on display  Safety value: 0100% (user enabled/disabled)  A non volatile memory stores for unlimited time all the parameter and configuration values  Configuration and parameterisation access are password protection and 24Vdc (-15+10%) 50/60Hz or 24Vac (-25+12%), 50/60 and 24Vdc (-15+25%). Power consumption 3Va max.  Compliance EN61010-1 (IEC 1010-1), installation class 2 (2.5kV), pollution class 2, class II instrument  etic Compliance to the CE standards for industrial system and
	Password	Configuration and parameterisation access are password protected
	Power supply	100240Vac (-15+10%) 50/60Hz or 24Vac (-25+12%), 50/60Hz and 24Vdc (-15+25%). Power consumption 3Va max.
	Safety	·
General characteristics	Electromagnetic compatibility	Compliance to the CE standards for industrial system and equipment
	Protection EN60529 (IEC 529)	IP65 front panel
	Overall	$^{1}/_{32}$ DIN - 48 x 24, depth 120 mm, weight 100g approx.
	dimensions	Panel cut-out: 45 <sup>+0.6</sup> x 22.2 <sup>+0.3</sup> mm



### **Ordering codes**



Power supply			
100240Vac (-15+10%)			
24Vac (-25+12%) or	24Vdc (-15+25%)	5	
OP1 output		В	
Relay		0	
Triac		3	
Serial comm.s	Options	C	D
	None	0	0
Not fitted	Transmitter power supply	0	6
	Transmitter power supply + Retransmission	0	7
RS485 Modbus/JBus	None	5	0
protocol	Transmitter power supply	5	6

p. 0 2 0 0 0 .	porror capp.	
Instruction handbook		F F
Italian-English (std)		0
French-English		1
German-English		2
Spanish-English		3

U	panish-Liighsh	J
F	ront case colour	G
	ark (std)	
Е	eige	1
	·	

Range scale			
-99.9300.0 °C	-99.9572.0	°F	0
-200600 °C	-3281112	°F	1
0600 °C	321112	°F	2
0600 °C	321112	°F	3
-200400 °C	-328752	°F	4
01200 °C	322192	°F	5
01600 °C	322912	°F	6
Engineering units			7
Engineering units			8
On request			9
	-99.9300.0 °C -200600 °C 0600 °C 0600 °C -200400 °C 01200 °C 01600 °C Engineering units Engineering units	-99.9300.0 °C -99.9572.0 -200600 °C -3281112 0600 °C 321112 -200400 °C 321112 -200400 °C -328752 01200 °C 322192 01600 °C 322912 Engineering units Engineering units	-99.9300.0 °C -99.9572.0 °F -200600 °C -3281112 °F 0600 °C 321112 °F -200400 °C 321112 °F -200400 °C -328752 °F 01200 °C 322192 °F 01600 °C 322912 °F Engineering units Engineering units

Output configuration	on	L
PID	Control OP1/alarm AL2 on OP2	0
רוט	Control OP2/alarm AL2 on OP1	1
ON - OFF	Control OP1/alarm AL2 on OP2	2
	Control OP2/alarm AL2 on OP1	3
Indicator with	Alarm AL1 on OP1/alarm AL2 on OP2	4
2 alarms	Alarm AL1 on OP2/alarm AL2 on OP1	5

Type of control	Safety	M
Reverse (AL1 active low)	0%	0
Direct (AL1 active high)	0%	1
Reverse (AL1 active low)	100%	2
Direct (AL1 active high)	100%	3

AL2 type and fund	tion	N
Disabled		0
Sensor break		1
Absolute	Active high	2
Ansolute	Active low	3
Deviation	Active high	4
Deviation	Active low	5
Band	Active out	6
Dallu	Active in	7

If not differently specified the controller will be supplied with standard version

Model: C1 3000-0000

